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## Autonomous Marine Vehicle Operations

**Edited by: Xiao Liang , Rubo Zhang and Xingru Qu**

The world has witnessed the rapid development of autonomous marine vehicles, leading to created fruitful innovative approaches to previously unsolvable problems in marine science and engineering. This reprint focuses on research related to the operation of autonomous marine vehicles. This reprint addresses motion control and operation, underwater object detection and recognition, path planning and decision making, and path following and trajectory tracking, among other topics.

