

Correction

Correction: Bianchi et al. Quadrotor Trajectory Control Based on Energy-Optimal Reference Generator. *Drones* 2024, 8, 29

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Figure corrections

- In the original publication [1], Figure 1 was removed since it is the same as Figure 1 in [27]. This was a mistake; this figure was included informally by us in a preliminary private draft and accidentally left in the submission. It can be removed without altering the comprehension of the paper.
- The remaining figures have been renumbered accordingly.

Text corrections

- Page 5 (modified sentence): "For detailed equations and a thorough understanding, we direct readers to the references included in this section, in particular [27]".
- The reference to the old Figure 1 is replaced with a reference to Figure 1 in [27] on page 6.
- Page 7 (modified sentence): "As also discussed in [27], to which we refer for further details, this expression represents the integral of the power, which is the product of voltage and current, with respect to time over the specified duration".
- Page 9 (modified sentence): "The quadrotor model undergoes enhancement, and the revised set of equations is as follows (see [27])".

Reference

1. Bianchi, D.; Borri, A.; Cappuzzo, F.; Di Gennaro, S. Quadrotor Trajectory Control Based on Energy-Optimal Reference Generator. *Drones* **2024**, *8*, 29. [[CrossRef](#)]

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