



Design, Selection and Application of Energy Recovery Device in Seawater Desalination: A Review

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Abstract: In the seawater desalination system, the energy recovery system is a crucial part, as it consumes a lot of energy and plays a guiding role in the recovery efficiency. Therefore, in the energy recovery system, the recovery rate and energy consumption are the key factors to guide the system design. In order to make the energy recovery device achieve a high recovery rate under conditions of low energy consumption, the design and selection of each device in the system are particularly important. At the current stage, system matching optimization, device design optimization, and function objective optimization are widely used to improve the energy recovery system. In this paper, the design principle of the energy recovery integration system is analyzed, methods of reducing energy consumption and improving recovery efficiency are presented. The study provides guidance for the design and selection of energy recovery devices under different operating conditions.

Keywords: energy recovery device; recovery rate; specific energy consumption; turbine; pressure exchanger

1. Introduction

The ocean is a vital strategic resource for all countries of the world. Under the current situation of increasing global water shortage, saving water alone will not solve the problem of resource scarcity. People have begun to look for new ways to obtain water resources, and desalination has increasingly become one of the important ways for people to obtain freshwater [1]. In the 14th century BCE, people distilled seawater to acquire freshwater [2,3]. With the development of science and technology, people began to gradually use electrodialysis [4], multistage flash evaporation [5], and reverse osmosis (RO) [6] to desalinate seawater.

Reverse osmosis seawater desalination technology has developed rapidly in recent years. Because of its advantages of high efficiency, simple equipment, and convenient maintenance, it has been widely used in industrial seawater treatment and other more industries. The main parts of the reverse osmosis desalination system are: the pretreatment part, the membrane assembly part, the high-pressure pump, the energy recovery unit, and the post-processing portion for stabilization [7].

To some extent, the acceleration of reverse osmosis has solved the problem of a shortage of freshwater resources. However, the energy consumption of the reverse osmosis desalination project should not be underestimated. In this kind of technology of desalination, the energy recovery system, along with the high-pressure pump and high-pressure pipeline system are the core parts of the whole project, where they spend 40% of their assets on equipment [8]. The consumption of electric energy accounts for more than 30% of the whole project, and so the cost incurred also accounts for a large

proportion of the whole project [9]. The final price of each desalination system technology in the early 21st century is shown in Figure 1.

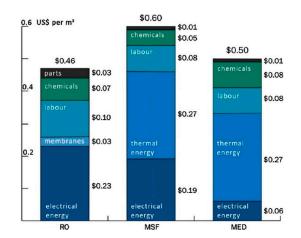


Figure 1. The ultimate water price for each desalination technology [10].

The existence of an energy recovery system is significant; in the seawater desalination system, 40% of the seawater can permeate through the reverse osmosis membrane to get freshwater [7]. If the rest of the 60% of the high-pressure concentrated brine that cannot go through the reverse osmosis membrane is discharged directly through the pressure relief valve, then the pressure energy will be wasted.

Therefore, how to obtain freshwater resources efficiently while reducing the energy consumption of the system has become the focus of numerous research.

The energy recovery device of the seawater desalination system can be divided into two categories: the positive displacement type and centrifugal type [11]. According to the different working parts of the equipment, the positive displacement type is mainly divided into a piston type (such as DWEERTM) and a ceramic rotary type (such as PXTM). The centrifugal types are mainly divided into the Pelton turbine, hydraulic turbocharger, hydraulic pressure booster, and reverse centrifugal pump. The energy recovery devices mostly adopted the centrifugal type first in the late 20th century, to reduce the energy consumption of the high-pressure pump and recover the pressure energy at the same time. In the 21st century, positive displacement energy recovery devices began to emerge, with higher efficiency than before. At present, due to the problems with the positive displacement device, researchers have made further innovations to the centrifugal device and made various improvements to the positive displacement device [12].

The positive displacement equation is mainly applied to the recovery of residual pressure energy in large-scale integrated seawater desalination plants. Although the flow of a single device is limited, it is commonly used in combination as parallel units [13], so the unit flow rate can be adjustable and run a wide range with high recovery efficiency. However, some of the positive displacement devices have problems that the noise is loud, and equipment failures abound. The centrifugal type is mainly applied to the energy recovery of high pressure concentrated seawater in small seawater desalination equipment. Its single flow rate is larger, the operation is stable, and the operating condition can be adjusted. Meanwhile, the design, improvement, and innovation of the centrifugal type is relatively diverse [14,15].

Specific energy consumption (SEC) is a key performance index in the reverse osmosis process. It refers to the total energy consumption generated by percolating fluid per unit volume [16]. It is one of the evaluation criteria for the efficiency of energy recovery devices [17,18]. It plays a decisive role in the energy consumption of the system and is closely related to the recovery efficiency of the devices [19,20]. The application of the energy recovery unit has significantly reduced the specific

energy consumption of penetration [21,22], which has promoted the development of SWRO seawater desalination [23,24].

From the perspective of reducing specific energy consumption, it is a trend to optimize the system by using optimization functions [25,26]. Each cycle of the system designed by Shayesteh [27] is composed of the power production department and the desalination water production. In order to reduce specific energy consumption and improve the recovery rate, the thermodynamic system is optimized by using the concentration disposal index (CDI) function [28]. The coordination relationship of various components in the energy recovery unit also has a great impact on the energy consumption and recovery rate [29,30]. In various energy recovery devices, the operating conditions and application conditions of various fluid machinery are different, in order to achieve the best efficiency of the system, the design, and the selection of each device crucial. Zhou et al. [31] made a comprehensive analysis of operating conditions of pump and recovery device, including motor and bypass regulating valve, so as to reach the optimal efficiency point of working together of all components, which is of great help to the selection of components of energy recovery systems under different operating conditions.

For the positive displacement energy recovery system, it is necessary to reduce the equipment floor space on the basis of high efficiency. For centrifugal types, blade optimization design and the best efficiency point (BEP) of the system will be the concern point. According to the different structures of reverse osmosis desalination systems under different operating conditions, the design principle and selection accordance of each part of the system is analyzed in this paper, to provide a theoretical and data basis for the design and selection of multiple seawater desalination energy recovery systems. The guidance of each kind of energy recovery system optimization is also provided.

2. Piston Type Energy Recovery Device

2.1. Description and Design of DWEERTM

The piston type energy recovery device (ERD) has the advantages of high efficiency, large capacity, and simple processing, and is a better choice for energy recovery in a large seawater reverse osmosis (SWRO) desalination plant [32]. A piston type ERD (such as DWEERTM) usually consists of three main components [32,33], two cylinders, a LinX valve, and a check seat (Figure 2).

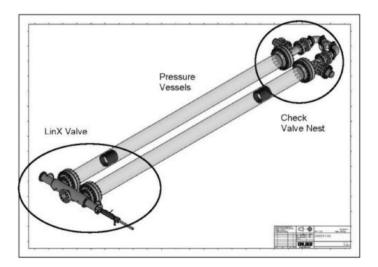


Figure 2. The DWEERTM work exchanger [13].

The feed flow is divided into two parts, which go into the high-pressure pump and the energy recovery device, respectively. Figures 3 and 4 give the scene of the recovery system. The size of the high-pressure pump is usually reduced due to the reduced flow. Booster pumps need to be installed in the system to compensate for the differential pressure on the diaphragm, and the pressure loss on the

pipeline and the energy recovery unit [34]. Generally, the pump is designed for differential pressure head of approximately 30 to 40 m [13].

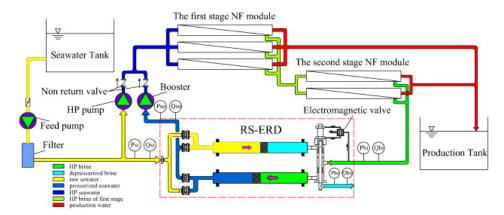


Figure 3. The flow diagram of the RS-ERD emulated test platform [35].

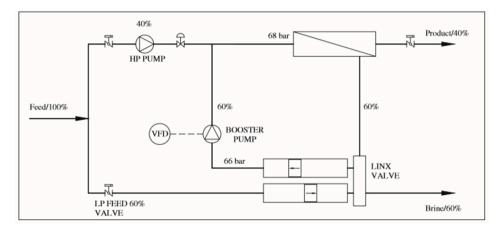


Figure 4. Integration of the work exchanger into a RO desalination system [13].

2.2. Selection and Applications of DWEERTM

The specific energy consumption of the lines using the pressure exchanger equipment as the energy recovery system was lower than that of the lines using the Pelton turbine [36,37], and the introduction of DWEERTM reduced the total specification energy consumption by 4.82%. The unit process is shown in Figure 5. Common DWEERTM selections [13] are shown in Table 1.

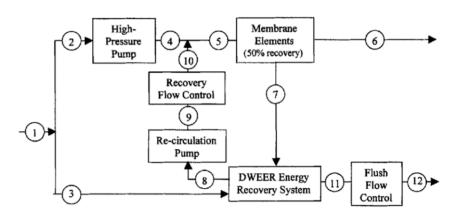


Figure 5. SWRO unit process (DWEERTM) [38].

Property	Flow Rate	Pressure
DWEER TM 1100	1100 USGPM or 250 m ³ /h	80 barg
DWEER TM 2200	2200 USGPM or 500 m ³ /h	80 barg

At brine flows above the standard product range flow, several DWEERTMs can be grouped in a DWEERTM system, as shown in Figure 6. As Schneider [13] compared, the center design is more accepted than the train design, because the energy consumption of the center design was reduced from 2.1 to 2.01 kWh/m³. In center design, it could use three high-pressure pumps. This can run the plant at 33%, 66%, and 100% capacity, with the different quad DWEERTMs switched off.



Figure 6. Rack design of a triple DWEERTM [13].

2.3. Other Piston Type Energy Recovery Devices

Based on experimental platform research, Wang [39] developed a hydraulic control switch energy recovery device (FS-ERD), and the experimental results showed that, under the capacity of 30 m³/h and the pressure of 6.0 MPa, the efficiency of the energy recovery system was 95.9%. Song [40] experimentally studied the system adaptability of signal control and time control on the basis of FS-ERD, and developed the reciprocating switch energy recovery device (RS-ERD) with four valve plates. The experimental results showed that the efficiency of the energy recovery device was 98% under the condition of 30 m³/h and 6.5 MPa. Zhou et al. [31] mainly introduced the RS-ERD, which is a type of equal-pressure piston type ERD. It consists of three main parts: a reciprocating-switcher (RS), two hydraulic cylinders, and a passive check valve nest, as shown in Figure 7. The pressurized decompression process of low-pressure seawater and high-pressure seawater is controlled by the cooperation of a passive check seat and reciprocating-switcher (RS).

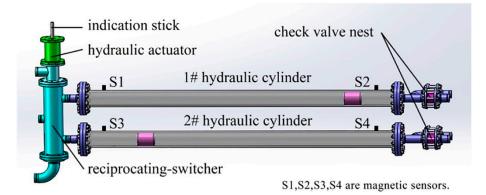


Figure 7. The basic components of RS-ERD [31].

A single RS-ERD can run well in a capacity range of 20 m³/h to 45 m³/h, equivalent to the design 66.7% to 150.0% capacity in the stable operation. Compared to the PX products, it is the same as capacity of two PXs. Compared to the DWEERTM, the control mode of DWEERTM limits the flexibility of capacity [13].

There are two main factors affecting RS-ERD efficiency; one is the leakage rate; the other is the pressure loss in the fluid. Equation (1) is a general formula for calculating the energy recovery efficiency of ERD [31]. As shown in Figure 8, when the flow is less than 30 m³/h, leakage is the dominant factor affecting the efficiency. When the flow exceeds the designed capacity of more than 30 m³/h, the pressure loss will become the main factor, and the influence will be more obvious than leakage.

$$\eta = \frac{\sum Energy_{out}}{\sum Energy_{in}} = \frac{Q_{so} \cdot P_{so} + Q_{bo} \cdot P_{bo}}{Q_{si} \cdot P_{si} + Q_{bi} \cdot P_{bi}}$$
(1)

where *Psi* means the pressure of the feed seawater inlet, MPa. *Pso* means the pressure of the pressurized seawater outlet, MPa. *Pbi* means the pressure of high-pressure brine inlet, MPa. *Pbo* means the pressure of the depressurized brine outlet, MPa. *Qsi* means the flow rate of the feed seawater inlet, m³/h. *Qso* means flowrate of the pressurized seawater outlet, m³/h. *Qbi* means flow rate of high-pressure brine inlet, m³/h.

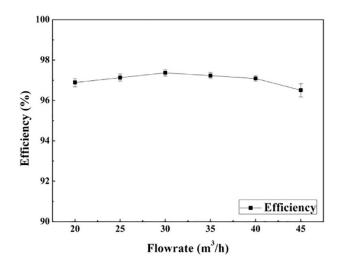


Figure 8. The energy recovery efficiency in different capacities [31].

As for the piston type isobaric ERD, because of the vibration and other problems, it requires regular maintenance of the piston and valves [41].

3. Pressure Exchanger

3.1. Description and Design of Pressure Exchanger

The Pressure Exchanger (PX) is a typical rotary energy recovery device [42,43] that consists of three main parts: a rotating rotor for pressure exchange, a sleeve, and two end caps [44].

The working process of PX is shown in Figure 9. The liquid transmits pressure through a short period of direct contact, and the PX rotor is used to transfer the pressure from the high-pressure brine discharge to the low-pressure seawater feed stream. Transfer occurs in the rotor pipe. The rotor is mounted in a ceramic sleeve between two ceramic end covers and has a precise clearance to form a fluid sliding bearing [45,46]; high-pressure and water-filled.

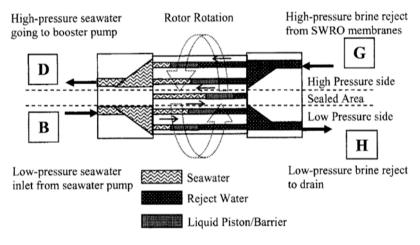


Figure 9. PX flow schematic [45].

When the rotor rotates, the high-pressure area and the low-pressure area will form the sealing area respectively through the pipe. If the high-pressure flow is equal to the low-pressure flow, Equation (2) is used to calculate the mix proportion of flow [47].

$$Volumetric mixing = \frac{HP_{out}salinity - LP_{in}salinity}{HP_{in}salinity - LP_{in}salinity} \times 100\%$$
(2)

where HP means high-pressure water, LP means low-pressure water.

PX, the direct positive displacement, makes the net transfer efficiency up to 97%, and has the behefits of a low failure rate, being not easy to corrode, and a low vibration. The relationship between system capacity (capital and operating costs) and the recovery rate is shown in Figure 10.

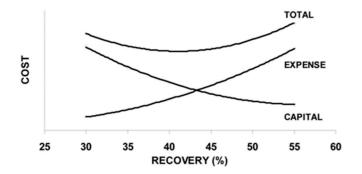


Figure 10. The overall plant cost optimization diagram [42].

The PX energy device does not require regular maintenance [42], and if the PX rotor stops rotating for any reason, the water will flow unimpeded through the path of equipment, because there are no

pistons or obstacles in the flow path through the equipment, and the damage of one of the rotors has little impact on the SWRO membrane [31,48]. This gives the equipment and maintenance staff time to buffer.

3.2. Selection and Applications of PXTM Units

PX was produced in 1989 [49,50] and first introduced as a commercial product in 1997 [51]. The processing capacity of a single rotor was increased to 50 m³/h after several generations of design improvement. The PX unit produces an almost perfect hydraulic disconnect between the high pressure and low-pressure pipelines [52–54]. The PX rotor rotates 500 to 2000 rotations per minute and is divided into 12 tubes with two sides. It can withstand pressures ranging from 12,000 to 48,000 per minute [45]. Multi-PX arrays are usually applied in large scale desalination plants, as Figure 11 displays the PX-120 array.

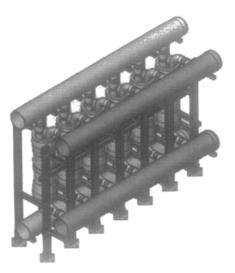


Figure 11. Twelve PX-120 arrays [45].

The fourth-generation device was the big rotor PX-200 [55]. The size is larger, with the water hammer and cavitation phenomenon is more serious, but this can be solved by the gentle transition of pressure. The efficiency decrease caused by fluid mixing in the PX-220 is approximately 1% at balanced flow, the same as the operating pressure to increase by approximately 1.3 bar. The efficiency of PX in the greater rotor is about 95%. The largest PX, PX-220 [45], has a capacity of 220 GPM or 50 m³/h, which can be integrated and run in parallel to achieve unlimited capacity. For example, a 10,000 m³/d SWRO plant running at a 45% recovery rate would require about 10 PX-220 units.

The basic information of PX device selection is exhibited in Table 2 Manipulating PX outside the capacity range may cause the rotor to rotate unsteadily in the sleeve [52].

PX Model Number	Capacity (m ³ /h)	Capacity (gpm)
PX-220	41–50	181-220
PX-180	32–41	141-180
PX-140	23–32	90-140
PX-90	16–20	71–90
PX-70	10–16	46-70
PX-45	6–10	26-45
PX-25	3–6	16-25
PX-15	2–3	10-15

Table 2. The PX sizes available [31,45].

Ashkelon seawater reverse osmosis plan [53] was the largest single-train SWRO capacity in 2007, whose full capacity of drinking water was 330,000 m³/d. It adopted a pressure center design. The Hamma (Algeria) desalination plant, designed by General Electric, Water Section, was the second largest plant at that time, was introduced by Mambrettia et al. [52] The plant adopted the train design method, utilized one array of 32 PX-220 devices on each of the nine first-pass trains for a total of 288 PX units, to minimize the high costs of processing the expected 200,000 m³/d of water [54]. The Hamma plant operates at 1084 m³/h and the efficiency is about 88%; the booster pump operates at 1351 m³/h and the efficiency is about 89% [52].

4. Pelton Turbine

4.1. Description and Design of Pelton Turbine

Although volumetric devices like DWEERTM and PX do have some interesting potential, centrifugal devices are the most widely used energy recovery technology by far and cut a figure in desalination field in uptime, flexibility, mechanical simplicity and robustness [56]. More than 98% of reverse-osmosis equipment installed worldwide has chosen centrifugal devices [41].

In centrifugal energy recovery devices, the Pelton turbine is a common counterattack turbine, widely used in seawater desalination energy recovery systems. The efficiency of the Pelton turbine at 570m³/h and 3000 rpm is shown in Figure 12.

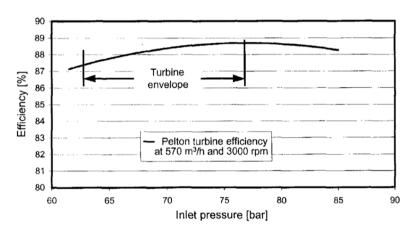


Figure 12. Pelton turbine efficiency curve [41].

According to the turbomachinery affinity law that the Pelton turbine follows, when rotating speed accelerates, the power input approximately grows cubically as a function of the speed. And the relation between efficiency and input power is described in Equation (3) [57]. With the affinity laws applied, the efficiency curve can be normalized when the operating speed changed [58].

$$\frac{1-\eta_1}{1-\eta_2} = \left(\frac{N_2}{N_1}\right)^{0.07} \tag{3}$$

where η means efficiency, *N* means input power.

The turbine part of the energy recovery device is coaxially connected with the high-pressure pump. The pump and turbine systems can find the same operating point by intelligent design of key parts of structure or system [14,15], such as the bucket of the turbine and impeller diameter [59–61]. The whole turbine structure and blade structure are shown in Figures 13 and 14.

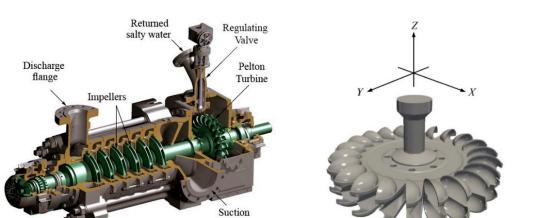


Figure 13. ERD assembled on the high-pressure centrifugal pump (left) [29] and the geometry of the runner (right) [14].

flange

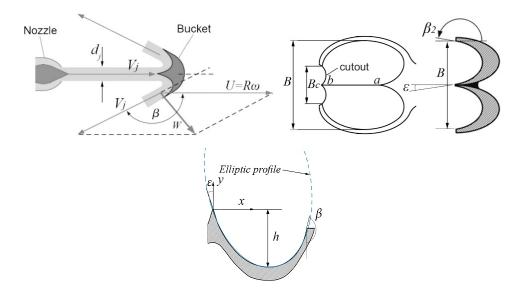


Figure 14. Bucket design for a Pelton turbine blade [29].

The design of the turbine bucket dimension is one of the key points to blades optimization [62,63]. The detailed parameters of condition that regulate the valve calculation for full opening are listed in Table 3.

Table 3. Regulating valve calculation for the full opening condition [29].

Parameter	Value
Input flowrate of RO package, Qp	325 m ³ /h
Discharge head of high-pressure pump, Hp	540 m
Head of the waste salty flow after filtering, H _i	520 m
Coefficient of pressure drop, C _v	0.95
Speed of the jet flow, V_i	95.9 m/s
Turbine input flowrate, \dot{Q}_{T}	195 m ³ /h
Specific speed of turbine, n _s	17
Jet flow diameter, d _i	26 mm
Optimum diameter of the turbine wheel, D _{m, opt}	303 mm
Width of the turbine bucket, B	3.16d _i = 84.7 mm
Depth of the turbine bucket, h	0.275B = 23.3 mm
Total efficiency of the EDR, η	78.5%

4.2. Selection and Application of Pelton Turbine

Manth et al. [41,64] argued that the key point to minimize the specific energy consumption (SEC) is to control the plant as a whole system and reduce throttling losses. By choosing a ring section pump, the energetic efficiency could come to 85% at the considered flow rate with the nominal speed of 3000 rpm. This pump is supplied by Duechting Pulnpen GmbH of Witten, Germany. The two-stages reverse osmosis desalination process is exhibited in Figure 15.

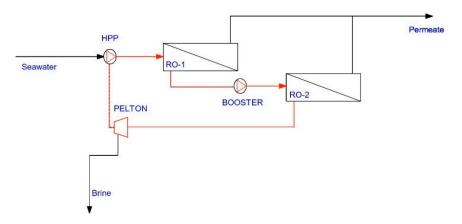


Figure 15. Schematic of a line with a Pelton turbine [64].

Based on the principle of specific energy consumption, the impact of throttling in the system is analyzed as follows in Table 4 [41,65].

Parameter	Title	Advantage	Disadvantage
Energy dissipation method	(a) Throttling (b) Permeate throttling	(a) Simple operation. (b) Low cost of investment.	Waste power consumption and cannot be recycled.
Energy control method	Variable Frequency Drives (VFD)	(a) The controllable hydraulic power range is wide.(b) The unit energy consumption is low when the water supply condition is good.	 (a) High cost of investment; (b) When water supply condition is poor, unit. energy consumption is high (c) The internal conversion rate of the VFD will affect the overall efficiency.

Table 4. Two types of flowrate controlling.

The first pump is used to provide the basic energy required for PROP in the system [66,67]. The duty point, which is the best efficiency point (BEP) of the reverse osmosis package, ensures efficient progress and stable energy input [41]. Sani [29] believes that impeller geometry and operating synchronicity of the turbine between turbine speed and centrifugal pump speed are important for improving efficiency and recovering the input power of energy recovery devices. The main parts and the seawater distribution of RO package introduced by Sani are shown in Figure 16.

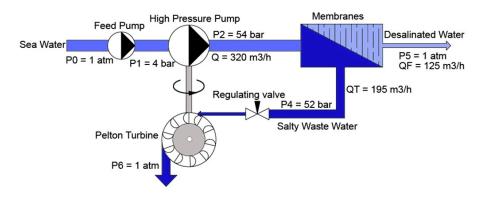


Figure 16. Schematic diagram of the cycle performance package [29].

Nowadays, in order to make energy recovery of reverse osmosis desalination process towards the direction of efficiency, the better match between high-pressure pumps, transmembrane pressures, and permeable fluids is often found by using equations and genetic algorithms [65,68].

5. Hydraulic Turbocharger and Hydraulic Pressure Booster

5.1. Description of Hydraulic Turbocharger and Hydraulic Pressure Booster

The hydraulic turbocharger (HTC), designed and manufactured by Pump Engineering Inc. [69], consists of two parts: a turbine and a pump whose blades are mounted on the same shaft. High-pressure brine enters into the turbine parts by a nozzle, with a bypass to adjust and control the flow and pressure of brine [70,71]. A hydraulic pressure booster (HPB), produced by FEDCO companies in the United States [72], is the second generation of energy recovery device on the basis of HTC. In this device, the saltwater control valve and energy recovery device are combined as a complete part instead of the bypass regulation. Both of those two kinds of devices work under the condition of a large flow rate [73]. The residual pressure energy of recovered brine is used to further pressurize seawater to the demanded pressure, which is equivalent to the role of booster pump in the process [74]. The energy recovery unit runs in series with a high-pressure pump to decrease system energy consumption by reducing the outlet pressure of the high-pressure pump.

With the hydraulic turbocharger (HTC), its overall energy transfer efficiency was up to 71%, applied for a reject flow ratio (i.e., the brine flow rate through the hydraulic turbo-booster/feed flow rate) of 60% [75].

Compared with other centrifugal energy recovery devices, the miniaturization of motors and switches, as well as the elimination of brine pressure relief valves, can save additional costs in new systems designed specifically for energy recovery. Systems such as ROWPU can save about \$2000 [76]. The equipment itself has the advantages of low cost, small floor space, and low energy consumption. By reducing the discharge pressure of the feed pump, the life of the feed pump components such as packing, valves, crossheads, and crank bearings is extended, resulting in additional cost savings [77,78].

5.2. Design and Selection of Energy Recovery Integration

The Fluid Machinery Team of Zhejiang University keeps the opinion that the efficiency of the integrated system composed of each recovery part cannot be represented by the efficiency of a single device, and the speed coordination of the primary pump, secondary pump, and turbine is more important. The energy recovery device (Figure 17) studied by Tamer et al. [30] is composed of the direct connection of the turbine, hydraulic turbocharger, and motor, which is called hydraulic energy management integration (HEMI). The study showed that where the auxiliary pipe size and valve opening were larger, the turbine inlet pressure was lower. The increase in turbine inlet pressure will lead to an increase of turbine rotating speed. In the device system set in this condition, the turbine

efficiency is highest when the speed is 11,000 rpm, and the balance between the pump and turbine will be realized at about 10,000 rpm.

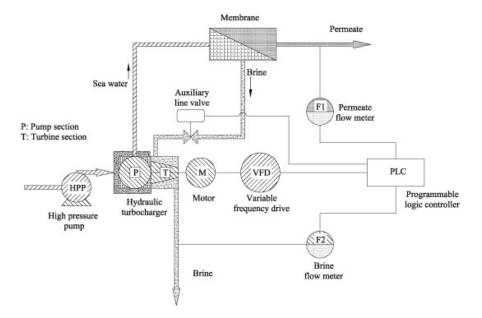


Figure 17. The control scheme of the HEMI system [30].

In 1992, Silbernagel et al. tested the high-pressure system. The size of the energy recovery device is shown in the Table 5 [76].

Table 5. Size of the energy recovery device.

Property	Index Parameter
Measure (without external tubing)	9.5 inches by 6.5 inches by 4.5 Inches
Weight	18 pounds

According to the test results, in the device displaced in Figure 18, the new rotor was made of a 2205 duplex alloy [79] and contained nitrogen, so the maximum strength of the shaft was achieved; The chrome oxide coating was used instead of alumina [76]. For the integrated RO package, more improvement has been made: the thrust bearing that can transmit more power adopted [80]; increase the shell thickness by increasing the flange; the shaft was placed in tension by rotor thrust to maximizing wear ring life [8].

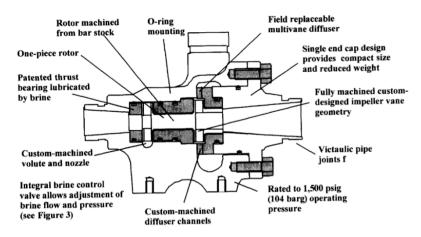


Figure 18. The internal construction and features of the HPBTM [8].

In terms of salinity and temperature, the design data can be considered to be representative of the Arabian gulf sea conditions [41]. The hydraulic assumptions of the case study plant are summarized in Table 6.

у I	
Operating Conditions	Value
Feed flow rate	950 m ³ /h
Permeate recovery	40%
Motor efficiency	97%
VFD efficiency	0.95
Feed pump type	Centrifugal
Brine discharge pressure	0 bar
Array/manifold loss	4 bar

Table 6. Hydraulic assumptions for model calculations [41].

The heart part of the integrated RO package (IROP) or hydraulic energy management integration (HEMI) is the feed pump and the energy recovery device [81]. The feed pump could select from Designated the TONKAFLO[®] SW series. The rated operating speed is 4200 rpm offered by TEFC motor, which is driven by VFD, the output frequency of the motor is 70 Hz [8]. HPB[™] is turbocharged with high-pressure brine, which drives the single-stage booster pump [82]. The feed pressure lift generated by HPB[™] reduces the required discharge pressure of the feed pump, thereby saving energy and reducing the size of the feed pump and motor [83].

The IROP assembly excluding the VFD can pump feed at up to 20 m³/h (85 gpm) at 67 bar (950 psig). The unit is driven by a 37 kW (50 hp) TEFC motor. The IROP standardized by the VFD is widely used, capable of operating at 50 or 60 Hz electric power with the same efficiency. ERT control valves and cleaning pump kits integrate components to simplify high-pressure pipes. One package can handle feed flows from about 50 gpm (12 m³/h) to 200 gpm (45 m³/h) [84]. The system is equipped with a control function to control the flow rate of the permeable fluid and brine [85,86].

The system components are shown in Figure 19. System parameters [8] of $120 \text{ m}^3/\text{d}$ and $500 \text{ m}^3/\text{d}$ output plant are listed in Tables 7 and 8 below.

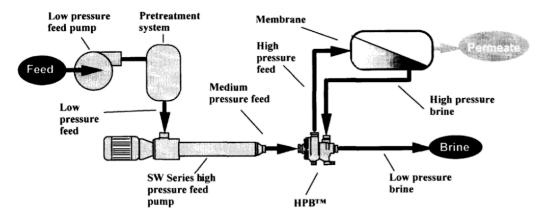


Figure 19. Component arrangement in a typical SWRO system [8].

Property	Index Parameter
Permeability	120 m ³ /d
Recovery rate	36%
Average operating pressure	60.0 bar or 58.0 bar
Shaft power	21.6 kW
kWh/ m ³ permeate	4.7
The total weight	290 kg
The total length	2.9 m

Table 7. A 120 ton/d example [8].

Property	Index Parameter
Permeability	500 m ³ /d
Recovery rate	45%
Average operating pressure	64.0 bar or 62.0 bar
Shaft power (The motor power)	125 hp (93 kW)
kWh/ m ³ permeate	4.7
The total weight	850 kg
The total length	4.1 m

6. Discussion and Conclusions

The positive displacement type and centrifugal type are two kinds of energy recovery devices. The classification, current status, and growing trend of different devices are discussed in Table 9.

	Positive Displacement Type	Centrifugal Type
Classification:	Piston type (DWEER TM , RS-ERD),	Pelton turbine, hydraulic pressure
	Pressure Exchanger	booster
	(a) Applied in large-scale desalination	(a) Applied in small-scale desalination
	plants;	plants;
	(b) Single device stands lower	(b) Single device stands higher pressure;
Current Status:	pressure;	(c) Single line and parallel units both
Current Status.	(c) Usually used in parallel units;	used;
	(d) Mostly keep more than 90%	(d) Single device keeps lower efficiency
	efficiency;	with more energy loss;
	(e) Some have noise while working.	(e) The operation is stable and adjusted.
Growing Trend:	(a) Reduce the equipment floor space;	(a) Use function objective optimization to design blade;
	(b) Solve the problems of serious noise and difficult maintenance.	(b) Find the best efficiency of point of all devices in system.

Table 9. Comparison and conclusion of energy recovery devices.

The positive displacement energy recovery device generally recycles the energy of high-pressure concentrated seawater through the direct transfer of liquid pressure. Therefore, its operation mechanism is simple, the device is efficient, and the usage is large in the early 21st century. In recent years, people have carried out blade design and pipeline improvement optimization for centrifugal energy recovery devices and found that the synchronism of devices is the key point to the energy recovery system. According to this point, researchers designed an integrated system with an energy recovery device as the core and other equipment as the auxiliary, so as to improve the overall system efficiency and energy consumption formed by the device and pipeline.

Different energy recovery devices are applied to different operating conditions. At present, the design and development of the energy recovery device of the seawater desalination system is relatively mature. It is becoming a top trend for people to study whether device selection or design conforms to

the operating conditions of the system and whether it can simultaneously reach the optimal operating conditions of all devices in the system.

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