A Time Two-Mesh Finite Difference Numerical Scheme for the Symmetric Regularized Long Wave Equation

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Abstract: The symmetric regularized long wave (SRLW) equation is a mathematical model used in many areas of physics; the solution of the SRLW equation can accurately describe the behavior of long waves in shallow water. To approximate the solutions of the equation, a time two-mesh (TT-M) decoupled finite difference numerical scheme is proposed in this paper to improve the efficiency of solving the SRLW equation. Based on the time two-mesh technique and two-time-level finite difference method, the proposed scheme can calculate the velocity \( u(x,t) \) and density \( \rho(x,t) \) in the SRLW equation simultaneously. The linearization process involves a modification similar to the Gauss-Seidel method used for linear systems to improve the accuracy of the calculation. By using the discrete energy and mathematical induction methods, the convergence results with \( O(\tau^2 + h^2) \) in the discrete \( L_{\infty} \)-norm for \( u(x,t) \) and in the discrete \( L_2 \)-norm for \( \rho(x,t) \) are proved, respectively. The stability of the scheme was also analyzed. Finally, some numerical examples, including error estimate, computational time and preservation of conservation laws, are given to verify the efficiency of the scheme. The numerical results show that the new method preserves conservation laws of four quantities successfully. Furthermore, by comparing with the original two-level nonlinear finite difference scheme, the proposed scheme can save the CPU time.

Keywords: SRLW equation; finite difference; time two-mesh; convergence analysis; conservation law

1. Introduction

The regularized long wave (RLW) equation \[1,2\] is a nonlinear partial differential equation that mainly describes the evolution of waves in shallow water channels and ion acoustics, etc. It is a simplified version of the more complex Korteweg-de Vries (KdV) equation \[3\], which includes higher-order nonlinearities and dispersion effects. The symmetric regularized long wave (SRLW) equation \[4\] is a modified version of the RLW equation that includes a symmetry-breaking term. This term allows for the formation of asymmetric solutions, making the SRLW equation a more realistic model for waves in shallow water channels.

In this paper, the following initial boundary value problem of the SRLW equation is considered:

\[
\begin{align*}
  u_t + \rho_x + uu_x - u_{xxt} &= 0, & x_L \leq x \leq x_R, & 0 < t \leq T, \\
  \rho_t + u_x &= 0, & x_L \leq x \leq x_R, & 0 < t \leq T, \\
  u(x_L,t) &= u(x_R,t) = 0, & \rho(x_L,t) = \rho(x_R,t) = 0, & 0 < t \leq T, \\
  u(x,0) &= u_0(x), & \rho(x,0) = \rho_0(x), & x_L \leq x \leq x_R,
\end{align*}
\]

where \( u(x,t) \) and \( \rho(x,t) \) are the fluid velocity and the density, respectively.

The SRLW equation has attracted significant attention and has been extensively studied in the literature. The existence of global attractors of the SRLW equation was studied in \[5\]. The travelling and solitary wave solutions of the SRLW equation were investigated by...
several methods including the exp-function method [6], the $(G'/G)$-expansion method [7,8],
the tanh-function method [9,10], the Lie symmetry approach [11], the extended simple
equation method [12], the analytical method [13], the tanh$(\phi(x)/2)$-expansion method [14]
and the sine–cosine method [15]. In [16,17], the spectral method and the Fourier pseudo-
spectral method with a constraint operator were developed as approximations for the
nonlinear term of the SRLW equation. Numerical solutions to the SRLW equation have also
been studied by numerous methods, ranging from conservative finite difference schemes to
mixed finite element methods. In their study, Wang et al. [18] introduced three conservative
finite difference schemes that achieve second-order accuracy in both spatial and temporal
domains. Their results indicate that each scheme is able to preserve energy conservation,
but only the first scheme is capable of preserving mass conservation. Yimnet et al. [19]
presented a novel finite difference method for the SRLW equation that utilizes a four-level
average difference technique for solving the fluid velocity independently from the density.
A coupled conservative three-level implicit scheme achieving fourth-order convergence rate
was developed by Hu et al. [20]. Li [21] considered a weighted and compact conservative
difference scheme that is decoupled and linearized in practical computation, thus requiring
only the solution of two tridiagonal systems of linear algebraic equations at each time
step. Bai et al. [22] investigated a two-layer conservative finite difference scheme for
the SRLW equation with homogeneous boundary conditions and analyzed the scheme’s
convergence and stability using a discrete functional analysis method. Xu et al. [23] applied
a mixed finite element method to solve the dissipative SRLW equations with damping term.
He et al. [24] developed a fourth-order accurate compact difference scheme for the SRLW
equation for a single nonlinear velocity form and conducted theoretical analysis using the
discrete energy method.

In terms of numerical computation, the time two-mesh (TT-M) method, when com-
bined with either the finite element method or the finite difference method, offers better
computational efficiency in solving a broad range of nonlinear partial differential equations.
For instance, Liu et al. [25] proposed the fast TT-M finite element method for solving
the fractional water wave model and applied it successfully to other fractional models.
Yin et al. [26] developed a TT-M finite element algorithm for solving a space fractional
Allen-Cahn model and analyzed the problem of parameter selection in detail. The TT-M
finite element method was also leveraged by Liu et al. [27] to numerically solve the 2D
Gray-Scott model with space fractional derivatives. A nonlinear distributed order dif-
fusion model was efficiently solved using the TT-M algorithm in conjunction with the
$H_1$-Galerkin mixed finite element method by Wen et al. [28], both smooth and non-smooth
solutions were considered. Additionally, Tian et al. [29] developed a finite element method
equipped with the TT-M technique to solve the coupled Schrödinger-Boussinesq equa-
tions. Moreover, some studies have investigated combining the TT-M and finite difference
methods to solve nonlinear fractional partial differential equations, such as the works of
Qiu and Xu et al. [30,31], who proposed and analyzed a TT-M algorithm based on finite
difference methods. The TT-M technique was also employed by Niu et al. [32] to develop a
fast high-order compact difference scheme for the nonlinear distributed order fractional
Sobolev model in porous media. Furthermore, He et al. [33] extended the application of
the TT-M method by studying a primary scheme of second-order convergence in time and
fourth-order in space for solving the nonlinear Schrödinger equation with a time two-mesh
high-order compact difference scheme. Despite the extensive research on the TT-M method
in various fields, to the best of our knowledge, no study on the application of the TT-M
method combined with finite difference to the SRLW equation has been discovered. Hence,
investigations on the TT-M finite difference method’s performance when applied to the
SRLW equation are still required.

The SRLW Equation (1) is a coupled system and most existing schemes found in
the literature are also coupled and require nonlinear implementation, which results in
prolonged CPU processing time. The objective of this paper is to develop a novel difference
scheme that offers the following three main advantages for solving the SRLW equation:
(i) Based on the time two-mesh technique, we proposed a scheme that achieves decoupling and the nonlinear term of the system is linearized by using Taylor’s formula for a function with three variables, which is different from the literature [32,33]. In [32,33], the time two-mesh scheme is formulated by using Taylor’s formula for a function with one or two variables. As a result, our scheme becomes a linearized system in approximate numerical solution and can reduce the computational time. (ii) The scheme’s convergence and stability have been verified through detailed proof, and the theoretical analysis process is more complex than that of existing methods, since the linearized scheme contains a function of three variables. (iii) The linearization process involves a modification similar to the Gauss-Seidel method used for linear systems to improve the accuracy of the calculation for solutions. The conservation law of four quantities is preserved in the new scheme at the discrete level.

The remaining part of this article is organized as follows. In Section 2, some notations and useful lemmas are given. In Section 3, the TT-M finite difference numerical scheme is presented. In Section 4, the convergence and stability of the scheme is analyzed. In Section 5, some numerical results are provided to test the theoretical results and computational efficiency of the scheme. Finally, in Section 6, we provide the conclusions of the paper.

2. Notations and Some Lemmas

As usual, the time interval \((0, T]\) and spatial interval \([x_L, x_R]\) are divided into \(N\) and \(J\) uniform partitions. The following notations will be used in this paper:

\[
\begin{align*}
(u^n)_x &= \frac{u^n_{j+1} - u^n_j}{h}, \quad (u^n)_\bar{x} = \frac{u^n_j - u^n_{j-1}}{h}, \quad \left(\frac{u^n}{h}\right)_x = \frac{u^n_{j+1} - u^n_{j-1}}{2h}, \\
(u^n)_j &= \frac{u^n_{j+1} - u^n_j}{\tau}, \quad u^n_j = \frac{1}{2}(u^{n+1}_j + u^n_j), \quad \left(\frac{u^n}{h}\right)_x = \frac{u^n_{j+1} - 2u^n_j + u^n_{j-1}}{h^2},
\end{align*}
\]

where \(\tau, h\) denote the uniform time and spatial step length, respectively, \(x_j = x_L + jh, j = 0, 1, 2, \cdots, J, t_n = n\tau, n = 1, 2, \cdots, [T/\tau] = N\), superscript \(n\) denotes the quantity associated with the time level \(t_n\), subscript \(j\) denotes a quantity associated with space mesh point \(x_j\). In this paper, \(M\) denotes general constant, which may have a different value in a different place.

Since \(u \to 0\) for \(x \to +\infty\) or \(x \to -\infty\), we may assume \(u^n_{j+1} = u^n_j = 0, 1 \leq n \leq N\) for simplicity, where \(j = -1\) and \(J + 1\) are ghost points. Let \(H_{h,0}\) denote the set of mesh functions \(u^n\) defined on \(I_h\) with boundary conditions \(u^{n+1}_0 = u^n_0 = u^n_J = u^{n+1}_J = 0\). For any two mesh functions \(u^n, w^n \in H_{h,0}\), we define the discrete inner product and norms as follows:

\[
(u^n, w^n) = h \sum_{j=1}^{J-1} u^n_j w^n_j, \quad \|u^n\| = \sqrt{(u^n, u^n)}, \quad \|u^n\|_\infty = \max_{1 \leq j \leq J-1} |u^n_j|.
\]

Next, we present some useful lemmas.

Lemma 1 (See [24]). For any mesh functions \(u^n, w^n \in H_{h,0}\), we have

(a) \((u^n_x, w^n_x) = -(u^n, w^n_x), (u^n, w^n_x) = -(u^n_x, w^n), (u^n, w^n_x) = -(u^n_x, w^n), (u^n, w^n) = -(u^n, w^n_x)\).

Lemma 2 (See [33,34]). Assume that a sequence of non-negative real numbers \(\{a_j\}_{j=0}^\infty\) satisfying

\[
a_{n+1} \leq \alpha + \beta \sum_{j=0}^{n} a_j \tau, \quad n \geq 0,
\]

then there has the inequality \(a_{n+1} \leq (\alpha + \tau \beta a_0) e^{\beta(n+1)\tau}, \) where \(\alpha \geq 0, \beta \) and \(\tau\) are positive constants.
Lemma 3 (See [22,34]). For any discrete mesh function \( u^n \in H_{h,0} \), there exists constants \( C_1 \) and \( C_2 \), such that
\[
\|u^n\|_\infty \leq C_1\|u^n\| + C_2\|u^n_k\|.
\]

3. The TT-M Finite Difference Scheme

In this paper, we studied a TT-M finite difference fast numerical method for the SRLW Equation (1). In order to give the TT-M finite difference scheme, firstly, the time interval \([0, T]\) is partitioned uniformly into \( P \) coarse time intervals and then each of them is divided into \( s(2 \leq s \in Z^+) \) fine time intervals. The coarse time mesh with the nodes \( t_{ks} = k\tau_C(k = 1, \ldots, P) \) satisfying \( 0 = t_0 < t_1 < t_2 \leq \cdots < t_{ps} = T \) and the fine time mesh with the nodes \( t_n = n\tau_F(n = 1, 2, \ldots, Ps = N) \) satisfying \( 0 = t_0 < t_1 < t_2 \leq \cdots < t_{Ps} = T \), where \( \tau_C = s\tau_F \) and \( \tau_F \) are the coarse time and the fine time step size, respectively.

Secondly, the truncation errors of the problem (1) are considered, let \( v^n_j = u(x_j, t_n) \), \( q^n_j = \rho(x_j, t_n) \) be the exact solutions of \( u(x,t) \) and \( \rho(x,t) \) in term of the point \( (x_j, t_n) \), then we have
\[
E_{r_j}^n = (v^n_j)_{t+} - (v^n_j)_{x} + \frac{1}{3}[v^{n+\frac{1}{2}}_{j+\frac{1}{2}} - (v^n_j)^2]_{x},
\]
\[
E_{s_j}^n = (q^n_j)_{t+} - (q^n_j)_{x} + \frac{1}{3}[v^{n+\frac{1}{2}}_{j+\frac{1}{2}} - (q^n_j)^2]_{x}.
\]

By Taylor series expansion, we have
\[
E_{r_j}^n = (u_0 + \rho_x - u_{xxt} + uu_x)_{(x_j,t_n)} = O(h^2 + \tau),
\]
\[
E_{s_j}^n = (\rho_1 + \rho_u)_{(x_j,t_n)} = O(h^2 + \tau).
\]

Next, based on Equations (2) and (3), a TT-M finite difference scheme for problem (1) is constructed with three steps.

Step 1: on the coarse time mesh, let \( u_{C,j}^{k} = u(x_j, t_{ks}) \), \( \rho_{C,j}^{k} = \rho(x_j, t_{ks}) \) be the numerical solutions of \( u(x,t) \) and \( \rho(x,t) \) in term of the point \( (x_j, t_{ks}) \), then the coarse time nonlinear finite difference scheme is given as
\[
\begin{align*}
(u_{C,j}^{k+1})_{t+} &- (u_{C,j}^{k})_{x} + \frac{1}{3}(u_{C,j}^{k+\frac{1}{2}})^2_{x} + \left[\frac{(u_{C,j}^{k+\frac{1}{2}})^2}{s}\right]_x = 0, \\
(\rho_{C,j}^{k+1})_{t+} &- (\rho_{C,j}^{k})_{x} + \frac{1}{3}(\rho_{C,j}^{k+\frac{1}{2}})^2_{x} + \left[\frac{(\rho_{C,j}^{k+\frac{1}{2}})^2}{s}\right]_x = 0,
\end{align*}
\]

where \( u_{C,j}^{k+\frac{1}{2}} = \frac{1}{2}(u_{C,j}^{k} + u_{C,j}^{k+1}) \).

Step 2: based on the solutions \( u_{C,j}^{k} \), \( \rho_{C,j}^{k} \) at time levels \( t_{ks} \) obtained from step 1, we apply the Lagrange’s linear interpolation formula to compute \( u_{C,j}^{k-1} \), \( \rho_{C,j}^{k-1} \) at time levels \( t_{ks-1} = t_1, \ldots, s - 1 \) and \( k = 1, \ldots, P, ks - l = 0 \), we have
\[
\begin{align*}
u_{C,j}^{k-1} & = \frac{t_{ks-l} - t_{ks}}{t_{k-1}s - t_{ks}}u_{C,j}^{k-1}s + \frac{t_{ks} - t_{k-1}s}{t_{k-1}s - t_{ks}}u_{C,j}^{k-1}s = \frac{1}{s}u_{C,j}^{(k-1)s} + (1 - \frac{1}{s})u_{C,j}^{ks}, \\
\rho_{C,j}^{k-1} & = \frac{t_{ks-l} - t_{ks}}{t_{k-1}s - t_{ks}}\rho_{C,j}^{k-1}s + \frac{t_{ks} - t_{k-1}s}{t_{k-1}s - t_{ks}}\rho_{C,j}^{k-1}s = \frac{1}{s}\rho_{C,j}^{(k-1)s} + (1 - \frac{1}{s})\rho_{C,j}^{ks}.
\end{align*}
\]
Remark 1. The Equation (7) is only employed for theoretical analysis of the scheme. In numerical simulation, the coarse numerical solutions $\rho_{C_j}^{k-1}$ are not needed for computation since they are not used in step 3.

Step 3: based on all the coarse numerical solutions $u_{C,j}^n (n = 0, 1, 2, \ldots, Ps = N, j = 1, 2, \ldots, I - 1)$ obtained in the first two steps, Taylor’s formula is used to construct a linearized system on the fine time mesh, which is expressed as follows. Let $u_{F,j}^n = u(x_j, t_n), \rho_{F,j}^n = \rho(x_j, t_n)$ be the numerical solutions of $u(x, t)$ and $\rho(x, t)$ in term of the point $(x_j, t_n)$ on the fine time mesh, then

\[
\begin{align*}
&\left( u_{F,j}^n \right)_t + (\rho_{F,j}^n)_{\xi} - \left( u_{F,j}^n \right)_{\xi} + \frac{1}{6\tau} \left( f(u_{C,j-1}^{n+1}, u_{C,j}^{n+\frac{1}{2}}, u_{C,j+1}^{n+\frac{1}{2}}) 
+ f_x(u_{C,j-1}^{n+1}, u_{C,j}^{n+\frac{1}{2}}, u_{C,j+1}^{n+\frac{1}{2}})(u_{F,j-1}^{n+1} - u_{C,j-1}^{n+1}) 
+ f_y(u_{C,j-1}^{n+1}, u_{C,j}^{n+\frac{1}{2}}, u_{C,j+1}^{n+\frac{1}{2}})(u_{F,j}^{n+1} - u_{C,j}^{n+1}) 
+ f_z(u_{C,j-1}^{n+1}, u_{C,j}^{n+\frac{1}{2}}, u_{C,j+1}^{n+\frac{1}{2}})(u_{F,j+1}^{n+1} - u_{C,j+1}^{n+1}) \right) = 0,
&\left( \rho_{F,j}^n \right)_t + (\rho_{F,j}^n)_{\xi} = 0,
&u_{F,0}^n = u_{F,j}^0 = 0, \quad \rho_{F,0}^n = \rho_{F,j}^0 = 0,
&u_{0}^n = u_0(x_L + jh), \quad \rho_{0}^n = \rho_0(x_L + jh),
&j = 1, \ldots, I - 1, \quad n = 0, 1, 2, \ldots, N,
\end{align*}
\]

where $f(x, y, z) = (z - x)y + z^2 - x^2$ and

\[
f_x(y, z) = -y - 2x, f_y(x, y, z) = z - x, f_z(x, y, z) = y + 2z
\]

are the three partial derivatives of $f(x, y, z)$ with respect to $x, y, z$.

Remark 2. Our method, similarly to the Gauss-Seidel method applied to linear systems, has been modified in order to enhance the accuracy of fine mesh solutions $u_{F,j}^{k+1}$ by using $u_{F,j}^k$ in calculation.


The focus of this section is on performing convergence analysis of the nonlinear system specifically on the coarse time mesh.

Theorem 1. Suppose that the exact solutions $v^n, \phi^n$ to the initial boundary value problem Equation (1) is sufficiently smooth and let $u_{C,i}^n, \rho_{C,i}^n$ be the numerical solutions on the coarse time mesh. Then,

\[
\| v^n - u_{C,i}^n \|_{\infty} \leq O(h^2 + \tau_c), \| \phi^n - \rho_{C,i}^n \| \leq O(h^2 + \tau_c).
\]

Proof. Denote $e_{C,i}^k = v_{C,i}^k - u_{C,i}^k, \eta_{C,i}^k = \phi_{C,i}^k - \rho_{C,i}^k, 1 \leq j \leq J - 1, 0 \leq k \leq P$. Subtracting Equation (4) from Equation (2) and Equation (5) from Equation (3), we obtain

\[
Er_{C,i}^k = (e_{C,i}^k)_t + \left( \eta_{C,i}^{k+1} \right)_\xi - \left( e_{C,i}^k \right)_{\xi t}
+ \frac{1}{3} \left\{ f_{e_{C,i}^k}^{k+\frac{1}{2}} + \left( f_{e_{C,i}^k}^{k+\frac{1}{2}} \right)_\xi + \left( \left( f_{e_{C,i}^k}^{k+\frac{1}{2}} \right) \right)_\xi \right\}
- \frac{1}{3} \left\{ f_{e_{C,i}^k}^{k+\frac{1}{2}} + \left( f_{e_{C,i}^k}^{k+\frac{1}{2}} \right)_\xi + \left( \left( f_{e_{C,i}^k}^{k+\frac{1}{2}} \right) \right)_\xi \right\}.
\]

\[
Es_{C,i}^k = (\eta_{C,i}^k)_t + \left( e_{C,i}^k \right)_\xi.
\]
The proof contains two cases. Firstly, we consider the case of \( n = ks(k = 0, 1, 2, \ldots, P) \), then \( n + 1 = (k + 1)s \). The initial and boundary condition satisfies

\[
e_{C,j}^0 = 0, \quad \eta_{C,j}^0 = 0, \\
u_{C,0}^0 = u_{C,j}^0 = 0, \quad \rho_{C,0}^0 = \rho_{C,j}^0 = 0.
\]

Taking the inner product \((\cdot, \cdot)\) on both sides of Equation (10) with \( e_{C}^{n+1} + e_{C}^n \), we have

\[
(Er_{C}^n, e_{C,j}^{n+1} + e_{C,j}^n) = ((e_{C,j}^{n+1})_t, e_{C,j}^n + e_{C,j}^n) + ((\eta_{C,j}^{n+1})_x, e_{C,j}^{n+1} + e_{C,j}^n)
\]

\[
- ((e_{C,j}^n)_{xxt}, e_{C,j}^{n+1} + e_{C,j}^n) + h \sum_{j=1}^{j-1} (I + II)(e_{C,j}^{n+1} + e_{C,j}^n),
\]

where

\[
I = \frac{1}{3} \left[ v_{j}^{n+\frac{1}{2}} (v_{j}^{n+\frac{1}{2}})_x - u_{C,j}^{n+\frac{1}{2}} (u_{C,j}^{n+\frac{1}{2}})_x \right], \quad II = \frac{1}{3} \left\{ \left[ (v_{j}^{n+\frac{1}{2}})^2 \right]_x - \left[ (u_{C,j}^{n+\frac{1}{2}})^2 \right]_x \right\}.
\]

Notice that

\[
((e_{C,j}^n)_t, e_{C,j}^{n+1} + e_{C,j}^n) = \frac{1}{\tau_C} (\|e_{C,j}^{n+1}\|^2 - \|e_{C,j}^n\|^2),
\]

\[
((\eta_{C,j}^{n+1})_x, e_{C,j}^{n+1} + e_{C,j}^n) = -h \sum_{j=1}^{j-1} \eta_{C,j+1}^{n+1} (e_{C,j+1}^{n+1} + e_{C,j}^n)_x,
\]

\[
- ((e_{C,j}^n)_{xxt}, e_{C,j}^{n+1} + e_{C,j}^n) = \frac{1}{\tau_C} (\|e_{C,j}^{n+1}\|^2 - \|e_{C,j}^n\|^2),
\]

\[
h \sum_{j=1}^{j-1} I \cdot (e_{C,j}^{n+1} + e_{C,j}^n) = -\frac{2}{3} h \sum_{j=1}^{j-1} (e_{C,j+1}^{n+\frac{1}{2}} \cdot v_{j}^{n+\frac{1}{2}})_x u_{C,j}^{n+\frac{1}{2}}
\]

\[
- \frac{2}{3} h \sum_{j=1}^{j-1} (e_{C,j+1}^{n+\frac{1}{2}})_x (e_{C,j+1}^{n+\frac{1}{2}} + e_{C,j}^{n+\frac{1}{2}}) u_{C,j}^{n+\frac{1}{2}},
\]

\[
h \sum_{j=1}^{j-1} II \cdot (e_{C,j}^{n+1} + e_{C,j}^n) = \frac{2}{3} h \sum_{j=1}^{j-1} (v_{j}^{n+\frac{1}{2}} \cdot e_{C,j}^{n+\frac{1}{2}})_x u_{C,j}^{n+\frac{1}{2}}
\]

\[
- \frac{2}{3} h \sum_{j=1}^{j-1} u_{C,j}^{n+\frac{1}{2}} e_{C,j}^{n+\frac{1}{2}} e_{C,j}^{n+\frac{1}{2}} (e_{C,j}^{n+\frac{1}{2}})_x,
\]

then substituting Equations (13)–(17) into (12), we have

\[
\|e_{C,j}^{n+1}\|^2 + \|e_{C,j}^{n+1}\|^2 = \|e_{C,j}^n\|^2 + \|e_{C,j}^n\|^2 + \tau_C h \sum_{j=1}^{j-1} \eta_{C,j+1}^{n+1} (e_{C,j+1}^{n+1} + e_{C,j}^n)_x
\]

\[
+ \frac{2}{3} \tau_C h \sum_{j=1}^{j-1} \left[ (e_{C,j}^{n+\frac{1}{2}})_x (e_{C,j+1}^{n+\frac{1}{2}} + e_{C,j}^{n+\frac{1}{2}}) u_{C,j}^{n+\frac{1}{2}} (e_{C,j}^{n+\frac{1}{2}})_x \right]
\]

\[
+ \tau_C (E_{C,j}^n, e_{C,j}^{n+1} + e_{C,j}^n).
\]

From Cauchy–Schwarz inequality, we obtain

\[
(Er_{C}^n, e_{C,j}^{n+1} + e_{C,j}^n) \leq \|Er_{C}^n\|^2 + \frac{1}{2} (\|e_{C,j}^{n+1}\|^2 + \|e_{C,j}^n\|^2).
\]
Using Lemma 1, the Equation (18) can be rewritten as
\[
\|e_n^{t+1}\|^2 + \|e_n^{t+1}\|^2 \leq \|e_n^t\|^2 + \|e_n^t\|^2 \\
+ M \tau_C (\|\eta_n^{t+1}\|^2 + \|e_n^{t+1}\|^2 + \|e_n^{t+1}\|^2 + \|e_n^{t+1}\|^2 + \tau_C \|E_n\|^2).
\] (19)

Similarly, taking the inner product \((\cdot, \cdot)\) on both sides of Equation (11) with \(\eta_n^{t+1} + \eta_n^t\), we obtain
\[
\|\eta_n^{t+1}\|^2 = \|\eta_n^t\|^2 - \tau_C \sum_{j=1}^{p-1} (e_n^{t,j})_x (\eta_n^{t,j} + \eta_n^t) + \tau_C (E_n, \eta_n^{t+1} + \eta_n^t). 
\] (20)

From the Cauchy–Schwarz inequality, we have
\[
(E_n, \eta_n^{t+1} + \eta_n^t) \leq \|E_n\|^2 + \frac{1}{2} (\|\eta_n^{t+1}\|^2 + \|\eta_n^t\|^2).
\]
Using Lemma 1, the Equation (20) can be rewritten as
\[
\|\eta_n^{t+1}\|^2 \leq \|\eta_n^t\|^2 + M \tau_C (\|e_n^{t+1}\|^2 + \|\eta_n^{t+1}\|^2 + \|\eta_n^t\|^2) + \tau_C \|E_n\|^2.
\] (21)

Add Equations (19) and (21), we obtain
\[
\|e_n^{t+1}\|^2 + \|e_n^{t+1}\|^2 \leq \|e_n^t\|^2 + \|e_n^t\|^2 + \|e_n^t\|^2 \\
+ M \tau_C (\|\eta_n^{t+1}\|^2 + \|\eta_n^t\|^2 + \|\eta_n^{t+1}\|^2 + \|\eta_n^t\|^2 + \|e_n^{t+1}\|^2 + \|e_n^t\|^2) \\
+ \tau_C \|E_n\|^2 + \tau_C \|E_n\|^2.
\] (22)

Let \(B_n = \|e_n^0\|^2 + \|e_n^{t+1}\|^2 + \|\eta_n^t\|^2\), then Equation (22) becomes
\[
B_n^{t+1} - B_n^t \leq M \tau_C (B_n^{t+1} + B_n^t) + M \tau_C (h^2 + \tau_C)^2,
\]
and obtain
\[
(1 - M \tau_C) (B_n^{t+1} - B_n^t) \leq 2 M \tau_C B_n^t + M \tau_C (h^2 + \tau_C)^2.
\]
By taking \(\tau_C\) small enough so that \((1 - M \tau_C) > 0\), then
\[
B_n^{t+1} - B_n^t \leq M \tau_C B_n^t + M \tau_C (h^2 + \tau_C)^2.
\] (23)

Summing from 0 to \(P - 1\) inequalities in Equation (23), we have
\[
B_n^P - B_n^0 \leq M \tau_C \sum_{n=1}^{P-1} B_n^0 + M (h^2 + \tau_C)^2,
\]
and using Lemma 2, we obtain
\[
B_n^P \leq [B_n^0 + M (h^2 + \tau_C)^2]^e^{M \tau_C}.
\] (24)

From Equation (24) and the initial and boundary condition, we have
\[
\|e_n^0\| < O(h^2 + \tau_C), \|e_n^P\| < O(h^2 + \tau_C), \|\eta_n^t\| < O(h^2 + \tau_C).
\] (25)
Then using Lemma 3, we obtain
\[
\|e_n^t\|_\infty < O(h^2 + \tau_C).
\] (26)
Secondly, we consider the case of \( n = ks - l, (l = 1, 2, \ldots, s - 1 \text{ and } k = 1, 2, \ldots, P, ks - l = n) \). Based on the Lagrange’s interpolation formula, we obtain
\[
\frac{v^{ks-l}}{s} = \frac{t_{ks-l} - t_{ks}}{t_{(k-1)s} - t_{ks}} v^{(k-1)s} + \frac{t_{ks-l} - t_{(k-1)s}}{t_{ks} - t_{(k-1)s}} v^{ks} = \frac{1}{s} v^{(k-1)s} + (1 - \frac{1}{s}) v^{ks} + \frac{v''(\theta_1)}{2} (t - t_{(k-1)s})(t - t_{ks}), \quad \theta_1 \in (t_{(k-1)s}, t_{ks}),
\]
(27)
\[
\frac{q^{ks-l}}{s} = \frac{t_{ks-l} - t_{ks}}{t_{(k-1)s} - t_{ks}} q^{(k-1)s} + \frac{t_{ks-l} - t_{(k-1)s}}{t_{ks} - t_{(k-1)s}} q^{ks} = \frac{1}{s} q^{(k-1)s} + (1 - \frac{1}{s}) q^{ks} + \frac{q''(\theta_2)}{2} (t - t_{(k-1)s})(t - t_{ks}), \quad \theta_2 \in (t_{(k-1)s}, t_{ks}).
\]
(28)
Subtracting Equation (27) from (6), we have
\[
v^{ks-l} - u^{ks-l} C = \frac{1}{s} (v^{(k-1)s} - u^{ks-l} C) + (1 - \frac{1}{s}) (v^{ks} - u^{ks-l} C) + \frac{v''(\theta_1)}{2} (t - t_{(k-1)s})(t - t_{ks}).
\]
Subtracting Equation (28) from (7), we obtain
\[
q^{ks-l} - \rho^{ks-l} C = \frac{1}{s} (q^{(k-1)s} - \rho^{ks-l} C) + (1 - \frac{1}{s}) (q^{ks} - \rho^{ks-l} C) + \frac{q''(\theta_2)}{2} (t - t_{(k-1)s})(t - t_{ks}).
\]
Using (25), (26) and triangle inequality, we conclude
\[
\|e^{ls-l} C\| \leq O(h^2 + \tau C), \|\eta^{ls-l} C\| \leq O(h^2 + \tau C).
\]
We obtain the result of Theorem 1 by synthesizing the aforementioned two cases. \( \square \)

Next, we give the convergence analysis of the scheme on the fine time mesh.

**Theorem 2.** Suppose that the exact solutions \( v^n, q^n \) to the initial boundary value problem Equation (1) is sufficiently smooth and let \( u^n F, \rho^n F \) be the numerical solutions on the fine time mesh. Then,
\[
\|v^n - u^n F\| \leq O(h^2 + \tau F), \|q^n - \rho^n F\| \leq O(h^2 + \tau F).
\]
**Proof.** Assume \( e^n F, j = v^n - u^n F, j, \eta^n F, j = q^n - \rho^n F, j \leq j \leq j - 1, 0 \leq n \leq N \), Subtracting Equation (8) from Equation (2) and Equation (9) from Equation (3), we obtain
\[
E e^n F, j = (e^n F, j)_{s} + (\eta^{n+1} F, j)_{s} - (e^n F, j)_{s} + \frac{1}{6h} \left[ f x e^{n+1} F, j-1 + f y e^{n+1} F, j + f z e^{n+1} F, j+1 + Q \right],
\]
(29)
\[
E \eta^n F, j = (\eta^{n+1} F, j)_{s} - (e^n F, j)_{s},
\]
(30)
where
\[
Q = \frac{1}{2} \left[ f x e^{n+1} F, j-1 (e^{n+1} C, j-1)^2 + f y (e^{n+1} C, j)^2 + f z (e^{n+1} C, j+1)^2 \right]
\]
\[+ f x e^{n+1} C, j-1 (e^{n+1} C, j)^2 + f y (e^{n+1} C, j+1)^2 + f z (e^{n+1} C, j-1, j)^2 + f y (e^{n+1} C, j+1)^2 + f z (e^{n+1} C, j-1, j)^2 + f y (e^{n+1} C, j+1)^2 + f z (e^{n+1} C, j-1, j)^2],
\]
and \( f x x = f x x(\xi, \nu, \delta), f y y = f y y(\xi, \nu, \delta), f z z = f z z(\xi, \nu, \delta), f x y = f x y(\xi, \nu, \delta), f x z = f x z(\xi, \nu, \delta), f y z = f y z(\xi, \nu, \delta) \) are the second order partial derivatives of \( f(x, y, z), \xi \in (v_{n-1} F, j, v_{n-1} F, j+1), \)
\( \nu \in (v^n F, j), \delta \in (v^n F, j-1, j^{n+1} F, j), \).
Taking the inner product \((\cdot, \cdot)\) on both sides of Equation (29) with \(e_F^{n+1} + e_F^n\), we have

\[
\|e_F^{n+1}\|^2 + \|e_F^n\|^2 = \|e_F\|^2 + \|e_F^{n+1}\|^2 + \tau_F \sum_{j=1}^{l-1} \left\{ \eta_F^{n+1} \left[ (e_F^{n+1})_x + (e_F^{n+1})_x \right] \right\} \\
- \frac{\tau_F}{3} \sum_{j=1}^{l-1} (f_x e_{F,j-1}^{n+\frac{1}{2}} + f_y e_{F,j}^{n+\frac{1}{2}} = f_x e_{F,j+1}^{n+\frac{1}{2}} e_{F,j}^{n+\frac{1}{2}} - \frac{\tau_F}{3} \sum_{j=1}^{l-1} Q e_{F,j}^{n+\frac{1}{2}} + 2\tau_F (E r_F^{n+1}, e_F^{n+\frac{1}{2}}). \tag{31}
\]

Using \(f_y = \frac{1}{2} (f_x + f_z)\) and \(f_{xx} = -2, f_{yy} = 0, f_{zz} = 2, f_{xy} = -1, f_{xz} = 0, f_{yz} = 1\), we obtain

\[
\sum_{j=1}^{l-1} (f_x e_{F,j-1}^{n+\frac{1}{2}} + f_y e_{F,j}^{n+\frac{1}{2}} = f_x e_{F,j+1}^{n+\frac{1}{2}} e_{F,j}^{n+\frac{1}{2}} = \frac{3}{\eta} (f_y e_{F}^{n+\frac{1}{2}}, e_{F}^{n+\frac{1}{2}}) + (f_x e_{F,x}^{n+\frac{1}{2}}, e_{F}^{n+\frac{1}{2}}), \tag{32}
\]

\[
\sum_{j=1}^{l-1} Q e_{F,j}^{n+\frac{1}{2}} = \frac{1}{2} \sum_{j=1}^{l-1} (f_x e_{F,j-1}^{n+\frac{1}{2}}) (e_{F,j-1}^{n+\frac{1}{2}}\) + f_y (e_{F,j}^{n+\frac{1}{2}}) (e_{F,j}^{n+\frac{1}{2}}) + f_x (e_{F,j+1}^{n+\frac{1}{2}}) (e_{F,j}^{n+\frac{1}{2}}) + f_y (e_{F,j}^{n+\frac{1}{2}}) (e_{F,j+1}^{n+\frac{1}{2}}) = ((e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\) - ((e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\) + (e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\) - (e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\).
\]

Using Lemma 1 and the Cauchy–Schwarz inequality, we have

\[
\frac{\tau_F}{3} (f_x e_{F,x}^{n+\frac{1}{2}} + e_{F}^{n+\frac{1}{2}}) - \frac{\tau_F}{\eta} (f_y e_{F}^{n+\frac{1}{2}}, e_{F}^{n+\frac{1}{2}}) - \frac{\tau_F}{3} (f_x e_{F,x}^{n+\frac{1}{2}}) \leq M \tau_F \left( \|e_{F,x}^{n+\frac{1}{2}}\|_2 + \|e_{F}^{n+\frac{1}{2}}\|_2 \right), \tag{34}
\]

\[
- \frac{\tau_F}{3} ((e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\) + \frac{\tau_F}{3} ((e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\) - \frac{\tau_F}{3} (e_{C}^{n+\frac{1}{2}}\) s, e_{F}^{n+\frac{1}{2}}\) \leq M \tau_F (\|e_{C,x}^{n+\frac{1}{2}}\|_2 \|e_{C}^{n+\frac{1}{2}}\|_2^2 + \|e_{F,x}^{n+\frac{1}{2}}\|_2^2 + \|e_{F}^{n+\frac{1}{2}}\|_2^2) + 2 \tau_F \left( E r_F^{n+1} \right) \leq \tau_F \left( \|E r_F^{n+1}\|_2 + M \tau_F \|e_{F}^{n+\frac{1}{2}}\|_2. \tag{36}
\]

Substituting Equations (34) and (35) into (31), then

\[
\|e_F^{n+1}\|^2 + \|e_F^n\|^2 \leq \|e_F^0\|^2 + \|e_F^n\|^2 + M \tau_F (\|\eta_F^{n+1}\|_2 + \|\eta_F^n\|_2 + \|\eta_F^0\|_2 + \|\eta_F^n\|_2) + M \tau_F (\|\eta_F^{n+1}\|_2 \|\eta_F^n\|_2^2 + \|\eta_F^0\|_2^2 + \|\eta_F^n\|_2^2 + \|\eta_F^n\|_2^2) + \tau_F \left( E r_F^{n+1} \right) \leq \tau_F \left( \|E r_F^{n+1}\|_2 + M \tau_F \|e_F^{n+\frac{1}{2}}\|_2. \tag{37}
\]

Taking the inner product \((\cdot, \cdot)\) on both sides of Equation (30) with \(\eta_F^{n+1} + \eta_F^n\), we obtain

\[
\|\eta_F^{n+1}\|^2 \leq \|\eta_F^0\|^2 + M \tau_F (\|\eta_F^n\|_2^2 + \|\eta_F^0\|_2^2 + \|\eta_F^n\|_2^2 + \tau_F \left( E r_F^n \right) \leq \tau_F \left( \|E r_F^{n+1}\|_2 + M \tau_F \|e_F^{n+\frac{1}{2}}\|_2. \tag{38}
\]
Add Equations (37) and (38), we have
\[
\|e^n_{c,x}\|^2 + \|e^{n+1}_{c,x}\|^2 + \|\eta^n_F\|^2 \leq \|e^n_F\|^2 + \|e^{n+1}_F\|^2 + M\tau_F (\|\eta^{n+1}_F\|^2 + \|\eta^{n+1}_F\|^2 + \|e^{n+1}_{c,x}\|^2 + \|e^{n+1}_{c,x}\|^2) + M\tau_F (\|e^{n+1}_{c,x}\|^2 + \|\eta^{n+1}_F\|^2) + \tau_F ||E^{n+1}_F||^2 + \tau_F ||E^{n+1}_F||^2.
\]
(39)
Let \(B^n_F = \|e^n_F\|^2 + \|e^{n+1}_{c,x}\|^2 + \|\eta^n_F\|^2\), then
\[
B^n_F + B^n_F \leq M\tau_F (B^{n+1}_F + B^n_F) + M\tau_F (\|e^{n+1}_{c,x}\|^2 + \|e^{n+1}_{c,x}\|^2) + \tau_F ||E^{n+1}_F||^2 + \tau_F ||E^{n+1}_F||^2,
\]

and obtain
\[
(1 - M\tau_F)(B^{n+1}_F + B^n_F) \leq 2M\tau_F B^n_F + M\tau_F (h^4 + \tau_C^4 + \tau_F^2).
\]

By taking \(\tau_F\) small enough so that \((1 - M\tau_F) > \lambda > 0\), then
\[
B^{n+1}_F + B^n_F \leq M\tau_F (h^4 + \tau_C^4 + \tau_F^2) + M\tau_F B^n_F.
\]
(40)
Summing from 0 to \(N-1\) inequalities in Equation (40), we obtain
\[
B^N_F \leq B^0_F + M(h^4 + \tau_C^4 + \tau_F^2) + M\tau_F \sum_{n=0}^{N-1} B^n_F.
\]
(41)
Using Lemma 2, we obtain
\[
B^N_F \leq [B^0_F + M(h^4 + \tau_C^4 + \tau_F^2)]e^{MN\tau_F}.
\]
(42)
From Equation (42) and the initial and boundary condition, we have
\[
\|e^n_F\| \leq O(h^2 + \tau_C^2 + \tau_F), \|e^{n+1}_{c,x}\| \leq O(h^2 + \tau_C^2 + \tau_F), \|\eta^n_F\| \leq O(h^2 + \tau_C^2 + \tau_F).
\]
(43)
Using Lemma 3, it led to
\[
\|e^n_{c,x}\|_\infty \leq O(h^2 + \tau_C^2 + \tau_F).
\]
(44)
This completes the proof of Theorem 2. \(\Box\)

Next, we prove stability of the scheme on the coarse time mesh.

**Theorem 3.** Suppose that \(u_0 \in H_{0,0}[x_L,x_R]\), if \(\tau_C\) and \(h\) are sufficiently small, then the proposed scheme (4)–(5) is stable with respect to the initial conditions.

**Proof.** The proof contains two cases. Firstly, we consider the case of \(n = ks(k = 0,1,2,\ldots,P)\). Taking the inner product \((\cdot,\cdot)\) on both sides of Equation (4) with \(u^{n+1}_c + u^n_c\), we have
\[
\|u^{n+1}_c\|^2 - \|u^n_c\|^2 + \|u^{n+1}_{c,x}\|^2 - \|u^n_{c,x}\|^2
\]
\[
+ \tau_Ch \sum_{j=1}^{l-1} [-\rho^{n+1}_{c,j}(u^{n+1}_{c,j})_s - \rho^n_{c,j}(u^n_{c,j})_s] = 0.
\]
(45)
Taking the inner product \((\cdot,\cdot)\) on both sides of Equation (5) with \(\rho^{n+1}_c + \rho^n_c\), we obtain
\[
\|\rho^{n+1}_c\|^2 - \|\rho^n_c\|^2 + \tau_Ch \sum_{j=1}^{l-1} [(u^n_{c,j})_s \rho^{n+1}_{c,j} + (u^n_{c,j})_s \rho^n_{c,j}] = 0.
\]
(46)
Add Equations (45) and (46), we obtain

$$
\|u_{C}^{n+1}\|^{2} + \|u_{C,x}^{n+1}\|^{2} + \|P_{C}^{n+1}\|^{2} = \|u_{C}^{n}\|^{2} + \|u_{C,x}^{n}\|^{2} + \|P_{C}^{n}\|^{2}
$$

$$
+ \tau_{C}h \sum_{j=1}^{l-1} \rho_{C,j}^{n+1}(u_{C,j}^{n+1})_{x} - \tau_{C}h \sum_{j=1}^{l-1} (u_{C,j}^{n})_{x} \rho_{C,j}^{n},
$$

$$
(47)
$$

$$
\leq \|u_{C}^{n}\|^{2} + \|u_{C,x}^{n}\|^{2} + \|P_{C}^{n}\|^{2}
$$

$$
+ M\tau_{C}(\|P_{C}^{n+1}\|^{2} + \|P_{C}^{n}\|^{2} + \|u_{C}^{n+1}\|^{2} + \|u_{C}^{n}\|^{2} + \|u_{C,x}^{n+1}\|^{2} + \|u_{C,x}^{n}\|^{2}).
$$

Let $D_{C}^{n} = \|u_{C}^{n}\|^{2} + \|u_{C,x}^{n}\|^{2} + \|P_{C}^{n}\|^{2}$, then Equation (47) becomes

$$
D_{C}^{n+1} - D_{C}^{n} \leq M\tau_{C}(D_{C}^{n+1} + D_{C}^{n}),
$$

and obtain

$$
(1 - M\tau_{C})(D_{C}^{n+1} - D_{C}^{n}) \leq 2M\tau_{C}D_{C}^{n}.
$$

By taking $\tau_{C}$ small enough so that $1 - M\tau_{C} > \lambda > 0$, then

$$
D_{C}^{n+1} - D_{C}^{n} \leq M\tau_{C}D_{C}^{n},
$$

(48)

Summing from 0 to $p - 1$ inequalities in Equation (48), we have

$$
D_{C}^{N} \leq D_{C}^{0} + M\tau_{C} \sum_{n=0}^{N-1} D_{C}^{n},
$$

and using Lemma 2, we obtain

$$
D_{C}^{N} \leq D_{C}^{0} e^{M\tau_{C}},
$$

(49)

that is

$$
\|u_{C}^{N}\|^{2} + \|u_{C,x}^{N}\|^{2} + \|P_{C}^{N}\|^{2} \leq M(\|u_{C}^{0}\|^{2} + \|u_{C,x}^{0}\|^{2} + \|P_{C}^{0}\|^{2}).
$$

Secondly, we consider the case of $n = ks - l, (l = 1, 2, \ldots, s - 1$ and $k = 1, 2, \ldots, p, ks - l = n)$. From Equations (6) and (7), we obtain

$$
\|u_{C}^{ks-l}\| \leq \frac{1}{s} \|u_{C}^{(k-1)s}\| + (1 - \frac{1}{s}) \|u_{C}^{ks}\| \leq M(\|u_{C}^{0}\| + \|u_{C,x}^{0}\| + \|P_{C}^{0}\|),
$$

$$
\|P_{C}^{ks-l}\| \leq \frac{1}{s} \|P_{C}^{(k-1)s}\| + (1 - \frac{1}{s}) \|P_{C}^{ks}\| \leq M(\|u_{C}^{0}\| + \|u_{C,x}^{0}\| + \|P_{C}^{0}\|).
$$

The results obtained in the aforementioned two cases mean that the solution of scheme (4)–(5) is stable on the coarse time mesh. This completes the proof of Theorem 3. □

Next, we present stability analysis of the scheme on the fine time mesh.

**Theorem 4.** Suppose that $u_{0} \in H_{p,0}[x_{L}, x_{R}]$, if $\tau_{F}$ and $h$ are sufficiently small, then the proposed scheme (8)–(9) is stable with respect to the initial conditions.
Proof. Taking the inner product $(\cdot, \cdot)$ on both sides of Equation (8) with $u_{F}^{n+1} + u_{F}^{n}$, we have
\[
\frac{1}{\tau}([u_{F}^{n+1}]^2 + [u_{F,x}^{n+1}]^2) = \frac{1}{\tau}([u_{F}^{n}]^2 + [u_{F,x}^{n}]^2) - h \sum_{j=1}^{l-1} [-\rho_{F,j}^{n+1} (u_{F,j}^{n+1})_x - \rho_{F,j}^{n} (u_{F,j}^{n})_x]
- \frac{1}{3} \sum_{j=1}^{l-1} ((u_{F,j+1}^{n+1} - u_{F,j-1}^{n+1}) u_{F,j}^{n+1} + (u_{F,j+1}^{n})^2 - (u_{F,j-1}^{n+1})^2) u_{F,j}^{n+1} 
- \frac{1}{3} \sum_{j=1}^{l-1} (f_x u_{F,j-1}^{n+1} + f_y u_{F,j}^{n+1} + f_z u_{F,j+1}^{n+1}) u_{F,j}^{n+1} 
+ \frac{1}{3} \sum_{j=1}^{l-1} (f_x u_{F,j-1}^{n+1} + f_y u_{F,j}^{n+1} + f_z u_{F,j+1}^{n+1}) u_{F,j}^{n+1}.
\]
(50)

From the Cauchy–Schwarz inequality, we obtain
\[
- \frac{1}{3} \sum_{j=1}^{l-1} (f_x u_{F,j-1}^{n+1} + f_y u_{F,j}^{n+1} + f_z u_{F,j+1}^{n+1}) u_{F,j}^{n+1} \leq M(||u_{F}^{n+1}||^2 + ||u_{F,x}^{n+1}||^2),
\]
(51)

then substituting Equations (51)–(53) into (50), we have
\[
||u_{F}^{n+1}||^2 + ||u_{F,x}^{n+1}||^2 \leq ||u_{F}^{n}||^2 + ||u_{F,x}^{n}||^2 + \tau h \sum_{j=1}^{l-1} \rho_{F,j}^{n+1} (u_{F,j}^{n+1})_x + \rho_{F,j}^{n} (u_{F,j}^{n})_x
+ M\tau (||u_{C}^{n+1}||^2 + ||u_{C,x}^{n+1}||^2 + ||u_{C}^{n+1}||^2 + ||u_{C,x}^{n+1}||^2)
+ M\tau (||u_{F}^{n+1}||^2 + ||u_{F,x}^{n+1}||^2).
\]
(54)

Taking the inner product $(\cdot, \cdot)$ on both sides of Equation (9) with $\rho_{F}^{n+1} + \rho_{F}^{n}$, we obtain
\[
||\rho_{F}^{n+1}||^2 = ||\rho_{F}^{n}||^2 - \tau h \sum_{j=1}^{l-1} (u_{F,j}^{n})_x \rho_{F,j}^{n+1} + (u_{F,j}^{n})_x \rho_{F,j}^{n}.
\]
(55)

Add Equations (54) and (55), we obtain
\[
||u_{F}^{n+1}||^2 + ||u_{F,x}^{n+1}||^2 + ||\rho_{F}^{n+1}||^2 \leq ||u_{F}^{n}||^2 + ||u_{F,x}^{n}||^2 + ||\rho_{F}^{n}||^2 
+ M\tau (||u_{C}^{n+1}||^2 + ||u_{C,x}^{n+1}||^2 + ||u_{C}^{n+1}||^2 + ||u_{C,x}^{n+1}||^2)
+ M\tau (||u_{F}^{n+1}||^2 + ||u_{F,x}^{n+1}||^2 + ||u_{F}^{n+1}||^2 + ||u_{F,x}^{n+1}||^2).
\]
(56)
Let \( D_F^n = \| u_F^n \|^2 + \| u_{F,x}^n \|^2 + \| \rho_F^n \|^2 \), then combine with the result of Theorem 3, the Equation (56) becomes
\[
D_F^{n+1} - D_F^n \leq M \tau_F (D_F^{n+1} + D_F^n) + M \tau_F (\| u_C^0 \|^2 + \| u_{C,x}^0 \|^2),
\]
and obtain
\[
(1 - M \tau_F) (D_F^{n+1} - D_F^n) \leq 2M \tau_F D_F^n + M \tau_F (\| u_C^0 \|^2 + \| u_{C,x}^0 \|^2).
\]
By taking \( \tau_F \) small enough so that \( 1 - M \tau_F > \lambda > 0 \), then
\[
D_F^{n+1} - D_F^n \leq M \tau_F D_F^n + M \tau_F (\| u_C^0 \|^2 + \| u_{C,x}^0 \|^2). \tag{57}
\]
Summing from 0 to \( N - 1 \) inequalities in Equation (57), we obtain
\[
\sum_{n=0}^{N-1} (D_F^{n+1} - D_F^n) \leq M \tau_F \sum_{n=0}^{N-1} D_F^n + M (\| u_C^0 \|^2 + \| u_{C,x}^0 \|^2),
\]
and then
\[
D_F^N \leq D_F^0 + M \tau_F \sum_{n=0}^{N-1} D_F^n + M (\| u_C^0 \|^2 + \| u_{C,x}^0 \|^2). \tag{59}
\]
Using Lemma 2, we obtain
\[
D_F^N \leq [D_F^0 + M (\| u_C^0 \|^2 + \| u_{C,x}^0 \|^2)] e^{MT}, \tag{60}
\]
that is
\[
\| u_F^0 \|^2 + \| u_{F,x}^0 \|^2 + \| \rho_F^0 \|^2 \leq M (\| u_F^0 \|^2 + \| u_{F,x}^0 \|^2 + \| \rho_F^0 \|^2 + \| u_C^0 \|^2 + \| u_{C,x}^0 \|^2). \tag{61}
\]
Notice that \( \| u_C^0 \|^2 = \| u_F^0 \|^2, \| u_{C,x}^0 \|^2 = \| u_{F,x}^0 \|^2 \), then
\[
\| u_F^0 \|^2 + \| u_{F,x}^0 \|^2 + \| \rho_F^0 \|^2 \leq M (\| u_F^0 \|^2 + \| u_{F,x}^0 \|^2 + \| \rho_F^0 \|^2), \tag{62}
\]
which indicates that the solution of scheme (8)–(9) is stable on the fine time mesh. This completes the proof of Theorem 4. \( \square \)

5. Numerical Results

This section provides some numerical examples aimed at demonstrating the accuracy and computational time of the TT-M finite difference scheme that was discussed in Section 3. All simulations were implemented using a Intel(R) i7-10710U 1.61 GHz CPU and 16 GB memory personal computer running Windows 10 and Matlab R2019b. The SRLW equation is represented in the following formation:

\[
\begin{align*}
&u_t + \rho_x + uu_x - u_{xxt} = 0, \quad -40 \leq x \leq 40, \quad 0 < t \leq 4, \\
&\rho_t + u_x = 0, \quad -40 \leq x \leq 40, \quad 0 < t \leq 4, \\
&u(x_L, t) = u(x_R, t) = 0, \quad \rho(x_L, t) = \rho(x_R, t) = 0, \quad 0 < t \leq 4, \\
&u(x, 0) = u_0(x), \quad \rho(x, 0) = \rho_0(x), \quad -40 \leq x \leq 40.
\end{align*}
\]

and consider the following initial conditions
\[
u_0(x) = \frac{5}{2} sech^2 \frac{\sqrt{5}}{6} x, \quad \rho_0(x) = \frac{5}{3} sech^2 \frac{\sqrt{5}}{6} x.
\]
The exact solitary wave solution [4] of the SRLW Equation (1) has the following form

\[ u(x, t) = \frac{3(v^2 - 1)}{v} \text{sech}^2 \left( \sqrt{\frac{v^2 - 1}{4v^2}} (x - vt) \right), \]

\[ \rho(x, t) = \frac{3(v^2 - 1)}{v^2} \text{sech}^2 \left( \sqrt{\frac{v^2 - 1}{4v^2}} (x - vt) \right), \]

which takes the form of

\[ u(x, t) = \frac{5}{2} \text{sech}^2 \left( \frac{\sqrt{5}}{6} (x - \frac{3}{2}t) \right), \quad \rho(x, t) = \frac{5}{3} \text{sech}^2 \left( \frac{\sqrt{5}}{6} (x - \frac{3}{2}t) \right), \]

when we set \( v = 1.5 \).

Next, we presented some values of error, convergence rate, conservation laws and long time simulation of the proposed scheme.

5.1. Error and Convergence Rate

We define the error and convergence rate by the following formula:

\[ e_m(h, \tau) = \|u^n - u_m^n\|_{\infty}, \quad \eta_m(h, \tau) = \|q^n - \rho_m^n\|, \]

\[ u\text{Rate}_m^x = \log_2 \left( \frac{e_m(2h, 4\tau)}{e_m(h, \tau)} \right), \quad \rho\text{Rate}_m^x = \log_2 \left( \frac{\eta_m(2h, 4\tau)}{\eta_m(h, \tau)} \right), \]

\[ u\text{Rate}_m^t = \log_2 \left( \frac{e_m(2h, 2\tau)}{e_m(h, \tau)} \right), \quad \rho\text{Rate}_m^t = \log_2 \left( \frac{\eta_m(2h, 2\tau)}{\eta_m(h, \tau)} \right), \]

where \( m \) represents the TT-M finite difference scheme or the standard nonlinear finite difference (SNFD) scheme in [22]. We set \( \tau_C = 4\tau_F \) in the whole numerical illustration process.

In order to illustrate the advantage of this approach, we calculated the error, convergence rate and computational time of the presented scheme and compared these numerical results with those obtained from scheme in [22]. Tables 1 and 2 present discrete norm errors, the corresponding convergence rates and the time cost for both the TT-M finite difference scheme and the SNFD scheme in [22] under \( \tau_F = h^2 \) and \( h = \tau_F \), respectively. We recorded the error of both schemes at the final time \( t = 4 \) for various mesh steps. The results from the new scheme show nearly identical important values as those obtained by the SNFD scheme in [22]. In term of the convergence rate, the results indicate that both the TT-M finite difference scheme and the SNFD scheme achieve approximately second-order convergence in space when \( \tau_F = h^2 \) and first-order in time when \( h = \tau_F \), which confirming the theoretical results in Theorem 2. Especially, the proposed scheme achieves a remarkable reduction in computation time of over 30 percent as compared to the SNFD scheme under \( \tau_F = h^2 \) and nearly half the computational time of the SNFD scheme under \( h = \tau_F \). The obtained results demonstrate a clear improvement achieved by our scheme over the previous method reported by [22].

The 3D images of numerical solutions of \( u(x, t) \) and \( \rho(x, t) \) computed by the present scheme were shown in Figure 1. From the graph, one can see the propagation state of waves over a period of time. Figure 2 illustrates the exact and numerical solutions of \( u(x, t) \) and \( \rho(x, t) \) at \( t = 4 \) obtained by the present scheme. It is evident that our numerical solutions exhibit an excellent correspondence with the exact solution. Furthermore, the CPU times of the two schemes are plotted in Figure 3 under \( \tau_F = h^2 \) and \( h = \tau_F \), respectively. From the figure, it is also can be seen that the present scheme can significantly decrease computation time. To sum up, compared with the method in [22], the scheme proposed in this paper not only ensures error and convergence order, but also greatly reduces computational time.
Table 1. The errors and convergence rates with $\tau_F = h^2$.

<table>
<thead>
<tr>
<th>$\tau_F$</th>
<th>$e_{\text{SNFD}}(h, \tau_F)$</th>
<th>$u\text{Rate}^e_{\text{SNFD}}$</th>
<th>$\eta_{\text{SNFD}}(h, \tau_F)$</th>
<th>$\rho\text{Rate}^e_{\text{SNFD}}$</th>
<th>CPU(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$h = 1/8$</td>
<td>8.2798 x 10^{-2}</td>
<td>2.9797 x 10^{-1}</td>
<td>0.14</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$h = 1/16$</td>
<td>2.0361 x 10^{-2}</td>
<td>7.3503 x 10^{-2}</td>
<td>2.02</td>
<td>2.02</td>
<td>0.51</td>
</tr>
<tr>
<td>$h = 1/32$</td>
<td>5.0629 x 10^{-3}</td>
<td>1.8306 x 10^{-2}</td>
<td>2.01</td>
<td>12.30</td>
<td></td>
</tr>
<tr>
<td>$h = 1/64$</td>
<td>1.2641 x 10^{-3}</td>
<td>4.5719 x 10^{-3}</td>
<td>2.00</td>
<td>136.31</td>
<td></td>
</tr>
<tr>
<td>$h = 1/128$</td>
<td>3.1597 x 10^{-4}</td>
<td>1.1427 x 10^{-3}</td>
<td>2.00</td>
<td>1943.47</td>
<td></td>
</tr>
</tbody>
</table>

Present scheme

<table>
<thead>
<tr>
<th>$\tau_F$</th>
<th>$e_{TT-M}(h, \tau_F)$</th>
<th>$u\text{Rate}^e_{TT-M}$</th>
<th>$\eta_{TT-M}(h, \tau_F)$</th>
<th>$\rho\text{Rate}^e_{TT-M}$</th>
<th>CPU(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$h = 1/8$</td>
<td>8.3934 x 10^{-2}</td>
<td>3.0015 x 10^{-1}</td>
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<td></td>
</tr>
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<td>$h = 1/16$</td>
<td>2.0361 x 10^{-2}</td>
<td>7.3555 x 10^{-2}</td>
<td>2.03</td>
<td>0.30</td>
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</tr>
<tr>
<td>$h = 1/32$</td>
<td>5.0629 x 10^{-3}</td>
<td>1.8308 x 10^{-2}</td>
<td>2.01</td>
<td>7.53</td>
<td></td>
</tr>
<tr>
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<td>1.2641 x 10^{-3}</td>
<td>4.5721 x 10^{-3}</td>
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<td>76.99</td>
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</tr>
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<td>$h = 1/128$</td>
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<td>1297.88</td>
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</tr>
</tbody>
</table>

Table 2. The errors and convergence rates with $h = \tau_F$.

<table>
<thead>
<tr>
<th>$\tau_F$</th>
<th>$e_{\text{SNFD}}(h, \tau_F)$</th>
<th>$u\text{Rate}^e_{\text{SNFD}}$</th>
<th>$\eta_{\text{SNFD}}(h, \tau_F)$</th>
<th>$\rho\text{Rate}^e_{\text{SNFD}}$</th>
<th>CPU(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$h = 1/8$</td>
<td>3.1920 x 10^{-2}</td>
<td>1.1381 x 10^{-1}</td>
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<td></td>
</tr>
<tr>
<td>$h = 1/16$</td>
<td>1.5552 x 10^{-2}</td>
<td>5.5256 x 10^{-2}</td>
<td>1.04</td>
<td>14.09</td>
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</tr>
<tr>
<td>$h = 1/32$</td>
<td>7.6748 x 10^{-3}</td>
<td>2.7221 x 10^{-2}</td>
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<tr>
<td>$h = 1/64$</td>
<td>3.8121 x 10^{-3}</td>
<td>1.3509 x 10^{-2}</td>
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<td>770.01</td>
<td></td>
</tr>
<tr>
<td>$h = 1/128$</td>
<td>1.8997 x 10^{-3}</td>
<td>6.7298 x 10^{-3}</td>
<td>1.00</td>
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</tr>
</tbody>
</table>

Present scheme

<table>
<thead>
<tr>
<th>$\tau_F$</th>
<th>$e_{TT-M}(h, \tau_F)$</th>
<th>$u\text{Rate}^e_{TT-M}$</th>
<th>$\eta_{TT-M}(h, \tau_F)$</th>
<th>$\rho\text{Rate}^e_{TT-M}$</th>
<th>CPU(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$h = 1/8$</td>
<td>3.1962 x 10^{-2}</td>
<td>1.1414 x 10^{-1}</td>
<td>1.49</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$h = 1/16$</td>
<td>1.5540 x 10^{-2}</td>
<td>5.5323 x 10^{-2}</td>
<td>1.04</td>
<td>7.10</td>
<td></td>
</tr>
<tr>
<td>$h = 1/32$</td>
<td>7.6694 x 10^{-3}</td>
<td>2.7237 x 10^{-2}</td>
<td>1.02</td>
<td>51.40</td>
<td></td>
</tr>
<tr>
<td>$h = 1/64$</td>
<td>3.8103 x 10^{-3}</td>
<td>1.3513 x 10^{-2}</td>
<td>1.01</td>
<td>414.33</td>
<td></td>
</tr>
<tr>
<td>$h = 1/128$</td>
<td>1.8991 x 10^{-3}</td>
<td>6.7308 x 10^{-3}</td>
<td>1.01</td>
<td>3289.71</td>
<td></td>
</tr>
</tbody>
</table>

Figure 1. Three–dimensional images of $u(x, t)$ (a) and $\rho(x, t)$ (b) with $h = 1/8$, $\tau_F = 1/64$. 
Figure 2. Exact and numerical solution of $u(x, t)$ (a) and $\rho(x, t)$ (b) at $t = 4$ with $h = 1/8, \tau_F = 1/64$.

Figure 3. Comparison of CPU times with $\tau_F = h^2$ (a) and $h = \tau_F$ (b) based on the data in Tables 1 and 2.

5.2. Conservative Approximations

To further verify the accuracy of the new scheme, we calculate four conservation laws of the SRLW Equation (1), such as:

\[
Q_1 = \frac{1}{2} \int_{-\infty}^{\infty} \rho \, dx,
\]

\[
Q_2 = \frac{1}{2} \int_{-\infty}^{\infty} u \, dx,
\]

\[
Q_3 = \frac{1}{2} \int_{-\infty}^{\infty} (u^2 + u_x^2 + \rho^2) \, dx,
\]

\[
Q_4 = \frac{1}{2} \int_{-\infty}^{\infty} (\rho u + \frac{1}{6} u^3) \, dx.
\]

Afterwards, employing discrete forms, we are able to compute four approximate conservative quantities which can be represented as

\[
Q_1 = h \sum_{j=0}^{l-1} \rho_j^n,
\]

\[
Q_2 = h \sum_{j=0}^{l-1} u_j^n,
\]

\[
Q_3 = h \sum_{j=0}^{l-1} (u_j^n)^2 + \frac{1}{2h} \sum_{j=0}^{l-1} (u_{j+1}^n - u_j^n)^2 + \frac{h}{2} \sum_{j=0}^{l-1} (\rho_j^n)^2,
\]

\[
Q_4 = h \sum_{j=0}^{l-1} \rho_j^n u_j^n + \frac{h}{12} \sum_{j=0}^{l-1} (u_j^n)^3.
\]
The values of four quantities are recorded in Tables 3–6. In Tables 3 and 4, regardless of the time step and grid spacing, the quantities $Q_1$ and $Q_2$ remain well-preserved at various times. In Table 5, for the case $h = 1/2$ and $\tau_F = 1/4$, one can see that the quantity $Q_3$ experiences a slight increase as time increases, however, as the spatial and temporal step sizes decrease, the variation of $Q_3$ becomes extremely small. In Table 6, it has been found that for quantity $Q_4$, there was a minor decline under different mesh steps, but it gradually rebounded over time. Meanwhile, as the spatial and temporal step sizes decrease, the $Q_4$ increases slightly. Figure 4 plots the variation curves of four quantities for the case $h = 1/8$ and $\tau_F = 1/64$, which visually demonstrate that our scheme preserves the four conservation laws.

### Table 3. Quantity $Q_1$ under different mesh steps $h$ and $\tau_F$ at various times.

<table>
<thead>
<tr>
<th>TT-M Finite Difference Scheme</th>
<th>$(\frac{1}{2}, \frac{1}{4})$</th>
<th>$(\frac{1}{4}, \frac{1}{16})$</th>
<th>$(\frac{1}{8}, \frac{1}{64})$</th>
<th>$(\frac{1}{16}, \frac{1}{256})$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t = 0.0$</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
<tr>
<td>$t = 0.5$</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
<tr>
<td>$t = 1.0$</td>
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<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
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<td>$t = 1.5$</td>
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<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
<tr>
<td>$t = 2.0$</td>
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<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
<tr>
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<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
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<tr>
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<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
<tr>
<td>$t = 3.5$</td>
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<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
<tr>
<td>$t = 4.0$</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
<td>4.2721359549</td>
</tr>
</tbody>
</table>

### Table 4. Quantity $Q_2$ under different mesh steps $h$ and $\tau_F$ at various times.

<table>
<thead>
<tr>
<th>TT-M Finite Difference Scheme</th>
<th>$(\frac{1}{2}, \frac{1}{4})$</th>
<th>$(\frac{1}{4}, \frac{1}{16})$</th>
<th>$(\frac{1}{8}, \frac{1}{64})$</th>
<th>$(\frac{1}{16}, \frac{1}{256})$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t = 0.0$</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
</tr>
<tr>
<td>$t = 0.5$</td>
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<td>6.7082039324</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
</tr>
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<td>6.7082039324</td>
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<tr>
<td>$t = 1.5$</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
</tr>
<tr>
<td>$t = 2.0$</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
<td>6.7082039324</td>
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<tr>
<td>$t = 2.5$</td>
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<td>6.7082039324</td>
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</tr>
<tr>
<td>$t = 3.0$</td>
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</tr>
<tr>
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<td>6.7082039324</td>
<td>6.7082039324</td>
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</tr>
</tbody>
</table>

### Table 5. Quantity $Q_3$ under different mesh steps $h$ and $\tau_F$ at various times.

<table>
<thead>
<tr>
<th>TT-M Finite Difference Scheme</th>
<th>$(\frac{1}{2}, \frac{1}{4})$</th>
<th>$(\frac{1}{4}, \frac{1}{16})$</th>
<th>$(\frac{1}{8}, \frac{1}{64})$</th>
<th>$(\frac{1}{16}, \frac{1}{256})$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t = 0.0$</td>
<td>17.3814360100</td>
<td>17.3890764778</td>
<td>17.3909982095</td>
<td>17.3914793723</td>
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<tr>
<td>$t = 0.5$</td>
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<td>17.3914810404</td>
</tr>
<tr>
<td>$t = 1.0$</td>
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<td>17.3910850544</td>
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</table>
Table 6. Quantity $Q_4$ under different mesh steps $h$ and $\tau_F$ at various times.

<table>
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<tr>
<th>TT-M Finite Difference Scheme</th>
<th>$\left(\frac{1}{2}, \frac{1}{4}\right)$</th>
<th>$\left(\frac{1}{4}, \frac{1}{16}\right)$</th>
<th>$\left(\frac{1}{8}, \frac{1}{64}\right)$</th>
<th>$\left(\frac{1}{16}, \frac{1}{256}\right)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t = 0.0$</td>
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<td>29.827080111</td>
<td>29.8174683777</td>
<td>29.8150480627</td>
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<tr>
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<td>29.5194998279</td>
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<td>29.794677954</td>
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<tr>
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<td>29.7805099425</td>
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<td>29.7989376025</td>
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</tr>
<tr>
<td>$t = 3.5$</td>
<td>29.635327196</td>
<td>29.773318952</td>
<td>29.8043614200</td>
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<tr>
<td>$t = 4.0$</td>
<td>29.676564108</td>
<td>29.7843463859</td>
<td>29.8071613054</td>
<td>29.8124980105</td>
</tr>
</tbody>
</table>

Figure 4. Quantities $Q_1$ (a), $Q_2$ (b), $Q_3$ (c) and $Q_4$ (d) under mesh steps $h = 1/8$, $\tau_F = 1/64$.

5.3. Long-Time Simulation

Using the parameters $h = 0.1$, $\tau_F = 0.01$, $x_L = -20$, $x_R = 100$ and $T = 40$, the long time waveforms of $u(x,t)$ and $\rho(x,t)$ generated by the present scheme are illustrated in Figure 5. The waveforms at $t = 20$ and 40 demonstrate a significant level of agreement with the waveforms at $t = 0$, which also indicates the accuracy of the scheme. Figure 6 displays the computational times of both the SNFD scheme and proposed scheme at long time. From the graph, it can be seen that the computational time difference between the two schemes grows increasingly as the simulation time increases, which indicates that the longer the simulation time, the more computational time can be saved by the scheme proposed in this paper. This once again proves the advantage of our scheme compared to the SNFD scheme in [22].
Figure 5. Numerical solutions of $u(x, t)$ (a) and $\rho(x, t)$ (b) at long time with $h = 1/10, \tau_F = 1/100$.

Figure 6. Comparison of computation times of the SNFD scheme in [22] with present scheme at long time under $h = 1/10, \tau_F = 1/100$.

6. Conclusions

This paper presents a new time two-mesh finite difference scheme for solving the symmetric regularized long wave equation, which contains a nonlinear derivative term in its formulation. Based on the previous work, our aim is to obtain a scheme that is not only error-preserving but also can save more computational time compared to the scheme in [22]. To achieve this goal, we have constructed a TT-M finite difference scheme that mainly consists of three steps. Firstly, the time interval is divided into coarse and fine time meshes, then the nonlinear system is solved on the coarse time mesh; secondly, coarse numerical solutions on the fine time mesh are computed using an interpolation formula based on the solutions derived in the step one; lastly, the nonlinear term of the SRLW equation is linearized using Taylor’s formula for a function with three variables and constructed the TT-M finite difference linear numerical scheme on the fine time mesh. In terms of theoretical results, we investigated the convergence and stability of numerical solutions. We observed that the solutions obtained from our proposed scheme converged to the exact solutions of the SRLW equation, and the rate of convergence is $O(\tau_C^2 + \tau_F + h^2)$. Additionally, $\tau_F$ and $h$ are sufficiently small, then the proposed scheme (8)–(9) is stable with respect to the initial conditions on the fine time mesh. The numerical results demonstrated that the proposed method effectively supported the analysis of the convergence rate. Meanwhile, one can observe that the errors of $u(x, t)$ and $\rho(x, t)$ in both the SNFD scheme in [22] and the present scheme are nearly identical, but the proposed scheme can reduce the computational time compared with the SNFD scheme. In addition, we calculated four conservation laws of the SRLW equation, regardless of the time step and grid spacing; the four quantities remain well-preserved at various times. The long time simulation example of the proposed scheme is also conducted in this part, the result shows that the waveform always maintains its original state in a long time. The error increases gently as simulation time is extended, which is a limitation of the proposed scheme and it will be improved by other methods in our future work. These findings demonstrate that the proposed method is more effective and yields a better improvement in solving the SRLW equation.
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