Article

Three-Dimensional Thermo-Mechanical Elastic Analysis of Functionally Graded Five Layers Composite Sandwich Plate on Winkler Foundations

Mohammad Reza Kardooni 1,2,*, Mohammad Shishesaz 2 and Reza Mosalmani 2

Abstract: In this work, the first shear deformation theory (FSDT) is used for the thermo-mechanical analysis of a simply supported five-layer functionally Graded (FG) sandwich plate resting on a Winkler elastic foundation. The sandwich plate consists of five layers (two functionally graded face sheets (Al – Al2O3), with aluminum (Al) as the metal and Alumina (Al2O3) as ceramic phases. Two vinyl ester adhesive layers bond the face sheets to an Elastollan core. The governing equations are obtained using the principle of virtual displacements. A uniform distributed load q with constant magnitude is applied on the top face sheet while all layers experience a steady temperature equal to T. We adapted layerwise theory (LT) to solve each layer’s stress distribution. Navier solution is employed to produce the semi-analytical solution results, which are compared with those of three-dimensional finite element analysis obtained by ABAQUS software. A parametric study is presented to observe the effect of the material gradation, variation in plate dimensions, variation in the thermo-mechanical load, and elastic foundation on the deflections and stresses in the functionally graded sandwich plate. For a composite sandwich plate with mechanical load, in the absence of thermal load, results of the first-order shear layer theory obtained by using the Navire method are relatively good in comparison to the normal stresses obtained for investigated points, which are obtained by finite element.

Keywords: sandwich plate; layerwise theory; thermo-elastic; Winkler elastic foundation

1. Introduction

Functionally graded materials (FGMs) were discovered by researchers in Japan to analyze thermal materials and then developed speedily [1]. FGMs often consist of two or more materials whose volume fractions change continuously along certain structure dimensions. The volume fractions of FGM materials are based on functions best describing the material properties in certain directions (i.e., thickness); furthermore, FGMs are capable of withstanding high temperatures [2].

In order to delineate the interactions between the sandwich plate and its bottom elastic foundation, different models are proposed. The simplest model for the elastic foundation is the Winkler model, which considers the foundation as a series of vertical springs without shear effects [3,4]. Mantari and Granados [5] evaluated the stress distribution in an FG sandwich plate under bi-sinusoidal load using first shear deformation theory (FSDT), and the Navier solution was used to solve the problem. The accuracy of the presented theory was determined by comparison with different available solutions in the other papers. Zenkour [6] carried out research on the thermomechanical bending behavior of functionally graded plates (FGPs) resting on an elastic foundation. Thai et al. [7] investigated the FG sandwich plates formed of FG face sheets and an isotropic homogeneous core by using a new first-order shear deformation theory (FSDT), and the results corroborated that the theory was exact, also comparable with the higher-order shear deformation theories.
Thai and Choi [8] worked on a first-order shear deformation theory (FS-DT) for the free vibrational and mechanical analysis of FG plates, and the results revealed that their theory could achieve the same accuracy as the conventional first-order shear deformation theory possessing more unknowns. Natarajan and Manicam [9] conducted research into the bending and free vibrational behavior of FGM material sandwich plates using flexible shear elements, and the exactness of the results was demonstrated. Xu et al. [10] investigated the steady heat conduction analysis of an FGM flat plate under temperature load on its upper surface. Ferreira et al. [11] researched the static and free vibrational analysis of shear flexible composite plates, and the layerwise theory was applied for the study of sandwich composite plates, and precise results were obtained. Kapuria and Achary [12] carried out a study with a higher-order zig-zag theory for the thermal study of sandwich plates and the results revealed that the efficiency of the presented higher-order zigzag theory was generally more than the previous zig-zag theory. Shodja et al. [13] evaluated an exact thermos-elastic solution for a two-dimensional thick FGM that is composed of homogeneous FG layers. The results confirmed that the effects of concentration stress are removed and the interfacial shear stress is lowered when an FG coating is used. Garg et al. [14] researched the static analysis of symmetric and anti-symmetric composite sandwich plates by trigonometric zig-zag theory and the obtained results were supported by those available in the existing literature. Mechab et al. [15] presented the analytical solutions of cross-ply laminated plates subjected to thermal and mechanical load based on higher-order shear deformation theory. The obtained results were in good agreement with those obtained by other studies. Moleiro et al. [16] examined a new layerwise model for the thermo-mechanical analysis of composite plates with FGM layers. The accuracy of the results was approved by comparison with three-dimensional (3D) exact solutions. Raissi et al. [17] used first order and higher-order layerwise theory (LT) to show the stress and deflection distribution for five layers simply supported square sandwich plate with FG face sheets and elastomeric core while two adhesive layers were used to join the core to the face sheets. Findings revealed that the finite element analysis and LT based on the first and higher-order shear deformation theories give.

Kardooni et al. [18] studied the free vibration of five layers composite sandwich plate resting on Winkler elastic foundation. The layerwise theory in conjunction with the third-order and hyperbolic shear deformation (HSDT) theories were used in [19] to determine the analytical and finite element (FE) solutions for stress distribution in the adhesive layer of a circular sandwich plate subjected to a uniformly distributed load. Results indicated that FEA findings give almost similar estimations on the planar stresses compared to analytical solutions based on TSDT and HSDT. However, the out-of-plane shear stresses predicted by HSDT were closer to FEA data.

Presented A refined trigonometric shear deformation theory (RTSDT) was used by Tounsi et al. [20] to take into account the transverse shear deformation effects on the thermos-elastic bending of functionally graded sandwich plates. Unlike any other theory, the number of unknown functions involved was only four, as against five in the case of other shear deformation theories. From numerical results, it was concluded that the proposed theory was accurate and simple in solving the thermos-elastic bending behavior of functionally graded plates. Mahmoudi et al. [21] indicated a theory for the thermo-mechanical analysis of functionally graded sandwich plates resting on a Pasternak elastic foundation. As a result, in contrast to similar studies, the number of unknowns and governing equations in their analysis was only four against six or more in other studies. Wenbin Zhou et al. [22] studied thermomechanical analysis in threads of porous metal–ceramic functionally graded composite joints by ABAQUS codes. Adelina Miteva et al. [23] reviewed some aerospace applications of functionally graded materials, and their paper is motivated by the huge interest in the rapidly developing field of material science, namely, functionally graded (or functionally gradient) materials (FGMs). In order to continue the work presented in [18], our research focuses on the effect of thermo-mechanical loading on the bending stresses developed in a five-layer sandwich plate with FG cover sheets, subjected to a uniformly distributed load applied to the top surface. The presented work
in [18], was focused on free vibration of Five Layers Composite Sandwich Plate but this research is focused on the thermo-mechanical analysis of FG sandwich plate and the effect of the mechanical load (uniform distributed load on the top face sheet) and thermal load (all layers are experiencing a steady temperature $\Delta T$) is studied. We assumed that the sandwich plate is resting on Winkler elastic foundation. One of the particle applications for the developed solution is in the body of automobile industry, body of ships, body of plane and the structures that are rested on the vibrated basement in the thermal environmental.

### 2. Problem Formulation

Figure 1 illustrates an FG sandwich plate subjected to a thermo-mechanical load and resting on Winkler elastic foundation. The face sheets have functional properties, and their exterior surfaces are of pure ceramic. Since the local coordinate in each layer is positioned at the corner of each constituent along the edges of the sandwich plate, then the variations in material properties of the face sheets are in the $z$-direction (thickness direction) $(z^{(k)})$, $k = 1, 5$, namely Young’s modulus $E$ and coefficient of thermal expansion $\alpha$, can be defined by Equation (1).

$$
M(z) = (M_c - M_m)V_c + M_m
$$

(1)

Where $M_m$ and $M_c$ are the corresponding material properties of the metal (aluminum (Al)) and the ceramic (Alumina (AL$_2$O$_3$)) phases, respectively. In Equation (1), $V_c$ is defined as the volume fraction of the ceramic phase within the face sheet. Equation (2) expresses the variation in this parameter along the non-dimensional thickness $(\frac{z^{(k)}}{h_k})$, as shown in Figure 1 for different values of power index $n$ [2]. Note that the volume fraction of the ceramic phase is highest at the free surfaces of the sandwich plate, and the metal phase is the highest at the cover sheet interfaces with the core.

$$
V_c = \left( \frac{1}{2} + \frac{z^{(k)}}{h_k} \right)^n \quad k = 1 \quad -h_1/2 \leq z^{(1)} \leq h_1/2
$$

$$
V_c = \left( \frac{1}{2} + \frac{z^{(k)}}{h_k} \right)^n \quad k = 5 \quad -h_5/2 \leq z^{(5)} \leq h_5/2
$$

(2)

**Figure 1.** Variation of volume fraction against the non-dimensional thickness [2].
The analysis was based on LT along with FSDT and the expansion of energy equation with the imposition of displacement continuity at the layer’s interfaces [24]. Assuming a continuous displacement across the layers, the displacement fields in each layer were obtained and presented in Appendix A.

Here, we assumed that \( u \) and \( v \) are the displacement components in the \( x \) and \( y \) directions at the core middle plane (\( z = 0 \)), respectively. Additionally, \( u^{(k)}, v^{(k)}, \) and \( w^{(k)} \) indicate the displacement components associated with the \( k \)th layer. For more information on the layer arrangement, the reader can refer to Figure 2. Furthermore, we assumed that the out-of-plane displacements, \( w^{(k)} \), for each layer were only a function of \( x \) and \( y \) directions. A perfect bond was assumed between any two neighboring layers at their interface.

Based on the linear elasticity and finite deformation, the strain components in the \( k \)th layer \((k = 1, 2, 3, 4, 5)\) are given by Equation (3) [24].

\[
\begin{bmatrix}
\varepsilon_{xx}^{(k)} \\
\varepsilon_{yy}^{(k)} \\
\varepsilon_{xy}^{(k)} \\
\gamma_{xz}^{(k)} \\
\gamma_{yz}^{(k)}
\end{bmatrix}
= 
\begin{bmatrix}
\frac{\partial u^{(k)}}{\partial x} \\
\frac{\partial v^{(k)}}{\partial y} \\
\frac{\partial u^{(k)}}{\partial y} + \frac{\partial v^{(k)}}{\partial x} \\
\frac{\partial u^{(k)}}{\partial z} + \frac{\partial w^{(k)}}{\partial x} \\
\frac{\partial v^{(k)}}{\partial z} + \frac{\partial w^{(k)}}{\partial y}
\end{bmatrix}
\]  

(3)

Substituting for displacement components from Appendix A in Equation (3), the strain vector in the \( k \)th layer \((k = 1, 2, 3, 4, 5)\) of the composite sandwich plate is:

\[
\begin{bmatrix}
\varepsilon_{xx}^{(k)} \\
\varepsilon_{yy}^{(k)} \\
\varepsilon_{xy}^{(k)} \\
\gamma_{xz}^{(k)} \\
\gamma_{yz}^{(k)}
\end{bmatrix}
= 
\begin{bmatrix}
p^{(k)} \\
0^{(k)} \\
0^{(k)} \\
\gamma_{xz}^{(k)} \\
\gamma_{yz}^{(k)}
\end{bmatrix}
+ \alpha^{(k)} 
\begin{bmatrix}
\varepsilon_{xx}^{(k)} \\
\varepsilon_{yy}^{(k)} \\
\varepsilon_{xy}^{(k)} \\
\gamma_{xz}^{(k)} \\
\gamma_{yz}^{(k)}
\end{bmatrix}
\]  

(4)

In Equation (4), \( \Delta T \) is the temperature change. The superscript “\( p \)” and “\( 0 \)” correspond to the total strains and middle-plane strains for the elastic and isotropic FGMs, respectively, and \( \varepsilon_{ij}^{f(k)} \) are the bending components. Neglecting \( \sigma_{zz}^{(k)} \) for each layer, the linear constitutive relations in the isotropic FGMs can be expressed as in Equation (5) [24].

\[
\begin{bmatrix}
\sigma_{xx}^{(k)} \\
\sigma_{yy}^{(k)} \\
\tau_{yz}^{(k)} \\
\tau_{xz}^{(k)} \\
\tau_{xy}^{(k)}
\end{bmatrix}
= 
\begin{bmatrix}
Q_{11}^{(k)} & Q_{12}^{(k)} & 0 & 0 & 0 \\
Q_{12}^{(k)} & Q_{22}^{(k)} & 0 & 0 & 0 \\
0 & 0 & Q_{44}^{(k)} & 0 & 0 \\
0 & 0 & 0 & Q_{55}^{(k)} & 0 \\
0 & 0 & 0 & 0 & Q_{66}^{(k)}
\end{bmatrix}
\begin{bmatrix}
\varepsilon_{xx}^{(k)} \\
\varepsilon_{yy}^{(k)} \\
\varepsilon_{xy}^{(k)} \\
\gamma_{xz}^{(k)} \\
\gamma_{yz}^{(k)}
\end{bmatrix}
\]  

(5)

where \((\sigma_{xx}^{(k)}, \sigma_{yy}^{(k)}, \tau_{yz}^{(k)}, \tau_{xz}^{(k)}, \tau_{xy}^{(k)})\) and \((\varepsilon_{xx}^{(k)}, \varepsilon_{yy}^{(k)}, \gamma_{xz}^{(k)}, \gamma_{yz}^{(k)}, \gamma_{xy}^{(k)})\) are the stress and strain components, respectively. Using the material properties defined in Equation (1), the stiffness coefficients \(Q_{ij}^{(k)}\) can be calculated easily (as in [24]).
Figure 2. Cont.
K was used for the shear correction factor where Meshed constitutive layer strains and transverse force resultants, and the elements of matrices A, B, and D, namely, the \( A_{ij}^{(k)} \), \( B_{ij}^{(k)} \), and \( D_{ij}^{(k)} \) (\( k = 1, 2, 3, 4, 5 \)), can be calculated as in [24]. According to [25], a value of 0.616 was used for the shear correction factor \( K \).

Figure 2. (a) The geometry of the functionally graded material (FGM) sandwich plate resting on an elastic foundation. (b) Simply supported boundary conditions are imposed on four edges. (c) Meshed model of the sandwiched plate showing the subdivisions in the FGM cover plates.

Note that due to the variation of the effective properties of the FG plate along the thickness direction (based on Equation (1)) the \( Q_{ij}^{(k)} \) elements will be a function of \( z \). Considering the static version of the principle of virtual work, the following expressions can be obtained as in Equation (6).

\[
\delta U = \int_\Omega \sum_{k=1}^{5} \int \frac{b}{2} \left[ \sigma_{xx}^{(k)} \delta \varepsilon_{xx}^{(k)} + \sigma_{yy}^{(k)} \delta \varepsilon_{yy}^{(k)} + \tau_{xy} \delta \gamma_{xy}^{(k)} + \tau_{yz} \delta \gamma_{yz}^{(k)} \right] d\Omega d\zeta + \int_\Omega (f_e - q) d\Omega = 0, \quad k = 1, 2, 3, 4, 5
\]

where \( \Omega \) and \( \delta U \) are the material volume, and virtual strain energy, respectively; \( q \) is the distributed transverse load and \( f_e \) is the density of reaction force of the foundation. For the Winkler foundation model, we have Equation (7):

\[
f_e = k_\omega \omega
\]
On using Equation (6), one can show that the equilibrium equations for the kth layer are:

\[
\begin{align*}
\delta u : & \sum_{k=1}^{5} \left( \frac{\partial N_{y}^{(k)}}{\partial x} - \frac{\partial N_{x}^{(k)}}{\partial y} \right) = f_{xx}^{(k)} \\
\delta v : & \sum_{k=1}^{5} \left( \frac{\partial N_{y}^{(k)}}{\partial y} - \frac{\partial N_{x}^{(k)}}{\partial x} \right) = f_{yy}^{(k)} \\
\delta w : & \sum_{k=1}^{5} \left( -\frac{\partial Q_{y}^{(k)}}{\partial x} + \frac{\partial Q_{y}^{(k)}}{\partial y} \right) + q + k_{w}w = 0 \\
\delta \omega_{x}^{(1)} : & \frac{h_{1}}{2} \frac{\partial N_{y}^{(1)}}{\partial x} + \frac{h_{1}}{2} \frac{\partial N_{y}^{(1)}}{\partial y} - \frac{\partial M_{y}^{(1)}}{\partial x} - \frac{\partial M_{y}^{(1)}}{\partial y} + Q_{x}^{(1)} = f_{x}^{(1)} \\
\delta \omega_{y}^{(1)} : & \frac{h_{1}}{2} \frac{\partial N_{y}^{(1)}}{\partial x} + \frac{h_{1}}{2} \frac{\partial N_{y}^{(1)}}{\partial y} - \frac{\partial M_{y}^{(1)}}{\partial x} - \frac{\partial M_{y}^{(1)}}{\partial y} + Q_{y}^{(1)} = f_{y}^{(1)} \\
\delta \omega_{x}^{(2)} : & \frac{h_{2}}{2} \frac{\partial N_{y}^{(2)}}{\partial x} + \frac{h_{2}}{2} \frac{\partial N_{y}^{(2)}}{\partial y} + h_{2} \frac{\partial N_{y}^{(2)}}{\partial x} + h_{2} \frac{\partial N_{y}^{(2)}}{\partial y} - \frac{\partial M_{y}^{(2)}}{\partial x} - \frac{\partial M_{y}^{(2)}}{\partial y} + Q_{x}^{(2)} = f_{x}^{(2)} \\
\delta \omega_{y}^{(2)} : & \frac{h_{2}}{2} \frac{\partial N_{y}^{(2)}}{\partial x} + \frac{h_{2}}{2} \frac{\partial N_{y}^{(2)}}{\partial y} + h_{2} \frac{\partial N_{y}^{(2)}}{\partial x} + h_{2} \frac{\partial N_{y}^{(2)}}{\partial y} - \frac{\partial M_{y}^{(2)}}{\partial x} - \frac{\partial M_{y}^{(2)}}{\partial y} + Q_{y}^{(2)} = f_{y}^{(2)} \\
\delta \omega_{x}^{(3)} : & -h_{3} \frac{\partial N_{y}^{(3)}}{\partial x} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial y} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial x} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial y} - \frac{\partial M_{y}^{(3)}}{\partial x} - \frac{\partial M_{y}^{(3)}}{\partial y} + Q_{x}^{(3)} = f_{x}^{(3)} \\
\delta \omega_{y}^{(3)} : & -h_{3} \frac{\partial N_{y}^{(3)}}{\partial x} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial y} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial x} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial y} - \frac{\partial M_{y}^{(3)}}{\partial x} - \frac{\partial M_{y}^{(3)}}{\partial y} + Q_{y}^{(3)} = f_{y}^{(3)} \\
\delta \omega_{x}^{(4)} : & -h_{4} \frac{\partial N_{y}^{(4)}}{\partial x} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial y} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial x} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial y} - \frac{\partial M_{y}^{(4)}}{\partial x} - \frac{\partial M_{y}^{(4)}}{\partial y} + Q_{x}^{(4)} = f_{x}^{(4)} \\
\delta \omega_{y}^{(4)} : & -h_{4} \frac{\partial N_{y}^{(4)}}{\partial x} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial y} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial x} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial y} - \frac{\partial M_{y}^{(4)}}{\partial x} - \frac{\partial M_{y}^{(4)}}{\partial y} + Q_{y}^{(4)} = f_{y}^{(4)} \\
\delta \omega_{x}^{(5)} : & -h_{5} \frac{\partial N_{y}^{(5)}}{\partial x} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial y} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial x} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial y} - \frac{\partial M_{y}^{(5)}}{\partial x} - \frac{\partial M_{y}^{(5)}}{\partial y} + Q_{x}^{(5)} = f_{x}^{(5)} \\
\delta \omega_{y}^{(5)} : & -h_{5} \frac{\partial N_{y}^{(5)}}{\partial x} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial y} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial x} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial y} - \frac{\partial M_{y}^{(5)}}{\partial x} - \frac{\partial M_{y}^{(5)}}{\partial y} + Q_{y}^{(5)} = f_{y}^{(5)}
\end{align*}
\]

where

\[
\begin{align*}
f_{xx}^{(k)} & = \sum_{k=1}^{5} \left( \frac{\partial N_{y}^{(k)}}{\partial x} \right) \\
f_{yy}^{(k)} & = \sum_{k=1}^{5} \left( \frac{\partial N_{y}^{(k)}}{\partial y} \right) \\
f_{x}^{(1)} & = \frac{h_{1}}{2} \frac{\partial N_{y}^{(1)}}{\partial x} - \frac{h_{1}}{2} \frac{\partial M_{y}^{(1)}}{\partial x} \\
f_{y}^{(1)} & = \frac{h_{1}}{2} \frac{\partial N_{y}^{(1)}}{\partial y} - \frac{h_{1}}{2} \frac{\partial M_{y}^{(1)}}{\partial y} \\
f_{x}^{(2)} & = \frac{h_{2}}{2} \frac{\partial N_{y}^{(2)}}{\partial x} + h_{2} \frac{\partial N_{y}^{(2)}}{\partial x} - \frac{\partial M_{y}^{(2)}}{\partial x} \\
f_{y}^{(2)} & = \frac{h_{2}}{2} \frac{\partial N_{y}^{(2)}}{\partial y} + h_{2} \frac{\partial N_{y}^{(2)}}{\partial y} - \frac{\partial M_{y}^{(2)}}{\partial y} \\
f_{x}^{(3)} & = \frac{h_{3}}{2} \frac{\partial N_{y}^{(3)}}{\partial x} + h_{3} \frac{\partial N_{y}^{(3)}}{\partial x} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial x} - \frac{\partial M_{y}^{(3)}}{\partial x} \\
f_{y}^{(3)} & = \frac{h_{3}}{2} \frac{\partial N_{y}^{(3)}}{\partial y} + h_{3} \frac{\partial N_{y}^{(3)}}{\partial y} - h_{3} \frac{\partial N_{y}^{(3)}}{\partial y} - \frac{\partial M_{y}^{(3)}}{\partial y} \\
f_{x}^{(4)} & = \frac{h_{4}}{2} \frac{\partial N_{y}^{(4)}}{\partial x} + h_{4} \frac{\partial N_{y}^{(4)}}{\partial x} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial x} - \frac{\partial M_{y}^{(4)}}{\partial x} \\
f_{y}^{(4)} & = \frac{h_{4}}{2} \frac{\partial N_{y}^{(4)}}{\partial y} + h_{4} \frac{\partial N_{y}^{(4)}}{\partial y} - h_{4} \frac{\partial N_{y}^{(4)}}{\partial y} - \frac{\partial M_{y}^{(4)}}{\partial y} \\
f_{x}^{(5)} & = \frac{h_{5}}{2} \frac{\partial N_{y}^{(5)}}{\partial x} + h_{5} \frac{\partial N_{y}^{(5)}}{\partial x} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial x} - \frac{\partial M_{y}^{(5)}}{\partial x} \\
f_{y}^{(5)} & = \frac{h_{5}}{2} \frac{\partial N_{y}^{(5)}}{\partial y} + h_{5} \frac{\partial N_{y}^{(5)}}{\partial y} - h_{5} \frac{\partial N_{y}^{(5)}}{\partial y} - \frac{\partial M_{y}^{(5)}}{\partial y}
\end{align*}
\]
The displacement components and curvatures are defined in Equation (11). In this equation, \( u_{mn} \), \( v_{mn} \), \( w_{mn} \), \( \varphi_{x_{mn}}^{(k)} \), and \( \varphi_{y_{mn}}^{(k)} \) are the Fourier series constants that can be easily determined.

\[
\begin{aligned}
    u &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} u_{mn} \cos(\alpha x) \sin(\beta y) \\
v &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} v_{mn} \sin(\alpha x) \cos(\beta y) \\
w &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} w_{mn} \sin(\alpha x) \sin(\beta y) \\
\varphi_{x_{mn}}^{(k)} &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \varphi_{x_{mn}}^{(k)} \cos(\alpha x) \sin(\beta y) \\
\varphi_{y_{mn}}^{(k)} &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \varphi_{y_{mn}}^{(k)} \sin(\alpha x) \cos(\beta y)
\end{aligned}
\]  

In Equation (11), \( \alpha = \frac{m \pi}{a} \) \( m = 1, 2, \ldots \) and \( \beta = \frac{n \pi}{b} \) \( n = 1, 2, \ldots \). The transvers load and thermal moments are also expanded in double sine series. For this purpose, \( q(x,y) \) is expanded as in Equation (12).

\[
q = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} B_{mn} \sin(\alpha x) \sin(\beta y) \quad \text{where,} \quad B_{mn} = \begin{cases} 
\frac{16q}{mn\pi^2} & \text{odd } m, n \\
0 & \text{even } m \text{ or } n
\end{cases}
\]  

The temperature increment is also expanded as in [24] such that:

\[
\Delta T(x,y,z) = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} T_{mn} \sin(\alpha x) \sin(\beta y) \\
T_{mn} = \begin{cases} 
\frac{16T}{mn\pi^2} & \text{odd } m, n \\
0 & \text{even } m \text{ or } n
\end{cases}
\]  

Additionally, one can write:

\[
\begin{aligned}
N_{xx}^{(k)} &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} N_{xx_{mn}}^{(k)} \sin(\alpha x) \sin(\beta y) \\
N_{xx_{mn}}^{(k)} &= \int_{-\frac{a}{2}}^{\frac{a}{2}} E(z)^{(k)} \frac{1}{1-\nu(z)^{(k)}} \alpha(z)^{(k)} T_{mn} dz_{(k)} \\
M_{xx}^{(k)} &= \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} M_{xx_{mn}}^{(k)} \sin(\alpha x) \sin(\beta y) \\
M_{xx_{mn}}^{(k)} &= \int_{-\frac{a}{2}}^{\frac{a}{2}} E(z)^{(k)} \frac{1}{1-\nu(z)^{(k)}} \alpha(z)^{(k)} T_{mn} z_{(k)} dz_{(k)}
\end{aligned}
\]

3. Numerical Results and Discussions

3.1. Three-Layers Sandwich Plate

For validation of the proposed model in the first step, we verify the formulation and FE modeling. For this reason, we studied the layerwise theory for a three layers sandwich plate (simply supported square with a layer sequence of \([0/90/0]\)) under a uniform distributed transverse load using the analytical solution in Ref. [26]. The proposed layer-wise model was compared with those based on 3D FE modeling in ABAQUS software, and close agreements between the results indicate the validity of the present formulation. In the next step, stress distributions in a five-layer sandwich plate with FG face sheets subject to thermo-mechanical load and resting on Winkler elastic foundation are explored. Results of LT theory are compared with those of FE finding using ABAQUS.
final results. Reference [27] presents a complete solution to this problem where the material properties of the core and the face sheets are expressed in Equation (15).

\[
Q_{\text{core}} = \begin{bmatrix}
0.999781 & 0.231192 & 0 & 0 & 0 \\
0.231192 & 0.52486 & 0 & 0 & 0 \\
0 & 0 & 0.62931 & 0 & 0 \\
0 & 0 & 0 & 0.266810 & 0 \\
0 & 0 & 0 & 0 & 0.159914
\end{bmatrix}
\] (15)

Additionally, skins material properties were related to core properties by a factor \( R \) as follows [27]:

\[
R = \frac{Q_{\text{skin}}}{Q_{\text{core}}}
\] (16)

Furthermore, the transverse displacements and stresses were normalized according to the following relations [27]:

\[
\begin{align*}
\sigma^1 & = \left( \frac{2}{h_2} \right) \frac{2.0097}{h} w \\
\sigma^2 & = \left( \frac{2}{h_2} \right) \frac{2.0097}{h} x \\
\sigma^3 & = \left( \frac{2}{h_2} \right) \frac{2.0097}{h} y \\
\tau_{xy} & = \left( \frac{2}{h_2} \right) \frac{2.0097}{h} w
\end{align*}
\] (17)

The findings on transverse displacements, normal stresses, and shear stresses are presented in Table 1. These results reveal that FE modeling in ABAQUS software predicts the values of normalized displacement (\( w \)), and normalized stress components \( \sigma_x \), \( \sigma_y \), and \( \tau_{xy} \) with good accuracy compared to those in [26,27].

| \( h_1/h = 0.1 \), \( h_2/h = 0.8 \), \( h_3/h = 0.1 \), \( a/b = 1 \), \( a/h = 10 \). | \( R \) Method | \(-1\) | \(-2\) | \(-3\) | \(-1\) | \(-2\) | \(-3\) |
|---|---|---|---|---|---|---|
| FE | 250.8 | 57.26 | 45 | 8.56 | 36.45 | 28.97 | 5.5 | 3.346 |
| %Difference | 3.2 | 5.1 | 3.5 | 8.4 | 5.3 | 3.7 | 10.8 | 2.4 |

3.2. Five-Layer FGM Sandwich Plate

Now consider a five-layer square FGM sandwich plate, composed of a core and two adhesive layers bonding the core to the two face sheets, resting on the Winkler foundation, as shown in Figure 2. The simply supported plate was assumed symmetry concerning its middle layer, and its top surface was exposed to a uniformly distributed transverse load \( q \) and a steady temperature load \( T \). Each face sheet was composed of \( (\text{AL} - \text{AL}_2\text{O}_3) \), with aluminum (Al) as the metal phase and Alumina (\( \text{AL}_2\text{O}_3 \)) as the ceramic phase. The vinyl ester (VE) based structural adhesive was used to bond the face sheets to an elastomeric core (Ellastollan R3000).

In the study performed in [28], the behavior of vinyl-ester polymer at strain rates 0.001/s and a wide range of temperatures (from room temperature (RT) to 100 °C) was investigated. Table 2 shows the results of this study over modules of elasticity for this adhesive. It is worth mentioning that the selected 100 °C is close to the glass transition temperature \( T_g \) of vinyl-ester. However, although for temperatures close to \( T_g \) and high strains, visco-plasticity behavior dominates the material properties yet, in the present
study, its effect on deformation was not considered in the standard linear solid model for the material.

Table 2. Modules of vinyl-ester at different temperatures [28].

<table>
<thead>
<tr>
<th>Elastic Modulus of Vinyl Ester (GPa)</th>
<th>Temperature (°C)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.4</td>
<td>RT</td>
</tr>
<tr>
<td>3.13</td>
<td>50</td>
</tr>
<tr>
<td>2.8</td>
<td>75</td>
</tr>
<tr>
<td>2.5</td>
<td>100</td>
</tr>
</tbody>
</table>

Additionally, Table 3 presents the modulus of elasticity of the Elastollan-R3000 core at four different temperatures (RT to 100 C) [29]. Other mechanical properties of the five-layer sandwich plate used in this simulation are given in Table 4.

Table 3. Modules of elasticity of Elastollan-R3000 at different temperatures [29].

<table>
<thead>
<tr>
<th>Elastic Modulus of Elastollan-R3000 $E_{core}$ (GPa)</th>
<th>Temperature (°C)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.8</td>
<td>RT</td>
</tr>
<tr>
<td>1.94</td>
<td>50</td>
</tr>
<tr>
<td>1.75</td>
<td>75</td>
</tr>
<tr>
<td>1.52</td>
<td>100</td>
</tr>
</tbody>
</table>

Table 4. The mechanical properties of the five-layer sandwich plate.

<table>
<thead>
<tr>
<th>Constituent</th>
<th>Mechanical Properties</th>
</tr>
</thead>
<tbody>
<tr>
<td>(Elastollan-R3000) core [29]</td>
<td>$v = 0.45$, $\alpha = 20 \times 10^{-6}$ °C$^{-1}$</td>
</tr>
<tr>
<td>Face sheet (Al – Al$_2$O$_3$) [30]</td>
<td>$E_m = 70$ GPa, $E_C = 380$ GPa, $\nu_C = \nu_m = 0.3$</td>
</tr>
<tr>
<td>Aluminum (Al) as metal and Alumina (Al$_2$ – O$_3$) as ceramic</td>
<td>$\alpha_m = 23.6 \times 10^{-6}$ °C$^{-1}$</td>
</tr>
<tr>
<td>Vinyl ester [31,32]</td>
<td>$\alpha_c = 6.6 \times 10^{-6}$ °C$^{-1}$</td>
</tr>
<tr>
<td></td>
<td>$\nu = 0.375$, $\alpha = 50.8 \times 10^{-6}$ °C$^{-1}$</td>
</tr>
</tbody>
</table>

In order to obtain the results on deflections and stress components, different points were selected at different locations in the sandwich plate, as shown in Figure 3. The location of these points is expressed in Table 5.

Table 5. The geometric positions for 8 points are defined in tables according to the coordinate system shown in Figure 3.

<table>
<thead>
<tr>
<th>Points Number</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Location</td>
<td>Core</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$x$</td>
<td>a/2</td>
<td>a/2</td>
<td>a/2</td>
<td>a/2</td>
<td>a/2</td>
<td>a</td>
<td>a</td>
<td></td>
</tr>
<tr>
<td>$y$</td>
<td>b/2</td>
<td>b/2</td>
<td>b/2</td>
<td>b/2</td>
<td>b/2</td>
<td>b/2</td>
<td>b/2</td>
<td></td>
</tr>
<tr>
<td>$z$</td>
<td>0</td>
<td>$-h_5/2$</td>
<td>$h_4/2$</td>
<td>$-h_4/2$</td>
<td>$h_3/2$</td>
<td>$-h_1/2$</td>
<td>$-h_4/2$</td>
<td>$h_3/2$</td>
</tr>
</tbody>
</table>

For the sake of simplicity and reducing the numerical simulation using the ABAQUS software, due to symmetry, the whole FE model was reduced to one-fourth of its original size. The three-dimensional solid element C3D20R was used for meshing. The simply supported boundary conditions were imposed on the two side edges, while the symmetry conditions were imposed on the remaining two edges. Furthermore, to properly model the FGM face sheets and implement the properties of FG material, the thickness of each face sheet was divided into 30 thin layers with different properties defined according to Equation (1). The whole plate was subjected to thermo-mechanical loading (uniform
mechanical load $q$ on its top surface and steady temperature $\Delta T$ in all layers) and resting on Winkler elastic foundation.

![Diagram](image.png)

**Figure 3.** The geometric position of different points selected in the postulated model.

In order to obtain the finite element results, several models were prepared and run based on different mesh qualities until the results converged to specific values given in Tables 6–11 and Figures 4–9. The geometric positions for all points used in these tables are given in Table 5 and Figure 3.
Table 6. Comparison of the results based on LT and those of FE findings for different temperature.

<table>
<thead>
<tr>
<th>$T$ °C</th>
<th>Method</th>
<th>$w \times 10^{-4}$ (m)</th>
<th>$\sigma_z$ (Mpa)</th>
<th>$\tau_{xz}$ (Mpa)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Point 1</td>
<td>Point 2</td>
<td>Point 3</td>
<td>Point 4</td>
</tr>
<tr>
<td>23</td>
<td>FE</td>
<td>−1.220</td>
<td>−6.51</td>
<td>−0.3838</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−1.278</td>
<td>−5.023</td>
<td>−0.2732</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>4.8</td>
<td>22.8</td>
<td>28.8</td>
</tr>
<tr>
<td>50</td>
<td>FE</td>
<td>−1.3865</td>
<td>−46.897</td>
<td>−6.807</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−1.5159</td>
<td>−45.125</td>
<td>−5.930</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>9.3</td>
<td>5.1</td>
<td>12.9</td>
</tr>
<tr>
<td>75</td>
<td>FE</td>
<td>−1.4460</td>
<td>−83.720</td>
<td>−11.483</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−1.602</td>
<td>−82.50</td>
<td>−10.018</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>10.8</td>
<td>1.5</td>
<td>12.7</td>
</tr>
<tr>
<td>100</td>
<td>FE</td>
<td>−1.538</td>
<td>−119.45</td>
<td>−15.01</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−1.7322</td>
<td>−120</td>
<td>−13.159</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>12.6</td>
<td>0.5</td>
<td>12.3</td>
</tr>
</tbody>
</table>

Table 7. Comparison of the results based on LT and those of FE findings.

<table>
<thead>
<tr>
<th>$K_w$ (N/m²)</th>
<th>Method</th>
<th>$w \times 10^{-4}$ (m)</th>
<th>$\sigma_z$ (Mpa)</th>
<th>$\tau_{xz}$ (Mpa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Point 1</td>
<td>Point 2</td>
<td>Point 3</td>
<td>Point 4</td>
</tr>
<tr>
<td>%Difference</td>
<td>9.4</td>
<td>11.6</td>
<td>16.3</td>
<td>13.5</td>
</tr>
<tr>
<td>$10^8$</td>
<td>FE</td>
<td>−6.329</td>
<td>−70.06</td>
<td>−8.108</td>
</tr>
<tr>
<td>%Difference</td>
<td>8.2</td>
<td>11.2</td>
<td>16.1</td>
<td>13.5</td>
</tr>
<tr>
<td>$10^9$</td>
<td>FE</td>
<td>−3.505</td>
<td>−56.842</td>
<td>−7.489</td>
</tr>
<tr>
<td>%Difference</td>
<td>2.4</td>
<td>8.1</td>
<td>17</td>
<td>13.1</td>
</tr>
</tbody>
</table>

Table 8. Comparison of the result based on LT and those FE findings.

| $\alpha$ = 1, $\beta$ = 20, $h_1/T = 0.1$, $h_2 = 0.02$, $h_3/T = 0.76$, $h = 12$ mm, $q = 500$ KPa, $k_w = 0$, $T = 50$ °C |
|-----------------|-----------------|-----------------|-----------------|
| $n$ | Method | $w \times 10^{-4}$ (m) | $\sigma_z$ (Mpa) | $\tau_{xz}$ (Mpa) |
| Point 1 | Point 2 | Point 3 | Point 4 | Point 5 | Point 6 | Point 7 | Point 8 |
| FE | −6.239 | −88.545 | −8.185 | −7.831 | −3.439 | 233.27 | −3.853 | −3.923 |
| %Difference | 12.4 | 28.6 | 16.5 | 13.5 | 46.6 | 22.5 | 16.6 | 18.1 |
| 1 | FE | −6.930 | −72.936 | −8.239 | −7.878 | −3.466 | 286.13 | −4.191 | −4.243 |
| %Difference | 9.4 | 11.6 | 16.3 | 15.6 | 46.1 | 19.9 | 14.6 | 15.6 |
| 2 | FE | −8.057 | −73.345 | −8.418 | −8.048 | −3.554 | 357.55 | −4.469 | −4.510 |
| LW | −8.536 | −68.337 | −7.091 | −6.99 | −1.991 | 299.2 | −3.97 | −3.97 |
| %Difference | 5.9 | 6.8 | 15.7 | 13.1 | 44 | 16.3 | 11.2 | 10 |
Table 9. Comparison of the result based on LT and those FE findings.

\[ n = 1, \frac{a}{h} = 1, b_i = 0.1, \frac{h_i}{h} = 0.02, \frac{b_j}{h} = 0.76, h = 12 \text{ mm}, q = 100 \text{ kPa}, k_{\text{w}} = 0. \]

<table>
<thead>
<tr>
<th>( \frac{a}{h} )</th>
<th>Method</th>
<th>( w \times 10^{-4} ) (m)</th>
<th>( \sigma_x ) (Mpa)</th>
<th>( \tau_{xz} ) (Mpa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>FE</td>
<td>−0.19316</td>
<td>−11.398</td>
<td>−10.272</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−0.26121</td>
<td>−8.938</td>
<td>−9.845</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>35.2</td>
<td>13.7</td>
<td>4.2</td>
</tr>
<tr>
<td>20</td>
<td>FE</td>
<td>−1.4460</td>
<td>−11.483</td>
<td>−11</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−1.602</td>
<td>−9.018</td>
<td>−10.013</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>10.8</td>
<td>1.5</td>
<td>12.7</td>
</tr>
<tr>
<td>30</td>
<td>FE</td>
<td>−5.601</td>
<td>−11.677</td>
<td>−11.325</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−5.566</td>
<td>−10.327</td>
<td>−10.302</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>1.1</td>
<td>5.7</td>
<td>11.6</td>
</tr>
</tbody>
</table>

Table 10. Comparison of the result based on LT and those FE findings.

\[ n = 1, \frac{a}{h} = 1, q = 100 \text{ kPa}, k = 0.616, T = 75 \text{ °C}, \frac{h_i}{h} = 0.76, b_j = 0.02. \]

<table>
<thead>
<tr>
<th>( h_i ) ( h ) (mm)</th>
<th>Method</th>
<th>( w \times 10^{-4} ) (m)</th>
<th>( \sigma_x ) (Mpa)</th>
<th>( \tau_{xz} ) (Mpa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1 12</td>
<td>FE</td>
<td>−1.446</td>
<td>−11.483</td>
<td>−11</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−1.602</td>
<td>−9.018</td>
<td>−10.013</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>10.8</td>
<td>1.5</td>
<td>12.7</td>
</tr>
<tr>
<td>0.15 13.2</td>
<td>FE</td>
<td>−1.010</td>
<td>−9.297</td>
<td>−9.926</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>17.3</td>
<td>6.8</td>
<td>14.4</td>
</tr>
<tr>
<td>0.2 14.2</td>
<td>FE</td>
<td>−0.77110</td>
<td>−9.488</td>
<td>−9.884</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−0.9424</td>
<td>−7.498</td>
<td>−7.882</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>22.2</td>
<td>13.9</td>
<td>15.4</td>
</tr>
</tbody>
</table>

Table 11. Comparison of the result based on LT and those FE findings.

\[ n = 1, \frac{a}{h} = 1, q = 500 \text{ kPa}, k = 0.616, T = 50 \text{ °C}, \frac{h_i}{h} = 0.76, b_j = 0.02. \]

<table>
<thead>
<tr>
<th>( h_i ) ( h ) (mm)</th>
<th>Method</th>
<th>( w \times 10^{-4} ) (m)</th>
<th>( \sigma_x ) (Mpa)</th>
<th>( \tau_{xz} ) (Mpa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1 12</td>
<td>FE</td>
<td>−6.930</td>
<td>−7.878</td>
<td>−3.466</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−7.580</td>
<td>−6.817</td>
<td>−1.609</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>9.4</td>
<td>11.6</td>
<td>16.3</td>
</tr>
<tr>
<td>0.15 13.2</td>
<td>FE</td>
<td>−4.804</td>
<td>−7.318</td>
<td>−3.247</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−5.554</td>
<td>−6.236</td>
<td>−1.459</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>15.6</td>
<td>5.8</td>
<td>18.2</td>
</tr>
<tr>
<td>0.2 14.4</td>
<td>FE</td>
<td>−3.650</td>
<td>−7.047</td>
<td>−3.173</td>
</tr>
<tr>
<td></td>
<td>LW</td>
<td>−4.395</td>
<td>−5.944</td>
<td>−1.254</td>
</tr>
<tr>
<td></td>
<td>%Difference</td>
<td>20.4</td>
<td>0.5</td>
<td>19.3</td>
</tr>
</tbody>
</table>
Figure 4. Effect of the thermal loads on the center deflection of the sandwich (for point 1) plate.

Figure 5. Effect of the thermal loads on the maximum normal stresses of sandwich plate (for point 6).
Figure 5. Effect of the thermal loads on the maximum normal stresses of sandwich plate (for point 6).

Figure 6. Effect of the thermal loads on the transverse shear stress of sandwich plate (for point 8).

Figure 7. Effect of the elastic foundation on the center deflection of sandwich plate.

Figure 8. Effect of the elastic foundation on the maximum normal stresses (point 6) of sandwich plate.

\[ n = 1, \frac{a}{h} = 20, \frac{h_1}{h} = 0.1, \frac{h_2}{h} = 0.02, \frac{h_3}{h} = 0.76, h = 12 \text{ mm}, q = 100 \text{ KPa}, k_w = 0. \]

\[ n = 1, \frac{a}{h} = 20, \frac{h_1}{h} = 0.1, \frac{h_2}{h} = 0.02, \frac{h_3}{h} = 0.76, h = 12 \text{ mm}, q = 100 \text{ KPa}, T = 75 \text{ °C}. \]
Figure 8. Effect of the elastic foundation on the maximum normal stresses (point 6) of sandwich plate.

\[ n = 1, \frac{a}{h} = 20, \frac{h_1}{h} = 0.1, \frac{h_2}{h} = 0.02, \frac{h_3}{h} = 0.76, h = 12 \text{ mm}, q = 100 \text{ KPa}, T = 50^\circ \text{C}. \]

Figure 9. Effect of the variation of \( a/h \) on the center deflection of sandwich plate.

\[ n = 1, \frac{a}{h} = 20, \frac{h_1}{h} = 0.1, \frac{h_2}{h} = 0.02, \frac{h_3}{h} = 0.76, h = 12 \text{ mm}, q = 100 \text{ KPa}, T = 75^\circ \text{C}, k_w = 0. \]
3.3. Numerical Results and Discussions

Now, numerical findings of the analysis of a five-layer FGM sandwich plate subjected to thermo-mechanical load are presented. In order to carry out the accuracy of the general approach that was outlined in the previous sections, the results of LT theory in MATLAB software were compared with those of three-dimensional finite element analysis using the ABAQUS software program. The dimension of the total thickness of the sandwich plate is 12 mm and \( h_1 = 0.1, h_2 = 0.02, h_3 = 0.76, h_4 = 1.2 \) mm \((-0.6 \text{ mm} \leq z_1, z_5 \leq 0.6 \text{ mm})\), \( h_2, h_4 = 0.24 \text{ mm} \((-0.12 \text{ mm} \leq z_2, z_4 \leq 0.12 \text{ mm})\), \( h_3 = 9.12 \text{ mm}\).

In Table 6, the effect of a distributed load of 100 KPa on the top surface, as well as the increase in temperature of 23 °C, 50 °C, 75 °C, and 100 °C, were investigated on the induced deflections and stresses in the absence of the elastic foundation. As expected, the results in this table show that increasing the temperature increases the normal stresses \( (\sigma_x) \), shear stresses \( (\tau_{xz}) \), and the transverse displacements \( (w) \). Due to a decline in the elastic moduli of the adhesive layer and the core concerning higher temperatures, the overall stiffness of the FG sandwich plate drops, and hence an increase in the transverse displacements of the sandwich plate is observed. According to these results, the maximum stress occurs at the middle and lower points of the bottom face sheet (point 6). The reason for this behavior is that the distributed and the thermal loads both create tensile stresses that add up at point 6.

Table 7 demonstrates the influence of the Winkler elastic foundation from points one to point eight. As expected, results show that the Winkler elastic foundation parameter reduces the center transverse displacements, as well as the maximum normal and shear stresses.

The results in Tables 8–10 show the effect of any variation in the plate dimensions as well as any change in the material parameter \( n \) on the center transverse displacement \( (w) \), normal stress, and shear stress for points one to eight.

The effects of the power-law index on maximum normal stresses, transverse displacement, and shear stress for sandwich plates subjected to thermo-mechanical loads, are presented in Table 8. These results indicate that increasing the value of the power-law index \( (n) \) increases the stress component \( \sigma_x \) as well as the transverse displacement \( w \). This behavior is expected because the sandwich plate with more metal phase \( (n > 1) \) experiences higher deflections and hence higher flexural stress \( \sigma_x \).

Results in Table 9 indicate that any increase in the \( a/h \) ratio reduces the differences between finite element findings and those of the current solution (for points one to six), which are based on LT and FSDT. This can be interpreted as for thinner sandwich composite plates, the LT in conjunction with FSDT is more applicable compared to thicker plates.

In order to seek the thickness effect of face sheets on the behavior of the square sandwich plate, the core thickness, as well as the adhesive layers, were considered to be fixed while the thickness of the face sheets was increased. According to the results in Table 10, increasing the thickness of the FGM cover sheets causes high differences in the results for \( \sigma_x \) and the in-plane shear stress \( \tau_{xy} \) at some critical locations (points). This difference is higher for the in-plane shear stress for a thicker composite sheet. Results indicate that LT does seem to be able to predict good results for these stresses at the selected critical points in thick composite sheets in the presence of the adhesive layer.

In addition, according to Table 11, with the increase in load and a decrease in temperature, the results of the first-order shear theory have better agreement with the results of the finite element method. However, at high temperatures, using FSDT, the results obtained based on LT do not seem to be reliable.

Figures 4–6 show a comparison between finite element results and those of semi-analytical solution based on LT for variations in the center deflection (point 1), the maximum normal stresses (at point 6), and the transverse shear stress (at point 8), respectively in the sandwich plate under thermo-mechanical loading for different values of the temperatures. As observed, the layerwise theory predicts more accurate results on \( w \) and \( \sigma_x \) at lower temperatures. However, for the out-of-plane \( \tau_{xz} \), this is not the case.
In Figures 7 and 8, the effects of elastic foundation on the maximum center deflection and the normal stresses are shown for a square sandwich plate under thermo-mechanical loads, respectively. These results are generated at a temperature of 75 °C. Results indicate that the center displacements and maximum normal stresses decline gradually with a rise in the value of foundation stiffness. The percentage difference between the finite element results and those of the LT diminishes with an increase in the foundation stiffness.

However, the results in Figure 9 indicate that the percentage difference in the center deflection between the results of both methods in the absence of foundation stiffness is almost zero for thin plates (as the span ratio $a/h$ increases). This indicates that the LT, in conjunction with FSDT, has better applicability in thinner composite five-layer sandwich plates.

4. Conclusions

In this work, LT, along with FSDT, was used to study the stress distribution in a five-layer sandwich composite plate subjected to a thermo-mechanical load. Results showed that the first-order shear layer theory, in conjunction with LT, gives relatively good results on a maximum transverse deflection in the five-layer sandwich plate. Moreover, for a composite sandwich plate with mechanical load, in the absence of thermal load, results of the first-order shear layer theory obtained by using the Navire method are relatively good in comparison to the normal stresses obtained for points two to six, which are obtained by finite element. Further results showed that the first-order shear deformation theory, in combination with LT, is not well suited for the determination of in-plane and out-of-plane shear stresses $\tau_{xy}$ and $\tau_{xz}$ as well as the normal flexural stresses $\sigma_z$ in the presence of thermo-mechanical loads. It was also observed that with increasing the temperature, the difference between the finite element and LT also increases. However, the LT, in conjunction with FSDT, had better applicability in predicting flexural, and shear stresses in thinner five-layer sandwich composite plates.

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Nomenclature

- $a$: Width of the plate
- $A_{ij}^{(k)}, B_{ij}^{(k)}, D_{ij}^{(k)}$: elements of matrices for the $k$th layer
- $b$: Length of the plate
- $E_M, E_c$: Elastic modules of the metal and ceramic phases, respectively.
- $f_r$: Density of foundation reaction force
- $G$: Shear Modulus
- $h$: Total thickness of the sandwich plate
- $h_1$: Cover sheet thickness
- $h_2$: Adhesive thickness
- $h_3$: Core thickness
Layer number

\( k_{wy} \)  
elastic foundation stiffness

\( M_{ij}^{(k)} \)  
Moment resultants for the \( k \)th layer

\( N_{ij}^{(k)} \)  
Force resultants for the \( k \)th layer

\( n \)  
Power law index

\( M_c \)  
Material properties of the ceramic phase

\( M_m \)  
Material properties of the metal phase

\( q \)  
Uniform distributed load

\( Q_{ij}^{(k)} \)  
The elements of the stiffness matrix

\( Q_{core} \)  
stiffness of core

\( Q_{skin} \)  
stiffness of skin

\( Q_{xx}^{(k)}, Q_{yy}^{(k)} \)  
Transverse shear stress results for the \( k \)th layer

\( R \)  
Ratio stiffness of skin to stiffness of the core

\( T \)  
Surrounding temperature

\( U \)  
Strain energy

\( U_f \)  
Strain energy of the foundation

\( \delta U \)  
Virtual strain energy

\( v \)  
Displacement component in the \( y \) direction

\( V_c \)  
Volume fraction of the ceramic phase within the face sheet

\( w \)  
Displacement component in the \( z \) direction

\( \bar{w} \)  
Dimensionless displacement component in the \( z \)-direction

\( z \)  
Thickness direction

\( \alpha \)  
Coefficient of expansion thermal for Elastollan R3000 core or vinyl ester

\( \alpha_m, \alpha_c \)  
Coefficients of expansion thermal for the metal and ceramic phases, respectively.

\( \varepsilon_{ij}^{(k)} \)  
Strain components in the \( k \)th layer

\( \kappa \)  
Shear correction factor

\( v \)  
Poisson ratio of Elastollan R3000 core or vinyl ester

\( \nu_v, \nu_m \)  
Poisson’s ratios of the ceramic and metal phases, respectively.

\( \sigma_{ij}^{(k)} \)  
Stress components in the \( k \)th layer

\( \tau \)  
Dimensionless Stress components

\( \tau_{ij}^{(k)} \)  
Shear Stress components in the \( k \)th layer

\( \tau \)  
Dimensionless Shear Stress components

\( \Omega \)  
Material volume

\( \varnothing_x^{(k)} \)  
rotations of the normal lines to the midplane about the \( y \)-axis

\( \varnothing_y^{(k)} \)  
rotations of the normal lines to the midplane about the \( x \)-axis.

**Appendix A**

**Layer 1:**

\[
\begin{align*}
    u^{(1)}(x, y, z, t) &= u(x, y, t) - \frac{h_2}{2} \varnothing_x^{(3)}(x, y, t) - h_2 \varnothing_y^{(2)}(x, y, t) - \frac{h_2}{2} \varnothing_x^{(1)}(x, y, t) + z^{(1)} \varnothing_y^{(1)}(x, y, t) \\
    v^{(1)}(x, y, z, t) &= v(x, y, t) - \frac{h_3}{2} \varnothing_y^{(3)}(x, y, t) - h_2 \varnothing_y^{(2)}(x, y, t) - \frac{h_2}{2} \varnothing_y^{(1)}(x, y, t) + z^{(1)} \varnothing_y^{(1)}(x, y, t) \\
    w^{(1)}(x, y, z, t) &= w(x, y, t)
\end{align*}
\]  
(A1)

**Layer 2:**

\[
\begin{align*}
    u^{(2)}(x, y, z, t) &= u(x, y, t) - \frac{h_1}{2} \varnothing_x^{(3)}(x, y, t) - h_2 \varnothing_y^{(2)}(x, y, t) - \frac{h_2}{2} \varnothing_x^{(1)}(x, y, t) + z^{(2)} \varnothing_y^{(1)}(x, y, t) \\
    v^{(2)}(x, y, z, t) &= v(x, y, t) - \frac{h_3}{2} \varnothing_y^{(3)}(x, y, t) - h_2 \varnothing_y^{(2)}(x, y, t) - \frac{h_2}{2} \varnothing_y^{(1)}(x, y, t) + z^{(2)} \varnothing_y^{(1)}(x, y, t) \\
    w^{(2)}(x, y, z, t) &= w(x, y, t)
\end{align*}
\]  
(A2)
Layer 3:
\[
\begin{align*}
    u^{(3)}(x, y, z, t) &= u(x, y, t) + z^{(3)} \varphi^{(3)}_x(x, y, t) \\
v^{(3)}(x, y, z, t) &= v(x, y, t) + z^{(3)} \varphi^{(3)}_y(x, y, t) \\
w^{(3)}(x, y, z, t) &= w(x, y, t)
\end{align*}
\]
(A3)

Layer 4:
\[
\begin{align*}
    u^{(4)}(x, y, z, t) &= u(x, y, t) + \frac{h_2}{2} \varphi^{(4)}_x(x, y, t) + \frac{h_2}{2} \varphi^{(4)}_y(x, y, t) + z^{(4)} \varphi^{(4)}_z(x, y, t) \\
v^{(4)}(x, y, z, t) &= v(x, y, t) + \frac{h_3}{2} \varphi^{(4)}_x(x, y, t) + \frac{h_3}{2} \varphi^{(4)}_y(x, y, t) + z^{(4)} \varphi^{(4)}_z(x, y, t) \\
w^{(4)}(x, y, z, t) &= w(x, y, t)
\end{align*}
\]
(A4)

Layer 5:
\[
\begin{align*}
    u^{(5)}(x, y, z, t) &= u(x, y, t) + \frac{h_2}{2} \varphi^{(5)}_x(x, y, t) + h_2 \varphi^{(5)}_y(x, y, t) + z^{(5)} \varphi^{(5)}_z(x, y, t) \\
v^{(5)}(x, y, z, t) &= v(x, y, t) + \frac{h_3}{2} \varphi^{(5)}_x(x, y, t) + h_3 \varphi^{(5)}_y(x, y, t) + z^{(5)} \varphi^{(5)}_z(x, y, t) \\
w^{(5)}(x, y, z, t) &= w(x, y, t)
\end{align*}
\]
(A5)

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