



Article A Nonhomogeneous Boundary Value Problem for Steady State Navier-Stokes Equations in a Multiply-Connected Cusp Domain

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Abstract: The boundary value problem for the steady Navier–Stokes system is considered in a 2*D* multiply-connected bounded domain with the boundary having a power cusp singularity at the point *O*. The case of a boundary value with nonzero flow rates over connected components of the boundary is studied. It is also supposed that there is a source/sink in *O*. In this case the solution necessarily has an infinite Dirichlet integral. The existence of a solution to this problem is proved assuming that the flow rates are "sufficiently small". This condition does not require the norm of the boundary data to be small. The solution is constructed as the sum of a function with the finite Dirichlet integral and a singular part coinciding with the asymptotic decomposition near the cusp point.

Keywords: stationary Navier–Stokes equations; multi-connected domain; power cusp; singular solutions; asymptotic expansion; regularity

JEL Classification: 35Q30; 35A20; 76M45; 76D03

1. Introduction

In the paper we study the nonhomogeneous stationary boundary value problem for the Navier-Stokes equations

$$\begin{cases} -\nu\Delta\mathbf{u} + (\mathbf{u}\cdot\nabla)\mathbf{u} + \nabla p = \mathbf{f}, & x \in \Omega, \\ \operatorname{div}\mathbf{u} = 0, & x \in \Omega, \\ \mathbf{u} = \mathbf{a}, & x \in \partial\Omega, \end{cases}$$
(1)

in a multiply-connected domain $\Omega \subset \mathbb{R}^2$ with a cusp point O = (0,0) on the boundary. We assume that $\partial \Omega = \bigcup_{i=1}^N \Gamma_i \cup \Gamma$ consists of N + 1 disjoint components Γ , Γ_j , j = 1, ..., N,

$$\Omega = \Omega_0 \cup G = \left(D_0 \setminus \left(\cup_{j=1}^N \overline{D}_j \right) \right) \cup G, \quad \overline{D}_j \subset D_0, \ j = 1, \dots, N,$$

where $\Gamma_j = \partial D_j$, j = 1, ..., N, $\Gamma = \partial \Omega \setminus \bigcup_{j=1}^N \Gamma_j$ and $G = \{x \in \mathbb{R}^2 : |x_1| \le \varphi(x_2), x_2 \in (0, H]\}$, $\varphi(x_2) = \gamma_0 x_2^\lambda$, $\gamma_0 = \text{const}$, $\lambda > 1$. Moreover, we suppose that $\partial \Omega \cap \partial \Omega_0$ is C^2 (see Figure 1). In (1) the velocity vector **u** and the pressure function p are the unknowns while the boundary value $\mathbf{a} \in W^{1/2,2}(\partial \Omega)$ and the external force $\mathbf{f} \in L^2(\Omega)$ are given; $\nu > 0$ denotes a constant coefficient of the kinematic viscosity.

We assume that the support of **a** is separated from the cusp point *O*, i.e.,

supp
$$\mathbf{a} \subset (\Gamma \cap \partial \Omega_0) \cup (\cup_{i=1}^N \Gamma_i).$$



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Figure 1. Domain $\Omega = \Omega_0 \cup G$.

Let

$$F_0 = \int_{\Gamma \cap \partial \Omega_0} \mathbf{a} \cdot \mathbf{n} \, dS, \quad F_j = \int_{\Gamma_j} \mathbf{a} \cdot \mathbf{n} \, dS, \quad j = 1, \dots, N,$$
(2)

be the flow rates of the boundary value **a** over the outer boundary $\Gamma \cap \partial \Omega_0$ and the inner boundaries Γ_j , j = 1, ..., N, where **n** denotes the unit vector of the outward normal to $\partial \Omega$. By the incompressibility of the fluid it follows that

$$\int_{\sigma(R)} \mathbf{u} \cdot \mathbf{n} \, dS = -\left(F_0 + \sum_{j=1}^N F_j\right), \quad 0 < R < H,\tag{3}$$

where $\sigma(R) = (-\varphi(R), \varphi(R))$ is a cross section of *G* by the straight line $x_2 = R$ parallel to the x_1 -axis. We assume that the total flux may be nonzero, i.e., $F_0 + \sum_{j=1}^{N} F_j \neq 0$. This nonzero condition means that there is a source or sink in the cusp point *O*. Then, due to the geometry of the domain, the velocity vector field **u** necessarily has infinite Dirichlet integral $\int |\nabla \mathbf{u}(x)|^2 dx = \infty$ (see, e.g., [1]).

The point source/sink approach is widely used in physics, astronomy and in fluid and aerodynamics. The behaviour of solutions to the Stokes and Navier–Stokes equations in singularly perturbed domains became of growing interest during the last fifty years. There is an extensive literature concerning these issues for various elliptic problems, e.g., [2–18]. In particular, the steady Navier–Stokes equations are studied in a punctured domain $\Omega = \Omega_0 \setminus \{O\}$ with $O \in \Omega_0$ assuming that the point O is a sink or source of the fluid [19–21] (see also [22] for the review of these results). We also mention the papers [23–25] where the existence of a solution (with an infinite Dirichlet integral) to the Navier–Stokes problem with a sink or source in the cusp point O was proved for arbitrary data and the papers [26–28] where the asymptotics of a solution to the nonstationary Stokes problem is studied in domains with conical points and conical outlets to infinity.

The existence of singular solutions to the time-periodic and initial boundary value problems for the linear Stokes and the nonlinear Navier–Stokes equations in domains with a cusp point on the boundary were studied in recent papers [29–32], where the case with a sink/source in the cusp point O was considered. In [23], the existence of a generic stationary solution with infinite Dirichlet integral was proved. However, the behaviour of the solution near the cusp point was not found. The asymptotic decomposition near the cusp point of the solution \mathbf{u} to problem (1) was constructed and the existence of a unique solution which is represented as a sum of this decomposition and a vector field belonging to a suitable second order weighted Sobolev space is proved in [1]. In [1], it is

assumed that $\mathbf{a} \in W^{3/2,2}(\partial\Omega)$ and the results are obtained under the condition that the norm $\|\mathbf{a}\|_{W^{3/2,2}(\partial\Omega)}$ is sufficiently small.

In this paper we extend the results of [1] in two directions: first, we study the case of domains with multiply-connected boundaries and, second, we prove the existence of the solution coinciding near the cusp point with the formal asymptotic decomposition assuming only that the flow rates F_0, F_1, \ldots, F_N of the boundary value **a** are sufficiently small. The proof is based on the construction of an extension of the boundary value which coincides near the cusp point with the asymptotic decomposition and allows to obtain needed a priori estimates assuming only that flow rates are sufficiently small. Note that in this case the norm of **a** is not obliged to be small. It is worth to mention the papers [33–35] where the nonhomogeneous boundary value problem for the stationary Navier–Stokes equations was studied in bounded domains with multiply-connected boundaries having C^2 -regularity.

2. Notation and Auxiliary Results

2.1. Function Spaces

We will use the letter "c" for a generic constant which numerical value or dependence on parameters is unessential to our considerations; "c" may have different values in a single computation. Vector valued functions are denoted by bold letters while function spaces for scalar and vector valued functions are denoted in the same way.

Let *D* be a bounded domain in \mathbb{R}^n with Lipschitz boundary. $C^{\infty}(D)$ denotes the set of all infinitely differentiable in *D* functions and $C_0^{\infty}(D)$ is the subset of all functions from $C^{\infty}(D)$ with compact supports in *D*. For given non-negative integers *k* and q > 1, $L^q(D)$ and $W^{k,q}(D)$ denote the usual Lebesgue and Sobolev spaces; $W^{k-1/q,q}(\partial D)$ is the trace space on ∂D of functions from $W^{k,q}(D)$. $\mathring{W}^{1,2}(D)$ is the closure of $C_0^{\infty}(D)$ in $W^{1,2}$ -norm. $J_0^{\infty}(D)$ is the set of all solenoidal (div $\mathbf{u} = 0$) vector fields \mathbf{u} from $C_0^{\infty}(D)$ and H(D) is the closure of $J_0^{\infty}(D)$ in the gradient norm $\|\nabla \cdot\|_{L^2(D)}$.

Lemma 1 ([36,37], Chapter 1, Lemma 1). Let $D \subset \mathbb{R}^2$ be a bounded domain. If $u \in W^{1,2}(D)$, then the following estimate

$$\|u\|_{L^4(D)}^4 \le c \|u\|_{W^{1,2}(D)}^2 \|u\|_{L^2(D)}^2 \le c \|u\|_{W^{1,2}(D)}^4$$

holds. Moreover, if $u \in \mathring{W}^{1,2}(D)$ *then*

$$\|u\|_{L^{4}(D)}^{4} \leq 2 \|u\|_{L^{2}(D)}^{2} \|\nabla u\|_{L^{2}(D)}^{2} \leq c \|\nabla u\|_{L^{2}(D)}^{4}$$

Consider the domain Ω with a cusp point. We introduce a family of subdomains $\Omega_k \subset \Omega$ with Lipschitz boundaries:

$$\Omega_k = \Omega_{k-1} \cup \{x \in \mathbb{R}^2 : |x_1| \le \varphi(x_2), x_2 \in (h_k, h_{k-1})\} = \Omega_{k-1} \cup \omega_k,$$

where

$$h_0 = H, \quad h_k = h_{k-1} - \frac{\varphi(h_{k-1})}{2L}, \quad k = 1, 2, \dots,$$
 (4)

and *L* is the Lipschitz constant for the function φ .

We write $u \in W_{loc}^{l,q}(\overline{\Omega} \setminus \{O\})$ if $u \in W^{l,q}(\Omega_k)$ for $\forall k$.

Lemma 2. Let $u \in W^{1,2}_{loc}(\overline{\Omega} \setminus \{O\})$, u = 0 on $\partial\Omega \setminus \{O\}$. If $\int_{G} |\varphi(x_2)|^{2\alpha} |\nabla u(x)|^2 dx < \infty$, then the integral $\int_{C} |\varphi(x_2)|^{2\alpha-2} |u(x)|^2 dx$ is finite and the following inequality

$$\int_{H_1-\varphi(x_2)}^{H_2-\varphi(x_2)} \int_{H_1-\varphi(x_2)}^{\varphi(x_2)} |\varphi(x_2)|^{\alpha-2} |u(x)|^2 dx_1 dx_2 \le \frac{4}{\pi^2} \int_{H_1-\varphi(x_2)}^{H_2-\varphi(x_2)} |\varphi(x_2)|^{\alpha} |\nabla u(x)|^2 dx_1 dx_2$$
(5)

holds, where H_1 , H_2 are any numbers from the interval [0, H]

The proof of this lemma can be found in [32] (see Lemma 2.1).

2.2. Formal Asymptotic Decomposition

The formal asymptotic decomposition $(\mathbf{U}^{[J]}, P^{[J]})$ of the solution (\mathbf{u}, p) of problem (1) near the cusp point *O* was constructed in [1]. It has the form

$$U_{1}^{[J]}(y_{1}, y_{2}) = y_{2}^{-1} \mathcal{U}_{1,0}(y_{1}) + \sum_{k=1}^{J} y_{2}^{-1+k(\lambda-1)} \mathcal{U}_{1,k}(y_{1}),$$

$$U_{2}^{[J]}(y_{1}, y_{2}) = \frac{\mathbb{F}}{\kappa_{0}} y_{2}^{-\lambda} \Phi(y_{1}) + \sum_{k=1}^{J} y_{2}^{-\lambda+k(\lambda-1)} \mathcal{U}_{2,k}(y_{1}),$$

$$P^{[J]}(y_{1}, y_{2}) = \frac{\mathbb{F}}{\kappa_{0}(1-3\lambda)} y_{2}^{1-3\lambda} + y_{2}^{-1-\lambda} \mathcal{Q}_{0}(y_{1}) + \sum_{k=1}^{J} y_{2}^{1-3\lambda+k(\lambda-1)} C_{k} + y_{2}^{-1-\lambda+k(\lambda-1)} \mathcal{Q}_{k}(y_{1}),$$
(6)

where $y_1 = \frac{x_1}{x_2^{\lambda}}$, $y_2 = x_2$, $\Phi(y_1) = \frac{1}{2\nu} (|y_1|^2 - \gamma_0^2)$, the functions $\mathcal{U}_{1,k}$, $\mathcal{U}_{2,k}$, \mathcal{Q}_k are regular, and

$$\int_{\sigma(R)} \mathbf{U}^{[J]}(\frac{x_1}{x_2^{\lambda}}, x_2) \cdot \mathbf{n}(x) \, dS = -\mathbb{F}, \quad \mathbb{F} = F_0 + \sum_{j=1}^N F_j.$$

It was proved in [1] that $U_j^{[J]}(y_1, y_2)$, $j = 1, 2, P^{[J]}(y_1, y_2)$ satisfy the estimates

$$\left|\frac{\partial^{l} U_{1}^{[J]}(y_{1}, y_{2})}{\partial y_{1}^{l}}\right| \leq c \frac{|\mathbb{F}|}{y_{2}^{1+l}}, \quad \left|\frac{\partial^{l} U_{2}^{[J]}(y_{1}, y_{2})}{\partial y_{1}^{l}}\right| \leq c \frac{|\mathbb{F}|}{y_{2}^{\lambda+l}}, \quad l = 0, 1, \dots,$$

$$|P^{[J]}(y_{1}, y_{2})| \leq c \frac{|\mathbb{F}|}{y_{2}^{3\lambda-1}}.$$
(7)

The asymptotic decomposition $(\widehat{\mathbf{U}}^{[J]}(x), \widehat{P}^{[J]}(x)) = (\mathbf{U}^{[J]}(\frac{x_1}{x_2^{\lambda}}, x_2), P^{[J]}(\frac{x_1}{x_2^{\lambda}}, x_2))$ is defined in *G* and, by construction, $\operatorname{div}_x \widehat{\mathbf{U}}^{[J]} = 0$, $\widehat{\mathbf{U}}^{[J]}|_{\partial G \cap \partial \Omega} = 0$. Moreover, it was proved in [1] that for a sufficiently large $J = J(\lambda)$ ($J > \frac{4\lambda + 1}{2(\lambda - 1)}$) holds the relation

$$-\nu \Delta \widehat{\mathbf{U}}^{[J]} + (\widehat{\mathbf{U}}^{[J]} \cdot \nabla) \widehat{\mathbf{U}}^{[J]} + \widehat{\nabla} P^{[J]} = \widehat{\mathbf{H}}^{[J]}$$
(8)

with $\widehat{\mathbf{H}}^{[J]} \in L^2(G)$. Moreover, the discrepancy $\widehat{\mathbf{H}}^{[J]}$ satisfies the estimate

$$\|\widehat{\mathbf{H}}^{[J]}\|_{L^2(G)} \le c \Big(|\mathbb{F}| + |\mathbb{F}|^2\Big).$$
(9)

3. Extension of Boundary Value

3.1. Flux Carrier from Inner Boundaries

In this subsection we construct a solenoidal vector function having the flow rates F_j on inner components of the boundaries Γ_j , j = 1, ..., N. We call such a function the flux carrier. The construction used below is based on ideas proposed by H. Fujita in [38] for the case of symmetric domains. In [38] such functions are called virtual drains.

First we define some auxiliary functions. Let $\kappa \in (0, 1/2)$ be a parameter. We introduce non-negative, even functions $\beta_{\kappa}(t) \in C_0^{\infty}(-\infty; +\infty)$ such that

$$eta_\kappa(t) \leq rac{1}{t} ext{ for } 0 < t < +\infty ext{ and } eta_\kappa(t) = \left\{ egin{array}{cc} 0, & |t| \geq 1, \ 1/t, & \kappa \leq |t| \leq 1/2. \end{array}
ight.$$

Define
$$y_{\kappa} = \int_{-\infty}^{\infty} \beta_{\kappa}(t) dt$$
. Then
$$y_{\kappa} = \int_{-\infty}^{+\infty} \beta_{\kappa}(t) dt = \int_{-1}^{1} \beta_{\kappa}(t) dt \ge 2 \int_{\kappa}^{\frac{1}{2}} \frac{1}{t} dt \to +\infty \text{ as } \kappa \to +0.$$

Define a smooth non-negative functions $s_{\kappa}(t) = s_{\kappa}(t,\delta) = \frac{1}{y_{\kappa}\delta}\beta_{\kappa}(\frac{t}{\delta})$ such that $s_{\kappa} \in C_0^{\infty}(-\infty; +\infty)$ and $\operatorname{supp} s_{\kappa} \subseteq [-\delta; \delta]$, where δ is a small positive number. Then

$$\int_{-\infty}^{+\infty} s_{\kappa}(t) dt = \int_{-\delta}^{\delta} s_{\kappa}(t) dt = 1.$$
(10)

Choose one of the domains D_j , j = 1, ..., N, and take two points $X_j \in D_j$ and $X_j^0 \in \Gamma \cap \partial \Omega_0$ such that the line $X_j X_j^0$ intersects Γ_j and Γ only at one point and, if $X_j X_j^0$ intersects other boundaries, say, Γ_{k_m} , $k_m = k_1, k_2, ..., K_j$, $0 \le K_j \le N - 1$, then-at even number of points (if $K_j = 0$, then $X_j X_j^0$ does not intersect any of Γ_{k_m}). Let us introduce in Ω the local coordinates $z^{(j)} = (z_1^{(j)}, z_2^{(j)})$ such that the origin of this coordinate system coincides with the point X_j and $z_2^{(j)}$ axis is directed over the vector $\overrightarrow{X_j X_j^0}$.

The points X_j^0 and X_j in the local coordinates $z^{(j)}$ have the form $X_j^0 = (0, Z_0^{(j)}), Z_0^{(j)} > 0$ and $X_j = (0, 0)$. Let us take a small number $\mu_0 > 0$ and define the strip:

$$\mathbf{Y}^{(j)} = [-\delta_j, \delta_j] \times [0, Z_0^{(j)} + \mu_0],$$

where we choose a small number δ_j so that the segments $\{z^{(j)} : z_1^{(j)} = \pm \delta_j\} \cap \partial Y^{(j)}$ intersect Γ_j and Γ only at one point and if intersect other boundaries, then - at even number of points.

In $\Upsilon^{(j)} \cap \Omega$ we define a vector field:

$$\mathbf{b}_j(z^{(j)}) = \left(0, -F_j s_{\kappa}(z_1^{(j)})\right)$$

Notice that $\mathbf{b}_j(z^{(j)})$ defined on $\mathbf{Y}^{(j)} \cap \Omega$ can be extended by zero into the whole domain Ω , because the bottom of $\mathbf{Y}^{(j)}$ is outside the domain Ω . For the sake of simplicity we keep the same notation for this extension, i.e., in the whole domain Ω we have:

$$\mathbf{b}_j(z^{(j)}) = \begin{cases} \left(0, -F_j s_\kappa(z_1^{(j)})\right) \text{ in } \mathbf{Y}^{(j)} \cap \Omega, \\ (0,0) \text{ in } \overline{\Omega} \setminus \mathbf{Y}^{(j)}. \end{cases}$$

We shall show that

$$\int_{\Gamma_i} \mathbf{b}_j(z^{(j)}) \cdot \mathbf{n} \, dS = \begin{cases} F_i, & i = j, \\ 0, & i \neq j. \end{cases}$$
(11)

Let us introduce the domain $\widetilde{Y}^{(j)} \subset Y^{(j)} \cap \Omega$ with the boundary $\partial \widetilde{Y}^{(j)}$ which is the union of: $\Gamma_j \cap Y^{(j)}$, $\{z^{(j)} : -\delta_j \leq z_1^{(j)} \leq \delta_j, z_2^{(j)} = \mu_j^*\}$ and the lines $z_1^{(j)} = \pm \delta_j$, where $\mu_j^* > 0$ is a such small number that $\widetilde{Y}^{(j)}$ is a simple connected set (see Figure 2). Since, due to the construction, $\mathbf{b}_j(z^{(j)})$ is solenoidal and $\mathbf{b}_j(z^{(j)})|_{z_1^{(j)}=\pm \delta_j} = 0$, we get

$$0 = \int_{\widetilde{Y}^{(j)}} \operatorname{div} \mathbf{b}_{j}(z^{(j)}) dz^{(j)} = \int_{\partial \widetilde{Y}^{(j)}} \mathbf{b}_{j}(z^{(j)}) \cdot \mathbf{n} \, dS$$

$$= \int_{Y^{(j)} \cap \Gamma_{j}} \mathbf{b}_{j}(z^{(j)}) \cdot \mathbf{n} \, dS + \int_{\{z^{(j)}: -\delta_{j} \leq z_{1}^{(j)} \leq \delta_{j}, z_{2}^{(j)} = \mu_{j}^{*}\}} \mathbf{b}_{j}(z^{(j)}) \cdot \mathbf{e}_{2} \, dS$$

$$= \int_{\Gamma_{j}} \mathbf{b}_{j}(z^{(j)}) \cdot \mathbf{n} \, dS + \int_{-\delta_{j}}^{\delta_{j}} \left(0, -F_{j}s_{\kappa}(z_{1}^{(j)})\right) \cdot (0, 1) \, dz_{1}^{(j)} = \int_{\Gamma_{j}} \mathbf{b}_{jk}(z^{(j)}) \cdot \mathbf{n} \, dS - F_{j} \int_{-\delta_{j}}^{\delta_{j}} s_{\kappa}(z_{1}^{(j)}) \, dz_{1}^{(j)},$$

where the vector field **n** denotes the unit outward normal to $\partial\Omega$ on Γ_j , while the vector \mathbf{e}_2 denotes the unit normal to $\partial\widetilde{\Upsilon}^{(j)}$ on $\{z^{(j)} : -\delta_j \leq z_1^{(j)} \leq \delta_j, z_2^{(j)} = \mu_j^*\}$. Due to (10), from the last equality we get (11). Notice that for the case $i \neq j$, when $\Upsilon^{(j)}$ does not intersect or touch Γ_i , the vector field \mathbf{b}_j vanishes on Γ_i (by construction). Otherwise, if $\Upsilon^{(j)}$ intersects Γ_i at even number of points, then flow rates of \mathbf{b}_j across Γ_i are equal to zero: the flow rates of \mathbf{b}_j over not intersecting parts of $\Upsilon^{(j)} \cap \Gamma_i$ cancel each other.



Figure 2. The strip $Y^{(1)}$. Dashed area is $\widetilde{Y}^{(1)}$.

In order to rewrite vector field $\mathbf{b}_j(z^{(j)})$ in global coordinates let us take the orthogonal matrix A_j with det $A_j = 1$ such that $z^{(j)} = A_j(x - x_0)$. Then it is easy to verify that

$$\mathbf{b}_{j}^{(inn)}(x) = A_{j}^{T} \mathbf{b}_{j}(z^{(j)}) \Big|_{z^{(j)} = A_{j}(x - x_{0})}.$$

Therefore, the flux carrier from the inner boundaries has the form:

$$\mathbf{b}^{(inn)}(x) = \sum_{j=1}^{N} \mathbf{b}_{j}^{(inn)}(x).$$

Lemma 3. The vector field $\mathbf{b}^{(inn)}$ is smooth and solenoidal. Moreover, $\operatorname{supp} \mathbf{b}^{(inn)} \subset \Omega_0$,

$$\int_{\Gamma_j} \mathbf{b}^{(inn)} \cdot \mathbf{n} dS = F_j, \quad j = 1, \dots, N, \quad \int_{\Gamma \cap \partial \Omega_0} \mathbf{b}^{(inn)} \cdot \mathbf{n} dS = -\sum_{j=1}^N F_j$$
(12)

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and the following estimate

$$\mathbf{b}^{(inn)}(x)| + |\nabla \mathbf{b}^{(inn)}(x)| \le c \sum_{j=1}^{N} |F_j|, \quad \forall x \in \overline{\Omega}_0$$
(13)

holds.

3.2. Flux Carrier from the Outer Boundary

The boundary condition $\mathbf{u} = \mathbf{a}$ is prescribed on $(\Gamma \cap \partial \Omega_0) \cup (\bigcup_{j=1}^N \Gamma_j)$. After subtracting the constructed flux carrier $\mathbf{b}^{(inn)}$, which "removes" the fluxes F_j from the inner boundaries Γ_j , j = 1, ..., N, we get a modified boundary value $\mathbf{a}_1 = \mathbf{a} - \mathbf{b}^{(inn)}|_{\partial\Omega}$ such that supp $\mathbf{a}_1 \subset (\Gamma \cap \partial \Omega_0) \cup (\bigcup_{j=1}^N \Gamma_j)$ and the flow rates of \mathbf{a}_1 over the inner boundaries Γ_j , j = 1, ..., N, are equal to zero:

$$\int_{\Gamma_i} \mathbf{a}_1 \cdot \mathbf{n} dS = 0,$$

and the flow rate of **a**₁ over the outer boundary $\Gamma \cap \partial \Omega_0$ is equal to $F_0 + \sum_{j=1}^N F_j$:

$$\int_{\Gamma\cap\partial\Omega_0} \mathbf{a}_1 \cdot \mathbf{n} dS = F_0 + \sum_{j=1}^N F_j = \mathbb{F}.$$

Now we remove the nonzero flux from the outer boundary $\Gamma \cap \partial \Omega_0$. For this we will need the notion of Stein's regularised distance. Let \mathcal{M} be a closed set in \mathbb{R}^2 . Stein's regularised distance $\Delta_{\mathcal{M}}(x)$ from the point x to the set \mathcal{M} is an infinitely differentiable function in $\mathbb{R}^2 \setminus \mathcal{M}$ and the following inequalities

$$a_1d_{\mathcal{M}}(x) \leq \Delta_{\mathcal{M}}(x) \leq a_2d_{\mathcal{M}}(x), \quad |\mathrm{D}^{lpha}\Delta_{\mathcal{M}}(x)| \leq a_3d_{\mathcal{M}}^{1-|lpha|}(x),$$

hold, where $d_{\mathcal{M}}(x) = dist(x, \mathcal{M})$ is the distance from x to \mathcal{M} . The positive constants a_1, a_2 and a_3 are independent of \mathcal{M} (see [39], Chapter VI, Sections 1 and 2, 167–171, Theorem 2).

Let γ be a smooth simple curve, which intersects the outer boundary at some point $x^{(out)} \in \Gamma \cap \partial \Omega_0$, does not intersect or touch any inner boundary Γ_j , j = 1, ..., N, and coincides with the straight line $x_1 = 0$ in *G* (see Figure 3).

Let us introduce a function

$$\xi(x) = \Psi\Big(\ln \frac{\rho(\Delta_{\gamma}(x))}{\Delta_{\partial \Omega \setminus (\Gamma \cap \partial \Omega_0)}(x)}\Big),$$

where Ψ and ρ are infinitely differentiable monotonic functions such that $\Psi(t) = 0$ for $t \leq 0$, $\Psi(t) = 1$ for $t \geq 1$, and $\rho(\tau) = \frac{a_1}{2}d_0$ for $\tau \leq \frac{a_2}{2}$, $\rho(\tau) = \tau$ for $\tau \geq a_2d_0$, d_0 is the distance between the curve γ and $\partial\Omega \setminus (\Gamma \cap \partial\Omega_0)$. The functions $\Delta_{\gamma}(x)$ and $\Delta_{\partial\Omega \setminus (\Gamma \cap \partial\Omega_0)}$ are regularised distances from x to γ and $\partial\Omega \setminus (\Gamma \cap \partial\Omega_0)$, respectively.



Figure 3. Curve γ .

Lemma 4. The function $\xi(x)$ vanishes at those points $x \in \overline{\Omega} \setminus \{O\}$, where $\rho(\Delta_{\gamma}(x)) \leq \Delta_{\partial\Omega \setminus (\Gamma \cap \partial\Omega_0)}(x)$, and $\xi(x) = 1$ at points $x \in \overline{\Omega} \setminus \{O\}$ where $\Delta_{\partial\Omega \setminus (\Gamma \cap \partial\Omega_0)}(x) \leq e^{-1}\rho(\Delta_{\gamma}(x))$. Moreover, the following inequalities

$$\left|\frac{\partial\xi(x)}{\partial x_{k}}\right| \leq \frac{c}{\Delta_{\partial\Omega\setminus(\Gamma\cap\partial\Omega_{0})}(x)} \leq c_{1}, \quad \left|\frac{\partial^{2}\xi(x)}{\partial x_{k}\partial x_{l}}\right| \leq \frac{c}{\Delta_{\partial\Omega\setminus(\Gamma\cap\partial\Omega_{0})}^{2}(x)} \leq c_{1}, \quad x \in \overline{\Omega}_{4},$$
(14)

hold with the constant c_1 dependent only on a_1, a_2 and d_0 .

The proof of this lemma can be found in [40] (see Lemma 2).

Let us define a vector field

$$\mathbf{b}^{(out)}(x) = -\mathbb{F}\Big(\frac{\partial \tilde{\xi}(x)}{\partial x_2}, -\frac{\partial \tilde{\xi}(x)}{\partial x_1}\Big),$$

where $\tilde{\xi}(x)$ coincides with $\xi(x)$ on the right side of the curve γ and $\tilde{\xi}(x) = 0$ on the left of γ .

By construction, the vector field $\mathbf{b}^{(out)}(x)$ is smooth, solenoidal and $\mathbf{b}^{(out)}(x)|_{\partial\Omega\setminus(\Gamma\cap\partial\Omega_0)}=0.$

Lemma 5. There hold the relation

$$\int_{\Gamma \cap \partial \Omega_4} \mathbf{b}^{(out)} \cdot \mathbf{n} \, dS = \mathbb{F} \tag{15}$$

and the estimate

$$|\mathbf{b}^{(out)}(x)| + |\nabla \mathbf{b}^{(out)}(x)| \le c |\mathbb{F}| \quad \forall x \in \overline{\Omega}_4.$$
(16)

Proof. Since $\operatorname{div} \mathbf{b}^{(out)} = 0$, we have

$$\int_{\Gamma \cap \partial \Omega_4} \mathbf{b}^{(out)} \cdot \mathbf{n} \, dS = -\int_{\sigma(h_4)} \mathbf{b}^{(out)} \cdot \mathbf{n} \, dS = \mathbb{F} \int_{-\varphi(h_4)}^{\varphi(h_4)} \left(\frac{\partial \widetilde{\xi}(x)}{\partial x_2}, -\frac{\partial \widetilde{\xi}(x)}{\partial x_1} \right) \cdot (0, -1) \, dx$$
$$= \mathbb{F} \int_{-\varphi(h_4)}^{\varphi(h_4)} \frac{\partial \widetilde{\xi}(x)}{\partial x_1} \, dx_1 = \mathbb{F} \left(\widetilde{\xi}(\varphi(h_4), h_4) - \widetilde{\xi}(-\varphi(h_4), h_4) \right) = \mathbb{F}.$$

Estimate (16) follows from Lemma 4 and properties of the regularised distance. \Box

The modified boundary value $\mathbf{a}_2 = \mathbf{a}_1 - \mathbf{b}^{(out)}|_{\partial\Omega}$ has a support on $(\Gamma \cap \partial\Omega_0) \cup (\bigcup_{j=1}^N \Gamma_j)$ and the flow rates of \mathbf{a}_2 on $\Gamma \cap \partial\Omega_0$ and Γ_j , j = 1, ..., N, are equal to zero:

$$\int_{\Gamma \cap \partial \Omega_0} \mathbf{a}_2 \cdot \mathbf{n} \, dS = 0, \quad \int_{\Gamma_j} \mathbf{a}_2 \cdot \mathbf{n} \, dS = 0, \quad j = 1, \dots, N.$$
(17)

3.3. Extension of a_2

The extension of the boundary value function having zero flux over the boundary was constructed by O.A. Ladyzhenskaya (see [37], Chapter V, Section 4, 127–128). To be more precise, in [37] was proved the following result

Lemma 6. Let $D \subset \mathbb{R}^2$ be a bounded domain with Lipschitz boundary ∂D , $\mathcal{L} \subseteq \partial D$, meas $(\mathcal{L}) > 0$. Assume that the vector field $\mathbf{h} \in W^{1/2,2}(\partial D)$ satisfies the conditions $\int_{\Omega} \mathbf{h} \cdot \mathbf{n} \, dS = 0$, supp $\mathbf{h} \subseteq \mathcal{L}$.

Then **h** can be extended inside D in the form

$$\mathbf{H}(x,\varepsilon) = \left(\frac{\partial(\chi(x,\varepsilon)\mathbf{E}(x))}{\partial x_2}, -\frac{\partial(\chi(x,\varepsilon)\mathbf{E}(x))}{\partial x_1}\right),\tag{18}$$

where $\mathbf{E} \in W^{2,2}(D)$, $(\frac{\partial \mathbf{E}(x)}{\partial x_2}, -\frac{\partial \mathbf{E}(x)}{\partial x_1})|_{\partial D} = \mathbf{h}$ and $\chi = \chi(x, \varepsilon)$ is Hopf's type cut-off function, *i.e.*, χ is smooth, $\chi(x, \varepsilon) = 1$ on \mathcal{L} , supp χ is contained in a small neighborhood of \mathcal{L} and

$$|\nabla \chi(x,\varepsilon)| \le \frac{\varepsilon c}{\operatorname{dist}(x,\mathcal{L})}.$$
(19)

The constant c in (19) *is independent of* $\varepsilon > 0$ *.*

The vector field $\mathbf{H} \in W^{1,2}(D)$ is solenoidal, $\mathbf{H}|_{\partial D} = \mathbf{h}$, supp \mathbf{H} is contained in a small neighbourhood of \mathcal{L} and there holds the estimate

$$\|\mathbf{H}\|_{W^{1,2}(D)} \le c(\varepsilon) \|\mathbf{h}\|_{W^{1/2,2}(\partial D)}.$$
(20)

Moreover, for any $\varepsilon > 0$ *the vector field* **H** *satisfies the Leray-Hopf inequality*

$$\int_{D} (\mathbf{w} \cdot \nabla) \mathbf{H} \cdot \mathbf{w} dx \le c \varepsilon \int_{D} |\nabla \mathbf{w}|^2 dx \quad \forall \mathbf{w} \in H(D)$$
(21)

with the constant *c* independent of ε .

Because of the condition (17) we can apply Lemma 6 to a_2 and we obtain the following result.

Lemma 7. There exists a vector field $\mathbf{b}_0 \in W^{1,2}(\Omega)$ such that $\mathbf{b}_0|_{\partial\Omega} = \mathbf{a}_2$, div $\mathbf{b}_0 = 0$, supp $\mathbf{b}_0 \subset \overline{\Omega}_1$,

$$\|\mathbf{b}_{0}\|_{W^{1,2}(\Omega)} \le c \|\mathbf{a}_{2}\|_{W^{1/2,2}(\partial\Omega)}.$$
(22)

Moreover,

$$\int_{\Omega_k} (\mathbf{w} \cdot \nabla) \mathbf{b}_0 \cdot \mathbf{w} dx \le c \varepsilon \int_{\Omega_k} |\nabla \mathbf{w}|^2 dx \quad \forall \mathbf{w} \in H(\Omega_k).$$
(23)

The constant c in (23) *is independent of* $\varepsilon > 0$ *and k.*

3.4. Construction of Extension Coinciding with Asymptotic Decomposition Near Cusp Point

Now we "glue" the above constructed vector field $\mathbf{B} = \mathbf{b}_0 + \mathbf{b}^{(inn)} + \mathbf{b}^{(out)}$ with the asymptotic decomposition $\mathbf{U}^{[J]}$.

Let ζ be a smooth cut-off function such that $\zeta(x_2) = 1$ for $x_2 \ge h_3$, $\zeta(x_2) = 0$ for $x_2 \le h_4$, $0 \le \zeta(x_2) \le 1$. We put

$$\mathbf{A} = \mathbf{b}_0 + \mathbf{b}^{(inn)} + \zeta \mathbf{b}^{(out)} + (1 - \zeta) \mathbf{U}^{[J]} + \mathbf{V}^{[J]},$$
(24)

where $\mathbf{V}^{[J]}$ is the solution of the following problem

div
$$\mathbf{V}^{[J]} = -\nabla \zeta \cdot \mathbf{b}^{(out)} + \nabla \zeta \cdot \mathbf{U}^{[J]}, \quad x \in \omega_4,$$

 $\mathbf{V}^{[J]} = 0, \qquad \qquad x \in \partial \omega_4.$
(25)

Notice that $\int_{\omega_4} \left(\nabla \zeta \cdot \mathbf{b}^{(out)} - \nabla \zeta \cdot \mathbf{U}^{[J]} \right) dx = \int_{\omega_4} \operatorname{div} \left(\mathbf{b}^{(out)} + (1 - \zeta) \mathbf{U}^{[J]} \right) dx = 0.$ Indeed,

$$\int_{\omega_4} \operatorname{div} \left(\zeta \mathbf{b}^{(out)} + (1-\zeta) \mathbf{U}^{[J]} \right) dx = \int_{\partial \omega_4} \zeta \mathbf{b}^{(out)} \cdot \mathbf{n} \, dS + \int_{\partial \omega_4} (1-\zeta) \mathbf{U}^{[J]} \cdot \mathbf{n} \, dS$$
$$= \int_{\sigma(h_3)} \mathbf{b}^{(out)} \cdot \mathbf{n} \, dS - \int_{\sigma(h_4)} \mathbf{U}^{[J]} \cdot \mathbf{n} \, dS = \left(F_0 + \sum_{j=1}^N F_j \right) - \int_{-\varphi(h_4)}^{\varphi(h_4)} U_2^{[J]} \, dx_1 = 0,$$

where we used the fact that $\mathbf{b}^{(inn)} = 0$ in ω_4 . Therefore, there exists a solution $\mathbf{V}^{[J]} \in \mathring{W}^{1,2}(\omega_4)$ of problem (25) satisfying the estimate

$$\|\nabla \mathbf{V}^{[J]}\|_{L^{2}(\omega_{4})} \leq c \|\nabla \zeta \cdot \left(\mathbf{b}^{(out)} + \mathbf{U}^{[J]}\right)\|_{L^{2}(\omega_{2})} \leq c |\mathbb{F}|,$$
(26)

see [41].

Since div $(\mathbf{b}_0 + \mathbf{b}^{(inn)}) = 0$ and supp $(\mathbf{b}_0 + \mathbf{b}^{(inn)}) \subset \overline{\Omega}_4$, from the construction we conclude the following result.

Lemma 8. The vector field $\mathbf{A} \in W^{1,2}_{loc}(\overline{\Omega} \setminus \{O\})$ satisfies the boundary condition $\mathbf{A}|_{\partial\Omega} = \mathbf{a}$, \mathbf{A} is solenoidal and $\mathbf{A}(x) = \mathbf{U}^{[J]}(x)$ for $x_2 \leq h_4$.

4. Existence and Uniqueness of Weak Solution

In this section we prove the existence of the weak solution of problem (1).

First assume that (\mathbf{u}, p) is a classical solution of (1). Multiplying $(1)_1$ by the test function $\eta \in C_0^{\infty}(\Omega)$ and integrating by parts, we obtain

$$\nu \int_{\Omega} \nabla \mathbf{u} \cdot \nabla \eta \, dx + \int_{\Omega} (\mathbf{u} \cdot \nabla) \mathbf{u} \cdot \eta \, dx - \int_{\Omega} p \operatorname{div} \eta \, dx = \int_{\Omega} \mathbf{f} \cdot \eta \, dx \quad \forall \eta \in C_0^{\infty}(\Omega).$$
(27)

We look for the solution (\mathbf{u}, p) in the form

$$\mathbf{u} = \mathbf{A} + \mathbf{v}, \quad p = (1 - \zeta)P^{[j]} + \tilde{p}, \tag{28}$$

where **A** is the extension of the boundary value **a** constructed in the previous section, $P^{[j]}$ is defined by (6)₃ and **v** \in $H(\Omega)$. Substituting (28) into (27) we obtain

$$\nu \int_{\Omega} \nabla \mathbf{v} \cdot \nabla \boldsymbol{\eta} \, dx + \int_{\Omega} \left((\mathbf{v} + \mathbf{A}) \cdot \nabla \right) \mathbf{v} \cdot \boldsymbol{\eta} \, dx + \int_{\Omega} \left(\mathbf{v} \cdot \nabla \right) \mathbf{A} \cdot \boldsymbol{\eta} \, dx = \langle \hat{\mathbf{f}}, \boldsymbol{\eta} \rangle_{\Omega} \quad \forall \boldsymbol{\eta} \in J_0^{\infty}(\Omega),$$
(29)

where

$$\langle \hat{\mathbf{f}}, \boldsymbol{\eta} \rangle_{\Omega} = \int_{\Omega} \mathbf{f} \cdot \boldsymbol{\eta} \, dx - \nu \int_{\Omega} \nabla \mathbf{A} \cdot \nabla \boldsymbol{\eta} \, dx - \int_{\Omega} (\mathbf{A} \cdot \nabla) \mathbf{A} \cdot \boldsymbol{\eta} \, dx - \int_{\Omega} \nabla \left((1 - \zeta) P^{[J]} \right) \cdot \boldsymbol{\eta} \, dx. \tag{30}$$

The vector field **v** will be found as a limit of the sequence $\{\mathbf{v}_k\}$, where \mathbf{v}_k are weak solutions in the domains Ω_k , that is, the vector fields $\mathbf{v}_k \in H(\Omega_k)$, satisfy the integral identities

$$\nu \int_{\Omega_k} \nabla \mathbf{v}_k \cdot \nabla \eta dx + \int_{\Omega_k} \left((\mathbf{v}_k + \mathbf{A}) \cdot \nabla \right) \mathbf{v}_k \cdot \eta dx + \int_{\Omega_k} (\mathbf{v}_k \cdot \nabla) \mathbf{A} \cdot \eta dx = \langle \hat{\mathbf{f}}, \eta \rangle_{\Omega_k} \quad \forall \eta \in H(\Omega_k).$$
(31)

Theorem 1. Let $\mathbf{f} \in L^2(\Omega)$, $\mathbf{a} \in W^{1/2,2}(\partial\Omega)$ and supp $\mathbf{a} \subset (\Gamma \cap \partial\Omega_0) \cup (\bigcup_{j=1}^N \Gamma_j)$. There exists a number $\mathcal{F}_0 > 0$ such that if

$$\sum_{j=0}^{N} |F_j| \le \mathcal{F}_0,\tag{32}$$

then problem (31) admits at least one solution $\mathbf{v}_k \in H(\Omega_k)$. There holds the estimate

$$\|\nabla \mathbf{v}_{k}\|_{L^{2}(\Omega)}^{2} \leq c \Big(\|\mathbf{f}\|_{L^{2}(\Omega_{k})}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{4} \Big)$$
(33)

with the constant c independent of k.

Proof. It is well known (see [37]) that integral identity (31) is equivalent to the operator equation

$$\mathbf{v}_k = \mathcal{B}\mathbf{v}_k \tag{34}$$

with a completely continuous operator \mathcal{B} : $H(\Omega_k) \hookrightarrow H(\Omega_k)$, defined by the relation

$$[\mathcal{B}\mathbf{v}_k,\boldsymbol{\eta}]_{\Omega_k} = -\nu^{-1} \int\limits_{\Omega_k} ((\mathbf{v}_k + \mathbf{A}) \cdot \nabla) \mathbf{v}_k \cdot \boldsymbol{\eta} dx - \nu^{-1} \int\limits_{\Omega_k} (\mathbf{v}_k \cdot \nabla) \mathbf{A} \cdot \boldsymbol{\eta} dx + \nu^{-1} \langle \widehat{\mathbf{f}}, \boldsymbol{\eta} \rangle_{\Omega_k}$$

where $[\mathbf{w}, \boldsymbol{\eta}]_{\Omega_k} = \int_{\Omega_k} \nabla \mathbf{w} \cdot \nabla \boldsymbol{\eta} dx$ is the scalar product in $H(\Omega_k)$.

So, the solvability of Equation (34) will follow from the Leray–Schauder theorem provided we prove that the norms of all possible solutions of the operator equations

$$\mathbf{v}_{k}^{(\lambda)} = \lambda \mathcal{B} \mathbf{v}_{k}^{(\lambda)}, \quad \lambda \in [0; 1],$$
(35)

are bounded by a constant independent of λ .

Operator Equation (35) is equivalent to the identity

$$\nu \int_{\Omega_{k}} \nabla \mathbf{v}_{k}^{(\lambda)} \cdot \nabla \eta dx + \lambda \int_{\Omega_{k}} \left((\mathbf{v}_{k}^{(\lambda)} + \mathbf{A}) \cdot \nabla \right) \mathbf{v}_{k}^{(\lambda)} \cdot \eta dx + \lambda \int_{\Omega_{k}} (\mathbf{v}_{k}^{(\lambda)} \cdot \nabla) \mathbf{A} \cdot \eta dx$$

$$= \lambda \langle \mathbf{\hat{f}}, \eta \rangle_{\Omega_{k}} \quad \forall \eta \in H(\Omega_{k}).$$
(36)

Taking in (36) $\eta = \mathbf{v}_k^{(\lambda)}$ we obtain

$$\nu \int_{\Omega_k} |\nabla \mathbf{v}_k^{(\lambda)}|^2 dx = -\lambda \int_{\Omega_k} (\mathbf{v}_k^{(\lambda)} \cdot \nabla) \mathbf{A} \cdot \mathbf{v}_k^{(\lambda)} dx + \lambda \langle \hat{\mathbf{f}}, \mathbf{v}_k^{(\lambda)} \rangle_{\Omega_k}.$$
 (37)

To estimate the term $\lambda \langle \hat{\mathbf{f}}, \mathbf{v}_k^{(\lambda)} \rangle_{\Omega_k}$ in the right hand side of (37), we use the representation (24) for the vector field **A**. We denote $\mathbf{A}_1 = \mathbf{b}_0 + \mathbf{b}^{(inn)} + \zeta \mathbf{b}^{(out)} + \mathbf{V}^{[J]}$ and $\mathbf{A}_2 = (1 - \zeta) \mathbf{U}^{[J]}$, so that $\mathbf{A} = \mathbf{A}_1 + \mathbf{A}_2$. Since supp $\mathbf{A}_1 \subset \Omega_4$, using estimates (13), (16), (22) and (26), the embedding $W^{1,2}(\Omega_4) \hookrightarrow L^4(\Omega_4)$ and the definition of $\mathbf{a}_2 = \mathbf{a} - (\mathbf{b}^{(inn)} + \mathbf{b}^{(out)})|_{\partial\Omega'}$, we obtain the following inequality

$$\lambda \nu \Big| \int_{\Omega_{4}} \nabla \mathbf{A}_{1} \cdot \nabla \mathbf{v}_{k}^{(\lambda)} dx \Big| + \lambda \Big| \int_{\Omega_{4}} (\mathbf{A}_{1} \cdot \nabla) \mathbf{v}_{k}^{(\lambda)} \cdot \mathbf{A}_{1} dx \Big|$$

$$\leq c \Big(\| \nabla \mathbf{A}_{1} \|_{L^{2}(\Omega_{k})}^{2} + \| \mathbf{A}_{1} \|_{L^{4}(\Omega_{k})}^{4} \Big) + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2}$$

$$\leq c \Big[\big(\sum_{j=0}^{N} |F_{j}| \big)^{2} + \big(\sum_{j=0}^{N} |F_{j}| \big)^{4} + \| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{2} + \| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{4} + \| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{4} + \| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{4} \Big] + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2}$$

$$\leq c \Big[\| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{2} + \| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{4} \Big] + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2}.$$

$$(38)$$

Since supp $(\mathbf{b}_0 + \mathbf{b}^{(inn)}) \subset \Omega_3$, we have $((\mathbf{b}_0 + \mathbf{b}^{(inn)}) \cdot \nabla) \mathbf{A}_2 + (\mathbf{A}_2 \cdot \nabla) (\mathbf{b}_0 + \mathbf{b}^{(inn)}) = 0$. Thus, by (7), (16) and (26),

$$\lambda \Big| \int_{\Omega_{4}} (\mathbf{A}_{1} \cdot \nabla) \mathbf{v}_{k}^{(\lambda)} \cdot \mathbf{A}_{2} dx \Big| + \lambda \Big| \int_{\Omega_{4}} (\mathbf{A}_{2} \cdot \nabla) \mathbf{v}_{k}^{(\lambda)} \cdot \mathbf{A}_{1} dx \Big|$$

$$\leq \Big| \int_{\omega_{4}} ((\mathbf{V}^{[J]} + \mathbf{b}^{(out)}) \cdot \nabla) \mathbf{v}_{k}^{(\lambda)} \cdot \mathbf{U}^{[J]} dx \Big| + \Big| \int_{\omega_{4}} (\mathbf{U}^{[J]} \cdot \nabla) \mathbf{v}_{k}^{(\lambda)} \cdot (\mathbf{V}^{[J]} + \mathbf{b}^{(out)}) dx \Big|$$

$$\leq c \Big(\| \mathbf{V}^{[J]} \|_{L^{4}(\omega_{4})}^{4} + \| \mathbf{b}^{(out)} \|_{L^{4}(\omega_{4})}^{4} + \| \mathbf{U}^{[J]} \|_{L^{4}(\omega_{4})}^{4} \Big) + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2} \qquad (39)$$

$$\leq c \Big(\| \mathbf{V}^{[J]} \|_{W^{1,2}(\omega_{4})}^{4} + \| \mathbb{F} \|^{4} \Big) + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2} \leq c \Big(\sum_{j=0}^{N} |F_{j}| \Big)^{4} + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2} \\ \leq c \| \mathbf{a} \|_{W^{1/2,2}(\partial\Omega)}^{4} + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2}.$$

Further, the straightforward calculations give the equality

$$\begin{split} \lambda \nu & \int_{\Omega_{k} \setminus \Omega_{3}} \nabla \mathbf{A}_{2} \cdot \nabla \mathbf{v}_{k}^{(\lambda)} dx + \lambda \int_{\Omega_{k} \setminus \Omega_{3}} (\mathbf{A}_{2} \cdot \nabla) \mathbf{A}_{2} \cdot \mathbf{v}_{k}^{(\lambda)} dx + \lambda \int_{\Omega_{k} \setminus \Omega_{3}} \nabla ((1-\zeta) P^{[J]}) \cdot \mathbf{v}_{k}^{(\lambda)} dx \\ &= \lambda \nu \int_{\Omega_{k} \setminus \Omega_{3}} \nabla ((1-\zeta) \mathbf{U}^{[J]}) \cdot \nabla \mathbf{v}_{k}^{(\lambda)} dx + \lambda \int_{\Omega_{k} \setminus \Omega_{3}} ((1-\zeta) \mathbf{U}^{[J]} \cdot \nabla) ((1-\zeta) \mathbf{U}^{[J]}) \cdot \mathbf{v}_{k}^{(\lambda)} dx \\ &\quad + \lambda \int_{\Omega_{k} \setminus \Omega_{3}} \nabla ((1-\zeta) P^{[J]}) \cdot \mathbf{v}_{k}^{(\lambda)} dx \\ &= \lambda \int_{\Omega_{k} \setminus \Omega_{4}} \left(-\nu \Delta \mathbf{U}^{[J]} + (\mathbf{U}^{[J]} \cdot \nabla) \mathbf{U}^{[J]} + \nabla P^{[J]} \right) \cdot \mathbf{v}_{k}^{(\lambda)} dx \\ &\quad + \lambda \nu \int_{\omega_{3}} \left(-(1-\zeta) \Delta \mathbf{U}^{[J]} + 2\nabla \zeta \cdot \nabla \mathbf{U}^{[J]} + \zeta'' \mathbf{U}^{[J]} \right) \cdot \mathbf{v}_{k}^{(\lambda)} dx \\ &\quad + \lambda \int_{\omega_{3}} \left(-P^{[J]} \nabla \zeta + (1-\zeta) \nabla P^{[J]} \right) \cdot \mathbf{v}_{k}^{(\lambda)} dx \\ &\quad + \lambda \int_{\omega_{3}} \left((1-\zeta)^{2} (\mathbf{U}^{[J]} \cdot \nabla) \mathbf{U}^{[J]} \cdot \mathbf{v}_{k}^{(\lambda)} - (1-\zeta) (\mathbf{U}^{[J]} \cdot \nabla) \zeta (\mathbf{U}^{[J]} \cdot \mathbf{v}_{k}^{(\lambda)}) \right) dx = \lambda \sum_{k=1}^{4} J_{k}. \end{split}$$

Because the asymptotic decomposition $(\mathbf{U}^{[J]}, P^{[J]})$ satisfies Equation (8), by (9), we obtain

$$\lambda J_{1} = \lambda \int_{\Omega_{k} \setminus \Omega_{4}} \left(-\nu \Delta \mathbf{U}^{[J]} + (\mathbf{U}^{[J]} \cdot \nabla) \mathbf{U}^{[J]} + \nabla P^{[J]} \right) \cdot \mathbf{v}_{k}^{(\lambda)} dx = \lambda \int_{\Omega_{k} \setminus \Omega_{4}} \mathbf{H}^{[J]} \cdot \mathbf{v}_{k}^{(\lambda)} dx$$

$$\leq c \int_{\Omega_{k} \setminus \Omega_{4}} |\mathbf{H}^{[J]}|^{2} dx + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2} \leq c \left(|\mathbb{F}|^{2} + |\mathbb{F}|^{4} \right) + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2}$$

$$\leq c \left(\|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{4} \right) + \varepsilon \| \nabla \mathbf{v}_{k}^{(\lambda)} \|_{L^{2}(\Omega_{k})}^{2}.$$
(40)

The integrals J_k , k = 2, 3, 4, can be estimated using (7), and we get

$$\lambda(|J_2| + |J_3| + |J_4) \le c(\|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^2 + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^4) + \varepsilon \|\nabla \mathbf{v}_k^{(\lambda)}\|_{L^2(\Omega_k)}^2.$$
(41)

From (39)–(41) it follows that

$$\left|\lambda\langle \widehat{\mathbf{f}}, \mathbf{v}_{k}^{(\lambda)}\rangle_{\Omega_{k}}\right| \leq c \left(\|\mathbf{f}\|_{L^{2}(\Omega_{k})}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{4}\right) + c\varepsilon \|\nabla \mathbf{v}_{k}^{(\lambda)}\|_{L^{2}(\Omega_{k})}^{2}.$$

Substituting this estimate into (37) and choosing ε sufficiently small we obtain

$$\sum_{\Omega_{k}}^{\nu} |\nabla \mathbf{v}_{k}^{(\lambda)}|^{2} dx \leq -\lambda \int_{\Omega_{k}} (\mathbf{v}_{k}^{(\lambda)} \cdot \nabla) \mathbf{A} \cdot \mathbf{v}_{k}^{(\lambda)} dx + c \Big(\|\mathbf{f}\|_{L^{2}(\Omega_{k})}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{4} \Big).$$
(42)

The constant c in (42) is independent of k.

Consider now the integral $\lambda \int_{\Omega_k} (\mathbf{v}_k^{(\lambda)} \cdot \nabla) \mathbf{A} \cdot \mathbf{v}_k^{(\lambda)} dx = -\lambda \int_{\Omega_k} (\mathbf{v}_k^{(\lambda)} \cdot \nabla) \mathbf{v}_k^{(\lambda)} \cdot \mathbf{A} dx.$ In virtue of Lemmas 3 and 5, we have

$$\lambda \Big| \int_{\Omega_{k}} (\mathbf{v}_{k}^{(\lambda)} \cdot \nabla) \, \mathbf{v}_{k}^{(\lambda)} \cdot (\mathbf{b}^{(inn)} + \zeta \mathbf{b}^{(out)}) dx \Big|$$

$$\leq \|\mathbf{v}_{k}^{(\lambda)}\|_{L^{4}(\Omega_{k})} \|\nabla \mathbf{v}_{k}^{(\lambda)}\|_{L^{2}(\Omega_{k})} \left(\|\mathbf{b}^{(inn)}\|_{L^{4}(\Omega_{4})} + \|\mathbf{b}^{(out)}\|_{L^{4}(\Omega_{4})} \right)$$

$$\leq c \sum_{i=0}^{N} |F_{i}| \|\nabla \mathbf{v}_{k}^{(\lambda)}\|_{L^{2}(\Omega_{k})}^{2}.$$
(43)

By (<mark>26</mark>),

$$\lambda \left| \int_{\Omega_k} \left(\mathbf{v}_k^{(\lambda)} \cdot \nabla \right) \mathbf{V}^{[J]} \cdot \mathbf{v}_k^{(\lambda)} dx \right| \le \| \mathbf{v}_k^{(\lambda)} \|_{L^4(\Omega_k)}^2 \| \nabla \mathbf{V}^{[J]} \|_{L^2(\omega_4)} \le c \sum_{i=0}^N |F_i| \| \nabla \mathbf{v}_k^{(\lambda)} \|_{L^2(\Omega_k)}^2.$$
(44)

For the integral $\lambda \int_{\Omega_k} (\mathbf{v}_k^{(\lambda)} \cdot \nabla) \mathbf{v}_k^{(\lambda)} \cdot \mathbf{U}^{([J]}(1-\zeta) dx$ inequalities (7) and (5) yield

$$\lambda \left| \int_{\Omega_{k} \setminus \Omega_{3}} \left(\mathbf{v}_{k}^{(\lambda)} \cdot \nabla \right) \mathbf{v}_{k}^{(\lambda)} \cdot \mathbf{U}^{([J]}(1-\zeta) dx \right| \leq \left(\int_{\Omega_{k} \setminus \Omega_{3}} |\mathbf{v}_{k}^{(\lambda)}|^{2} |\mathbf{U}^{([J]}|^{2} dx \right)^{1/2} \|\nabla \mathbf{v}_{k}^{(\lambda)}\|_{L^{2}(\Omega_{k})}$$

$$\leq c \|\mathbb{F}| \left(\int_{h_{k} - \varphi(x_{2})}^{h_{3}} \frac{|\mathbf{v}_{k}^{(\lambda)}|^{2}}{\varphi^{2}(x_{2})} dx_{1} dx_{2} \right)^{1/2} \|\nabla \mathbf{v}_{k}^{(\lambda)}\|_{L^{2}(\Omega_{k})} \leq c \sum_{i=0}^{N} \|F_{i}\| \|\nabla \mathbf{v}_{k}^{(\lambda)}\|_{L^{2}(\Omega_{k})}^{2}.$$

$$(45)$$

Finally, using Leray–Hopf's inequality (23), we estimate the integral $\int_{\Omega_k} (\mathbf{v}_k^{(\lambda)} \cdot \nabla) \mathbf{b}_0 \cdot \mathbf{v}_k^{(\lambda)} dx$:

$$\int_{\Omega_k} (\mathbf{v}_k^{(\lambda)} \cdot \nabla) \mathbf{b}_0 \cdot \mathbf{v}_k^{(\lambda)} dx \le c_0 \varepsilon \int_{\Omega_k} |\nabla \mathbf{v}_k^{(\lambda)}|^2 dx.$$
(46)

Estimates (43)-(46) yield the inequality

$$\lambda \int_{\Omega_{k}} \left(\mathbf{v}_{k}^{(\lambda)} \cdot \nabla \right) \mathbf{A} \cdot \mathbf{v}_{k}^{(\lambda)} dx \leq \left(c_{0}\varepsilon + c_{*} \sum_{i=0}^{N} |F_{i}| \right) \int_{\Omega_{k}} |\nabla \mathbf{v}_{k}^{(\lambda)}|^{2} dx \quad \forall \lambda \in [0, 1],$$
(47)

where the constants c_0 and c_* are independent of k and λ . Thus, estimate (42) takes the form

$$\frac{\nu}{2} \int\limits_{\Omega_k} |\nabla \mathbf{v}_k^{(\lambda)}|^2 dx \leq \left(c_0 \varepsilon + c_* \mathcal{F}_0\right) \int\limits_{\Omega_k} |\nabla \mathbf{v}_k^{(\lambda)}|^2 dx + c \left(\|\mathbf{f}\|_{L^2(\Omega)}^2 + \|\mathbf{a}\|_{W^{1/22}(\partial\Omega)}^2 + \|\mathbf{a}\|_{W^{1/22}(\partial\Omega)}^4\right).$$

Choosing ε sufficiently small, say $\varepsilon = \frac{\nu}{8c_0}$ and assuming that $\mathcal{F}_0 = \frac{\nu}{8c_*}$ from the last inequality we derive

$$\frac{\nu}{2} \int_{\Omega_k} |\nabla \mathbf{v}_k^{(\lambda)}|^2 dx \le c \Big(\|\mathbf{f}\|_{L^2(\Omega)}^2 + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^2 + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^4 \Big).$$

So, the norms $\|\nabla \mathbf{v}_k^{(\lambda)}\|_{L^2(\Omega_k)}^2$ of all possible solutions $\mathbf{v}_k^{(\lambda)}$ of operator Equation (35) are bounded by a constant independent of $\lambda \in [0, 1]$ and, according to the Leray–Schauder theorem, operator Equation (34) has at least one solution $\mathbf{v}_k \in H(\Omega_k)$. Moreover, for \mathbf{v}_k holds estimate (33). \Box

Theorem 2. Suppose that the conditions of Theorem 1 are fulfilled. Then problem (29) admits a solution $\mathbf{v} \in H(\Omega)$ satisfying the following estimate

$$\|\nabla \mathbf{v}\|_{L^{2}(\Omega)}^{2} \leq c \Big(\|\mathbf{f}\|_{L^{2}(\Omega)}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{2} + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{4} \Big).$$
(48)

Proof. Let us take the sequence of solutions \mathbf{v}_k constructed in Theorem 1. Extending \mathbf{v}_k by zero into $\Omega \setminus \Omega_k$ we get vector fields $\tilde{\mathbf{v}}_k \in H(\Omega)$. Notice that $\tilde{\mathbf{v}}_k$ satisfy integral identity (31) in which we can integrate over the domain Ω instead of Ω_k . Taking an arbitrary function $\eta \in J_0^{\infty}(\Omega)$ we can find a number k such that $\operatorname{supp} \eta \subset \Omega_k$. Since the sequence $\{\tilde{\mathbf{v}}_k\}$ is bounded in $H(\Omega)$, there exists a subsequence $\{\tilde{\mathbf{v}}_{k_m}\}$ which converges weakly in the space $H(\Omega)$ and converges strongly in $L^4(\Omega_k)$ for any k, as the embedding $H(\Omega_k) \hookrightarrow L^4(\Omega_k)$ is compact. Such subsequence constructed using Cantor's diagonal argument. Then we can pass to the limit as $k_m \to \infty$ in integral identity (31) taking any test function $\eta \in J_0^{\infty}(\Omega)$. For the limit function $\mathbf{v} \in H(\Omega)$ we obtain the integral identity (29). Obviously, the limit function \mathbf{v} obeys estimate (48). \Box

Remark 1. Since the space $J_0^{\infty}(\Omega)$ is dense in $H(\Omega)$, integral identity (29) remains valid for every test function $\eta \in H(\Omega)$.

Let us prove now the uniqueness of the solution to problem (1) having representation (28).

Theorem 3. Let $\mathbf{a} \in W^{1/2,2}(\partial\Omega)$, $\mathbf{f} \in L^2(\Omega)$ and let the boundary value \mathbf{a} satisfies the conditions of Theorem 1, in particular, the fluxes F_i , i = 0, 1, ..., N, satisfy condition (32). Let \mathbf{u}_1 and \mathbf{u}_2 be two solutions of problem (1) admitting representation (28): $\mathbf{u}_i = \mathbf{A} + \mathbf{v}_i$, i = 1, 2, with $\mathbf{v}_i \in H(\Omega)$. There exists a number $a_0 > 0$ such that if

$$\|\nabla \mathbf{v}_2\|_{L^2(\Omega)} \le a_0,\tag{49}$$

then the solutions \mathbf{u}_1 and \mathbf{u}_2 coincide.

Proof. Suppose problem (1) has two solutions \mathbf{u}_1 and \mathbf{u}_2 admitting representation (28), i.e., $\mathbf{u}_1 = \mathbf{A} + \mathbf{v}_1$, $\mathbf{u}_2 = \mathbf{A} + \mathbf{v}_2$, where $\mathbf{v}_1, \mathbf{v}_2 \in H(\Omega)$ and satisfy integral identity (29). Denote $\mathbf{v} = \mathbf{u}_1 - \mathbf{u}_2 = \mathbf{v}_1 - \mathbf{v}_2 \in H(\Omega)$. Subtracting integral identity (29) for \mathbf{v}_2 from the one for \mathbf{v}_1 we obtain

$$\nu \int_{\Omega} \nabla \mathbf{v} \cdot \nabla \boldsymbol{\eta} \, dx + \int_{\Omega} (\mathbf{v}_1 \cdot \nabla) \mathbf{v} \cdot \boldsymbol{\eta} \, dx + \int_{\Omega} (\mathbf{v} \cdot \nabla) \mathbf{v}_2 \cdot \boldsymbol{\eta} \, dx + \int_{\Omega} (\mathbf{A} \cdot \nabla) \mathbf{v} \cdot \boldsymbol{\eta} \, dx + \int_{\Omega} (\mathbf{v} \cdot \nabla) \mathbf{A} \cdot \boldsymbol{\eta} \, dx = 0 \quad \forall \boldsymbol{\eta} \in H(\Omega).$$
(50)

Taking in (50) η = **v** yields

$$\nu \int_{\Omega} |\nabla \mathbf{v}|^2 dx = -\int_{\Omega} (\mathbf{v} \cdot \nabla) \mathbf{v}_2 \cdot \mathbf{v} dx - \int_{\Omega} (\mathbf{v} \cdot \nabla) \mathbf{A} \cdot \mathbf{v} dx.$$
(51)

The integral $\int_{\Omega} (\mathbf{v} \cdot \nabla) \mathbf{A} \cdot \mathbf{v} dx$ admits the estimate

$$\left|\int_{\Omega} \left(\mathbf{v} \cdot \nabla\right) \mathbf{A} \cdot \mathbf{v} dx\right| \leq \left(c_0 \varepsilon + c_* \sum_{i=0}^{N} |F_i|\right) \int_{\Omega} |\nabla \mathbf{v}|^2 dx \leq \left(c_0 \varepsilon + c_* \mathcal{F}_0\right) \int_{\Omega} |\nabla \mathbf{v}|^2 dx$$

see (47), (32), and

$$\left|\int_{\Omega} (\mathbf{v} \cdot \nabla) \mathbf{v}_{2} \cdot \mathbf{v} dx\right| \leq \|\mathbf{v}\|_{L^{4}(\Omega)}^{2} \|\nabla \mathbf{v}_{2}\|_{L^{2}(\Omega)} \leq c_{1} a_{0} \int_{\Omega} |\nabla \mathbf{v}|^{2} dx$$

Then from (51) it follows

$$u \int_{\Omega} |\nabla \mathbf{v}|^2 dx \leq \left(c_0 \varepsilon + c_* \mathcal{F}_0 + c_1 a_0 \right) \int_{\Omega} |\nabla \mathbf{v}|^2 dx.$$

Remind that \mathcal{F}_0 is equal to $\frac{\nu}{8c_*}$ (see the proof of Theorem 1). Taking $\varepsilon = \frac{\nu}{8c_0}$ and assuming that $a_0 = \frac{\nu}{4c_1}$ we get

$$\frac{\frac{\nu}{2}}{\Omega}\int_{\Omega}|\nabla\mathbf{v}|^{2}\,dx\leq0.$$

Thus, $\mathbf{v}_1 = \mathbf{v}_2$. \Box

Remark 2. If v_2 satisfies estimate (48), that is

$$\|\nabla \mathbf{v}_2\|_{L^2(\Omega)}^2 \le c \Big(\|\mathbf{f}\|_{L^2(\Omega)}^2 + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^2 + \|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^4 \Big),$$

then (49) follows from the condition

$$c\Big(\|\mathbf{f}\|_{L^{2}(\Omega)}^{2}+\|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{2}+\|\mathbf{a}\|_{W^{1/2,2}(\partial\Omega)}^{4}\Big) \leq a_{0}^{2}$$

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