

Correction

Correction: Phan Thi et al. Secure Communication of Electric Drive System Using Chaotic Systems Base on Disturbance Observer and Fuzzy Brain Emotional Learning Neural Network. *Math. Comput. Appl.* 2025, 30, 73

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In the original publication [1], incorrect versions of Figures 7, 11, 12, 16, 17 and 21 were published. The original figures presented results with wrong experimental durations. The corrected Figures 7, 11, 12, 16, 17 and 21 are provided below. Additionally, some spelling errors have been corrected, and Figure 2 has been replaced with a higher-resolution version. The authors confirm that this correction does not affect the results or the scientific conclusions of the paper. The authors apologize for the error and any inconvenience caused. This correction was approved by the Academic Editor. The original publication has also been updated.

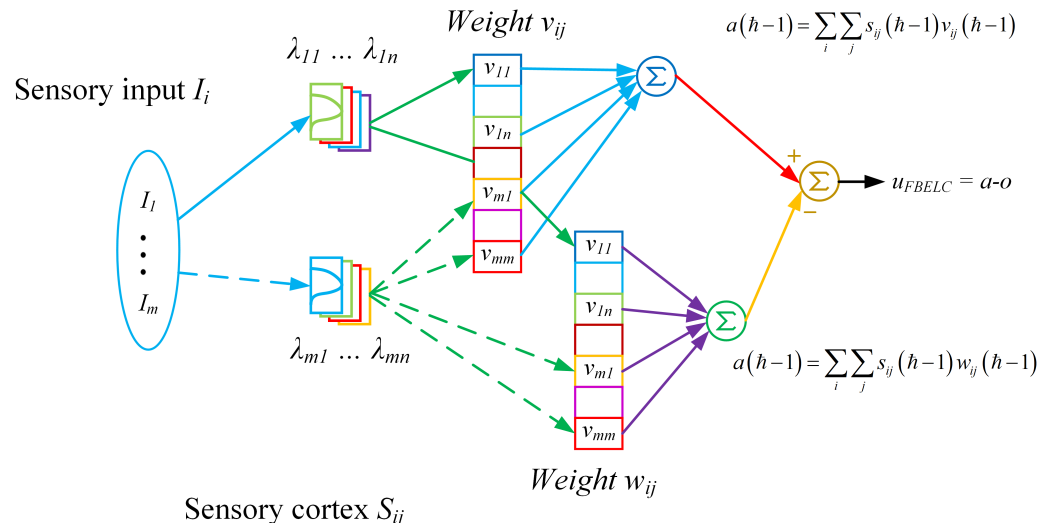


Figure 2. Structure of fuzzy brain emotional learning.



Received: 16 October 2025
Accepted: 16 October 2025
Published: 30 October 2025

Citation: Phan Thi, H.C.; Dang, N.Q.; Giap, V.N. Correction: Phan Thi et al. Secure Communication of Electric Drive System Using Chaotic Systems Base on Disturbance Observer and Fuzzy Brain Emotional Learning Neural Network. *Math. Comput. Appl.* 2025, 30, 73. *Math. Comput. Appl.* **2025**, 30, 118. <https://doi.org/10.3390/mca30060118>

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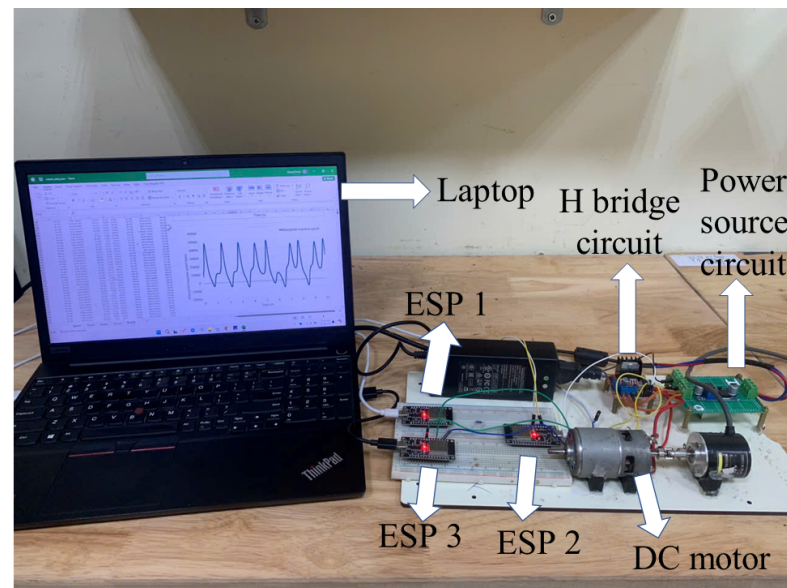


Figure 7. Experimental setup.

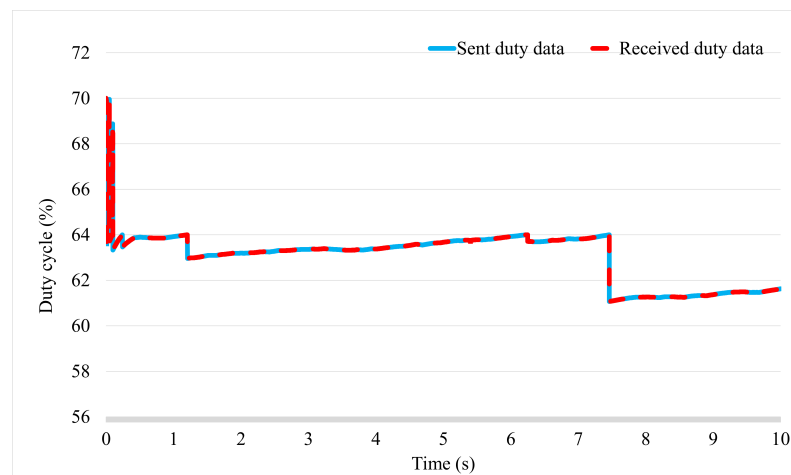


Figure 11. Original and decrypted control signal.

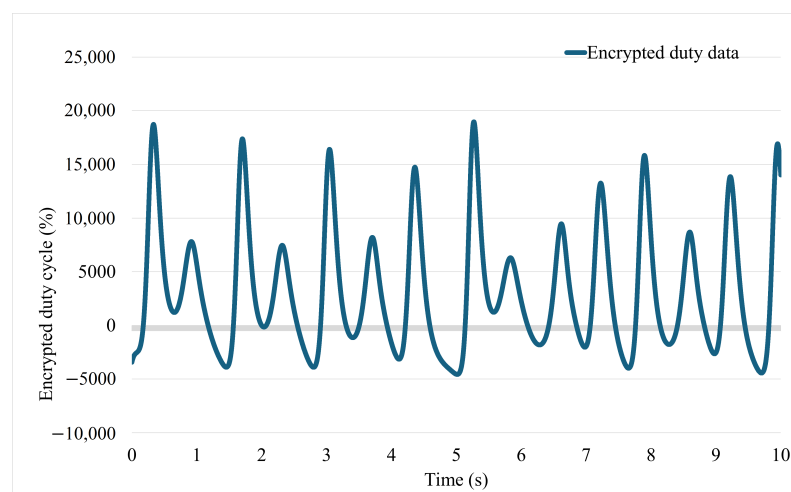


Figure 12. Encrypted control signal.

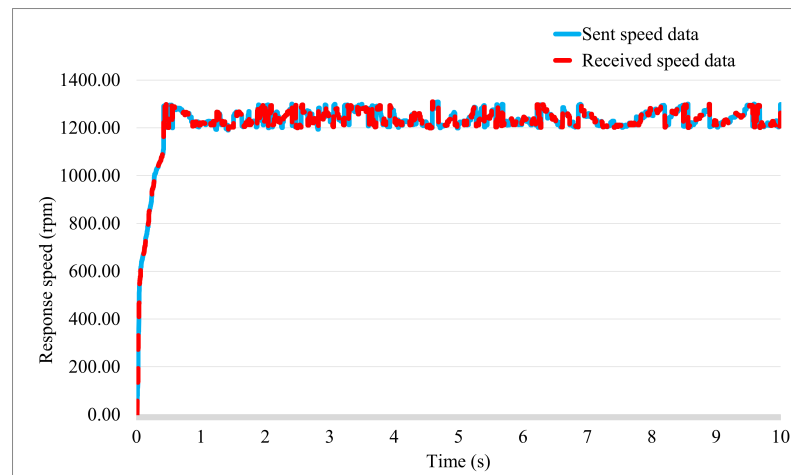


Figure 16. Original and decrypted response speed signal.

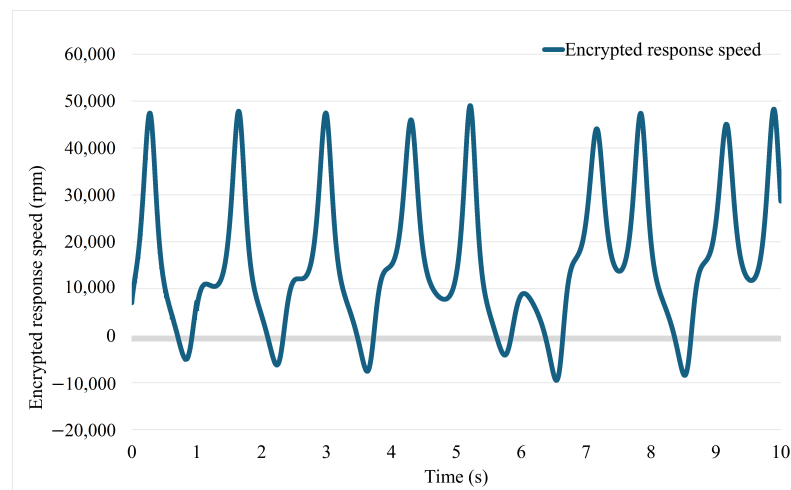


Figure 17. Encrypted response speed signal.

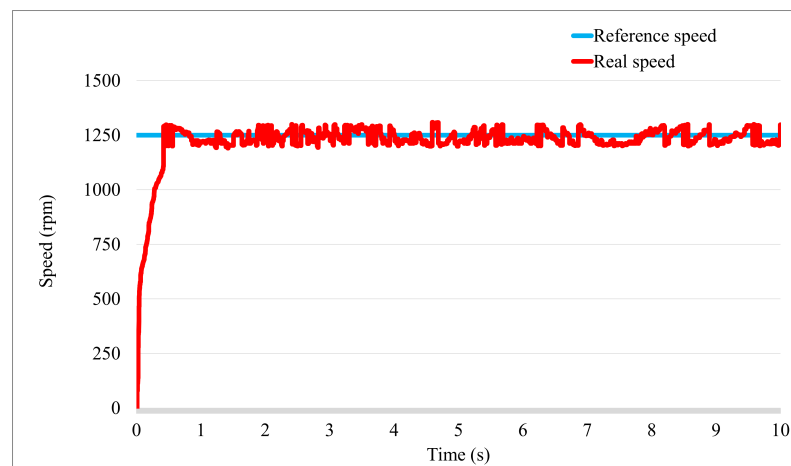


Figure 21. PI controller's performance.

Reference

1. Phan Thi, H.C.; Dang, N.Q.; Giap, V.N. Secure Communication of Electric Drive System Using Chaotic Systems Base on Disturbance Observer and Fuzzy Brain Emotional Learning Neural Network. *Math. Comput. Appl.* **2025**, *30*, 73. [[CrossRef](#)]

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