Retraction


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*Remote Sensing* retracts the article “Robot Path Planning Method Based on Indoor Spacetime Grid Model” [1].

Following publication, the authors contacted the Editorial Office regarding concerns relating to the ownership of the data presented in this article [1].

Adhering to our complaint’s procedure, an investigation was conducted by the Editorial Office and Editorial Board, which confirmed with the Aerospace Information Engineering Research Center of Peking University that the presented data were subject to a confidentiality agreement with a third party and that appropriate permission had not been gained. As a result, the Editorial Office, Editorial Board, and authors have decided to retract this article as per MDPI’s retraction policy (https://www.mdpi.com/ethics#_bookmark30) and in line with the Committee on Publication Ethics (COPE) retraction guidelines (https://publicationethics.org/retraction-guidelines).

This retraction was approved by the Editor-in-Chief of the journal *Remote Sensing*. The authors agreed to this retraction.

Reference


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