

Retraction

RETRACTED: Abdallah, I.B.; Bouteraa, Y. A Newly-Designed Wearable Robotic Hand Exoskeleton Controlled by EMG Signals and ROS Embedded Systems. *Robotics* 2023, 12, 95

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The *Robotics* Editorial Office retracts the article, “A Newly Designed Wearable Robotic Hand Exoskeleton Controlled by EMG Signals and ROS Embedded Systems” [1] cited above.

Following publication, the Editorial Office was made aware of concerns relating to overlap between this article [1] and a previously published article [2].

Adhering to our complaints procedure, an investigation was conducted by the Editorial Office and the Editorial Board, which confirmed the significant overlap between this article [1] and the previously published article [2] with a different authorship group and without appropriate citation. This overlap included a number of overlapping figures and tables, as well as significant similarities in the analysis of the samples. Therefore, the *Robotics* Editorial Office and Editorial Board have taken the decision to retract this article [1] as per MDPI's retraction policy (https://www.mdpi.com/ethics#_bookmark30, accessed on 16 January 2024).

This retraction was approved by the Editor-in-Chief of the journal *Robotics*.

The authors disagree with the retraction.



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1. Abdallah, I.B.; Bouteraa, Y. RETRACTED: A Newly-Designed Wearable Robotic Hand Exoskeleton Controlled by EMG Signals and ROS Embedded Systems. *Robotics* 2023, 12, 95. [[CrossRef](#)]
2. Arteaga, M.V.; Castiblanco, J.C.; Mondragon, I.F.; Colorado, J.D.; Alvarado-Rojas, C. EMG-driven hand model based on the classification of individual finger movements. *Biomed. Signal Process. Control* 2020, 58, 101834. [[CrossRef](#)]

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