Investigating the Effect of Parameters on Confinement Coefficient of Reinforced Concrete Using Development of Learning Machine Models

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Abstract: The current research aims to investigate the parameters’ effect on the confinement co-efficient, \( K_s \), forecast using machine learning. Because various parameters affect the \( K_s \), a new computational model has been developed to investigate this issue. Six parameters are among the effective parameters based on previous research. Therefore, according to the dimensions of the variables in the problem, a supply–demand-based optimization (SDO) model was developed. The performance of this model is directly dependent on its main parameters, such as market size and iteration. Then, to compare the performance of the SDO model, classical models, including particle swarm size (PSO), imperialism competitive algorithm (ICA), and genetic algorithm (GA), were used. Finally, the best-developed model used different parameters to check the uncertainty obtained. For the test results, the new SDO-ANFIS model was able to obtain values of 0.9449 and 0.134 for the coefficient of determination (R2), and root mean square error (RMSE), which performed better than other models. Due to the different relationships between the parameters, different designed conditions were considered and developed based on the hybrid model and, finally, the number of longitudinal bars and diameter of lateral ties were obtained as the strongest and weakest parameters based on the developed model for this study.

Keywords: prediction; confinement coefficient; supply–demand-based optimization; concrete technology

1. Introduction

Design procedures for reinforced concrete (R/C) structures often require ductile behavior. The ductile behavior can be provided by confining the concrete with the lateral or spiral reinforcement [1]. By implementing lateral or spiral reinforcements, the strength and ductility in the R/C increase significantly. In order to increase the strength of R/C columns, the confinement coefficient, \( K_s \), can be used. Over the past few years, many studies have been conducted to predict the confinement degree. In the proposed models, various conditions and parameters have been considered for confined concrete. Considering the concrete confined by rectangular steel hoops, Ken and Park [2] presented a stress–strain diagram. This diagram consists of three parts, including a parabola to the maximum stress point, a strongly descending linear section, and a horizontal linear section. In the horizontal section, the stress is constant and equal to 0.2 of the maximum stress. In the descending portion of the diagram, factors such as concrete cylinder strength, the width of confined concrete to the hoops distance ratio, and the ratio of hoops volume to the concrete core volume affect the line slope. Park et al. [3] developed the diagram designed by Kent and
Park [2] and improved it. Sheikh and Uzumeri [4] provided 24 short tied columns and put them under uniform axial pressure. Their main purpose of executing these experiments was to analyze the effect of different parameters on the behavior of tied columns. They stated that the most important effective factors include the tie configuration, distribution of longitudinal steel, column perimeter, longitudinal column steel, and the rate of lateral confinement. In addition, Sheikh and Uzumeri [5] proposed a stress–strain curve according to the finding of their experiments conducted on confined concrete. They concluded that the concrete strength and ductility increased as a result of the reduced tie spacing and distribution of longitudinal steel. Considering the confined concrete, Saatcioglu and Razvi [6,7] highlighted a stress–strain diagram. This diagram consists of two sections: an ascending part in the form of a parabola and a linear descending part. In the descending portion of the curve, the strain is equal to 85% of the peak stress. In another part of the diagram, a constant residual strength at the strength level of 20% has been considered. Though the above mentioned model is an analytical model, its parameters were obtained using a large quantity of experimental data. These experimental data are related to concretes where some of them have been well confined and some have been poorly confined. Additionally, in order to assess the performance of the above mentioned model, its results were compared with the results of a large number of concrete columns. According to an experimental study conducted on 65 concrete columns, Chung et al. [8] stated a strain–stress relationship. The parameters affecting this model include the concrete strength, volume ratio, confinement type of rectilinear ties, and distribution of longitudinal.

Using neural network modeling, the above mentioned behavioral models can be validated. Therefore, by the use of the experimental model proposed by Chung et al. [8], a neural network model was trained and tested. Over recent years, the use of a neural network, which is able to obtain a high level of accuracy for non-linear problems, has significantly increased [9–14]. The most important advantages of a neural network are as follows:

The neural network is developed based on experimental data, and this way, it can present appropriate solutions for different problems. New techniques have been developed to solve problems with large and complex data, based on intelligent models and metaheuristic algorithms. Various applications of these models have been highlighted in civil, mining, and petroleum engineering [15–45]. However, algorithms based on artificial neural networks (ANN), decision trees, hybrids, adaptive neuro-fuzzy inference system (ANFIS) models, among others, are recent examples of predictive models that are developing and increasing efficiency in different engineering fields [39,46]. Optimization algorithms such as particle swarm optimization (PSO), firefly algorithm, imperialistic competitive algorithm (ICA), genetic algorithm (GA), etc., are used in the development of forecasting models [47–62]. Over time and by changing the conditions, neural networks can cover these changes and match solutions. Using a neural network, theoretical, experimental, empirical data, or a combination of them, can be analyzed effectively and with sufficient accuracy [63].

In the current research, a hybrid ANFIS model was developed in order to estimate $K_s$ in the R/C rectangular columns. This was executed in order to maximize accuracy. When previous research was taken into consideration, it is possible to draw the conclusion that the $K_s$ prediction is fraught with unpredictability because of the many different parameters. As a result, there is a requirement for the development of a new model that, in addition to providing accurate forecasts, is able to evaluate the impact of various parameters. The primary objective of this study is to develop a novel hybrid-ANFIS method for predicting $K_s$. This novel algorithm, which is based on supply–demand-based optimization (SDO), will be presented as a new hybrid approach in this work. After that, its effectiveness is analyzed with the help of traditional models. Lastly, the uncertainty effect caused by the parameters is taken into account by the superior model.
2. Experimental Setting

2.1. Data

Conducting an experimental study on 65 concrete columns, Chung et al. [8] presented a strain–stress relation for confined concrete, and this way, they investigated the effect of confinement by lateral tie on the concrete columns. They considered the cross sectional area of the columns, concrete cover thickness, and longitudinal reinforced diameter, to be 600 mm, 17 mm, and 12 mm, respectively. The letters L, M, and H show the compressive strength of 20, 39, and 34 MPa for concrete, respectively (Figure 1). The letter P also shows the plain concrete column which has no bars. In order to develop a neural network, the experimental studies conducted by Chung et al. [7] were used. Some of the data related to their studies used for neural network modeling are shown in Table 1. These data include compressive strength of concrete \( f'_c \), yield strength of lateral tie \( f_{yh} \), number of longitudinal bars \( m \), spacing between lateral ties \( s \), diameter of lateral ties \( \phi_h \), volumetric ratio of lateral ties \( \rho_s \), and lateral confinement coefficient \( K_s \).

![Figure 1. Characteristics of the designed cases.](image)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>X1</th>
<th>X2</th>
<th>X3</th>
<th>X4</th>
<th>X5</th>
<th>X6</th>
<th>Y</th>
</tr>
</thead>
<tbody>
<tr>
<td>Symbol</td>
<td>m</td>
<td>( \phi_h )</td>
<td>( f'_{c} )</td>
<td>( \rho_s )</td>
<td>( f_{yh} )</td>
<td>s</td>
<td>( K_s )</td>
</tr>
<tr>
<td>Limit</td>
<td>8–12</td>
<td>6–8</td>
<td>19.6–56.4</td>
<td>0.007–0.051</td>
<td>550–1300</td>
<td>30–100</td>
<td>0.81–3.6</td>
</tr>
<tr>
<td>Unit</td>
<td>-</td>
<td>mm</td>
<td>MPa</td>
<td>-</td>
<td>MPa</td>
<td>mm</td>
<td>-</td>
</tr>
</tbody>
</table>

2.2. Previous Analytical Models

In order to assess the increased strength of R/C columns, the confinement coefficient \( K_s \) can be used. Over the past few years, many studies were used to predict the confinement degree. In the proposed models, different conditions and parameters affecting confined concrete were considered [4,6,8,64]. In the following, the studies conducted to predict lateral confinement coefficient are presented:
Park et al. [64] modified the stress–strain relation in confined concrete and obtained a new relation for passive confinement. The $K_s$ coefficient controlled this new relation. Of course, in their studies, the effect of two parameters of lateral reinforcement arrangements and the location of longitudinal reinforcement were not applied. The above mentioned relation was obtained as follows:

$$K_s = 1 + \frac{\rho_s f_{yh}}{f'_c}$$

(1)

where $\rho_s$ was obtained as follows:

$$\rho_s = \frac{A_{sh} l_s}{s b'_c d'_c}$$

(2)

In relation (2), the width and depth of the confined core (which are measured up to the external part of ties) are shown by $b'_c$ and $d'_c$, respectively. The ties center-to-center distance and the total length of lateral ties are shown by $S$ and $l_s$, respectively.

Sheikh and Uzumeri [4] conducted an experimental study on the stress–strain relation. They supposed that the $K_s$ parameter is affected by the increased strength of the concrete. An increase in the strength also occurred as a result of the concrete rectilinear reinforcement. Additionally, they applied the effect of rectilinear reinforcement in the form of square root of volumetric ratio. Using regression analysis, $K_s$ parameter was obtained as follows:

$$K_s = 1 + \frac{b_c^2}{140 P_{occ}} \left[(1 - \frac{m c_i^2}{5.5 b_c^2})(1 - \frac{s}{2b_c})^2\right] \sqrt{\rho_s f_{yh}}$$

(3)

$$P_{occ} = 0.85 f'_c (A_{ck} - A_{st})$$

(4)

In relations (3) and (4), the parameters $A_{st}, A_{ck}, c_i,$ and $m$ indicate the area of total longitudinal reinforcement. The volumetric ratio of the lateral ties’ parameter is also obtained as follows:

$$\rho_s = \frac{A_{sh} l_s}{s b'_c d'_c}$$

(5)

where the width and depth of the confined core (which is measured up to the center of ties) are shown by $b_c$ and $d_c$, respectively.

Based on their research studies, Saatcioglu and Razvi [6] concluded that passive lateral pressure was not always uniform. Therefore, the above-mentioned model was built based on the equivalent uniform pressure calculation. Actually, the effect of this pressure is similar to non-uniform confinement pressures which are created in different columns. These columns may be strengthened in different orders and structures (Figure 1). The relation related to $K_s$ calculation is as follows:

$$k_s = 1 + \frac{6.7}{f'_c} (f_{1e})^{-0.17} f_{1e}$$

(6)

In order to calculate the equivalent uniform pressure $f_{1e}$, in relation (6), the following relation was used:

$$f_{1e} = k_2 f_1 = k_2 \frac{\sum A_{sh} f_{yh} s \sin \alpha}{s b_c}$$

(7)

In relation (7), the medium lateral pressure and the angle between transverse reinforcement and $b_c$ are shown by $f_1$ and $\alpha$, respectively. The $K_2$ coefficient defined to decrease the average pressure is also shown as follows:

$$k_2 = 0.26 \sqrt{\left(\frac{b_c}{s}\right)\left(\frac{b_c}{c_i}\right)\left(\frac{1}{f_1}\right)} \leq 1$$

(8)
3. Methodology

The present methodology explains the inspiration of supply–demand-based optimization (SDO); afterwards, it provides the detailed mathematical model of SDO.

3.1. Inspiration

Based on the economic theory, within a given market, first, the commodity quantity (CQ) and commodity price (CP) may be exposed to various fluctuations; then, they may be progressively stable onto their corresponding points of equilibrium [65]. In general, this procedure is dependent upon both the producers’ supply relation and the consumers’ demand relation [66]. In a market economy, there is an economic theory which called the supply–demand mechanism (SDM) for determining the price. Based on this theory, the CQ in the next time \( q_{t+1} \), with considering its current price \( p_t \), within a market is specified by taking into account the producers’ supply relation, that is \( q_{t+1} = f(p_t) \), where \( f \) stands for a linear supply function. In a given market, with the rise of the current \( p_t \), the CQ rises in supply at the next time [66]. With the rise in the commodity quantity, its price reduces; thus, \( g \) will be a reducing function. When oscillation occurs, the two functions will be intersected eventually at a certain point \( P(x_0, y_0) \), called the equilibrium point, where \( x_0 \) and \( y_0 \). Equation (9) expresses the supply function \( f \) [66] as follows:

\[
q_{t+1} - q_0 = a(p_0 - p_t)
\]  

On the other hand, Equation (10) expresses the demand function \( g \) [61] as follows:

\[
p_{t+1} - p_0 = -b(q_{t+1} - q_0)
\]

where \( t \) stands for the time, \( a \) and \( b \) represent the linear coefficients. In general, the SDM is in two different modes: stability and instability, as can be observed in Figure 2A,B, respectively. In case \( |ab| < 1 \), the supply function \( f \) will be steeper compared to the demand function \( g \); the extent of oscillations then decreases at each time. Thus, the CP and quantity curve tends to spiral inwards with respect to time. As a result, with time passing, the price and quantity will diverge from the point of equilibrium \( (x_0, y_0) \) progressively [65]. The cobweb model is a popular theory in the economic context based on which fluctuation in price will lead to fluctuation in supply, thereby resulting in a sporadic rise or fall of price. As a result, this model has been widely applied to investigating the price fluctuations of different products in given markets.

3.2. Developing SDO

Based on the SDM, the stability mode is capable of encouraging both the CP and CQ to exploit the equilibrium-point neighborhood, and such an exploitation process oscillates in magnitude over time. However, the instability mode typically forces both the CP and CQ to progressively find new areas positioned far from the point of equilibrium. The stability mode that is slowly reducing the oscillations in the SDM is able to be simply introduced to SDO as exploitation to carry out a local search within an encouraging area. Likewise, it is also possible to lend the instability mode to SDO as exploration in such a way as to carry out a search globally within the search space. Figure 3 demonstrates converting the SDM condition to the SDO algorithm. In case this solution outperforms the candidate solution, it will be used instead of the candidate one. It is worth mentioning that the method introduced in this study is actually an algorithm that works based on a swarm optimization; as a consequence, two matrixes are provided to present the CP and commodity quantity, respectively.
3.2. Developing SDO

Based on the SDM, the stability mode is capable of encouraging both the CP and CQ to exploit the equilibrium-point neighborhood, and such an exploitation process oscillates in magnitude over time. However, the instability mode typically forces both the CP and CQ to progressively find new areas positioned far from the point of equilibrium. The stability mode that is slowly reducing the oscillations in the SDM is able to be simply introduced to SDO as exploitation to carry out a local search within an encouraging area. Likewise, it is also possible to lend the instability mode to SDO as exploration in such a way as to carry out a search globally within the search space. Figure 3 demonstrates converting the SDM condition to the SDO algorithm. In case this solution outperforms the candidate solution, it will be used instead of the candidate one. It is worth mentioning that the method introduced in this study is actually an algorithm that works based on a swarm optimization; as a consequence, two matrixes are provided to present the CP and commodity quantity, respectively.

In case the variable $L$ equals the product of $\alpha$ (supply weight) and $\beta$ (demand weight), the following relation will be achieved:

$$L = \alpha \beta = \frac{4(T - t + 1)}{T} \cdot \sin(2\pi r) \cdot \cos(2\pi r)$$  (11)
If \(|L| < 1\) corresponds to the stability mode as displayed in Figure 4A, various CP vectors around the equilibrium price \(x_0\) are achieved considering the current price vector through the adjustment of the weights \(\alpha\) and \(\beta\). In this case, we can indicate that with the help of this algorithm, each market will be capable of updating all of its CPs in the neighborhood of the current CPs and mimicking the stability mode depicted in Figure 2A. Such a mechanism puts a focus on exploitation and gives the SDO algorithm encouragement for searching at a local level. As can be observed in Figure 4B, \(|L| > 1\) corresponds to the instability mode, which makes the CP vector within any market capable of moving to make a simulation of the instability mode displayed in Figure 2B. Such a mechanism is concentrated upon exploration, and because of this mechanism, SDO has to perform a global search.

![Figure 4](image_url)

**Figure 4.** The two modes of SDO (a) stability; (b) instability.

Figure 5 displays the values of the variable \(L\) over iterations, where \(T\) is fixed at 1000. As the figure demonstrates, in the initial iterations, the \(L\) values are \(L > 1\) or \(L < -1\) with a high probability. With the rise of the iterations, such high probability starts to drop, and an increasing probability exists, indicating that the \(L\) function values are in the interval of \([-1, 1]\). In the following iterations, the \(L\) values are in the interval of \([-1, 1]\) with an increasingly high probability. It is obvious that in the primary stage of iterations, SDO achieves high exploration and then switches smoothly to high exploitation.

![Figure 5](image_url)

**Figure 5.** The distribution of the \(L\) parameter.

When both the CP and CQ vectors get updated in each iteration, they are assessed using their corresponding arrays. In case the fitness value of the \(i\)th CQ vector is better than
the fitness value of the ith CP vector, the ith CP vector is changed with this quantity vector as a chosen solution. The mechanism of this solution replacement is depicted in Figure 6.

The optimization process is started by SDO through forming a set of markets in a random way. At each iteration of this process, both the equilibrium quantity and the equilibrium price are taken into consideration to update each CQ of a market. After that, the equilibrium price is considered to update each CP of a market. It is possible to switch the equilibrium price vector in a random way between a selected CP vector from the price array on the basis of CP vectors. The CPs and CQs are updated in this way through the adjustment of the weights' values of both $\alpha$ and $\beta$. For the purpose of performing either exploration or exploitation, the L values are reduced linearly with a random fluctuation. The CPs of a market are inclined with the aim of diverging from the equilibrium price in cases where $|L| > 1$, while they converge toward the equilibrium price in the case where $|L| < 1$. Afterwards, the fitness function is employed in order to assess the updated price vectors and quantity vectors. For every market, when the fitness value of its CQs is better than the fitness value of its CPs, its commodity quantities are used instead of its CPs as a candidate solution. Finally, once the termination criterion is met, the optimum CP vector of a market is returned as the optimal solution explored.

4. Simulation Procedure
4.1. Pre-Training

The input variables are the most important factor affecting the accuracy of a computing model. In order to predict $K_s$ (model output) in the RC columns, six parameters were considered in the input layer of the neural network. Based on the experimental studies conducted in the past years [67–69], the above mentioned six parameters were selected as the most important factors affecting $K_s$. The value variation range of these parameters is shown in Table 1. In order to compute the model, a total of 59 pieces of data were used, and their details are given in Table 1. The above mentioned 59 pieces of data (including $K_s$ and the six parameters affecting them) were divided into two groups. Among them, the first 48 cases were considered for the training of the network (training data). The other ones, including the remaining data, were used to assess the neural network performance (testing data). In fact, 20% of the whole data, including 11 pieces of data that were selected randomly,
were considered to test the model in each training stage. In order to investigate the pre-training of the main models, an analysis was implemented on different combinations of data to evaluate the $K_s$ parameter. Table 2 shows the main combinations of these data for designing computational models. This analysis helps to investigate the effect of parameters on the model structure and its performance in predicting the $K_s$ parameter at each stage. Figure 7 shows the results of this analysis in which the least error is related to the G14.

### Table 2. The main combinations of data.

<table>
<thead>
<tr>
<th>Group</th>
<th>X1</th>
<th>X2</th>
<th>X3</th>
<th>X4</th>
<th>X5</th>
<th>X6</th>
<th>Y</th>
</tr>
</thead>
<tbody>
<tr>
<td>G1</td>
<td>*</td>
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<td></td>
<td>*</td>
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<tr>
<td>G2</td>
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<td>*</td>
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<td>G3</td>
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<td>G5</td>
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</tbody>
</table>

Figure 7. The 14 selected combinations to analyze the effect of parameters on output.
4.2. ANFIS

The ANFIS base structure is based on an extended fuzzy inference system (FIS)-based model. For better implementation of the structure, the ANFIS model uses the BP learning method. This method allows the membership function (MF) parameters of the FIS to develop different stages based on conditional rules (“if–then”) [70]. These laws, which are based on the theory of Takagi and Sugeno fuzzy type, include different elements such as the middle layers, input, and output layers that are mentioned in Figure 8.

![Figure 8. A view of the ANFIS structure.](image)

The ANFIS structure in this research is developed and implemented from the BP algorithm based on the gradient descent (steepest descent) approach and finally, it is implemented to predict the $K_s$ parameter. In the first step, the various parameters of the ANFIS model are determined for the optimal design of its structure based on previous research. With trial and error methods, the process continues until the best conditions are obtained. The results of the initial structure are presented in Table 3. Due to the existing conditions, the gradient descent method sometimes gets stuck in local minima, and optimization methods are used to solve this problem or to reduce it, to achieve more favorable results. Therefore, the model structure of this section is designed and developed based on two optimization algorithms in order to improve the performance of prediction models for $K_s$ parameters.

### Table 3. The performance of initial ANFIS and its optimum structure.

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Input MF Type</th>
<th>No. of Nonlinear Parameters</th>
<th>No. of MFs for Each Input</th>
<th>No. of Fuzzy Rules</th>
<th>No. of Linear Parameters</th>
<th>Output MF Type</th>
<th>No. of Output MFs</th>
<th>$R^2$ Training</th>
<th>$R^2$ Testing</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specification</td>
<td>Gaussian</td>
<td>100</td>
<td>6</td>
<td>8</td>
<td>100</td>
<td>Linear</td>
<td>8</td>
<td>0.8961</td>
<td>0.8821</td>
</tr>
</tbody>
</table>

4.3. SDO-ANFIS

According to the structure of the SDO optimization algorithm, the algorithm can provide suitable solutions for the problem by using two steps of searching and extracting the answer. According to this solution, a hybrid method between the optimization algorithm and the basic model called SDO-ANFIS was developed in this research. This new combination can prevent the model from getting stuck in local minima and determine the best structure minima. In addition, the SDO algorithm has wider capabilities and simpler parameters that can achieve the optimal conditions of the problem. This search process comes with the help of the ANFIS base model. By improving the performance of ANFIS functions, the performance of models for $K_s$ prediction increases. In other words, the higher the power of the optimization algorithm in this new combination, the more accurate the optimal structure will be. In the following, more details about parameters of the SDO
algorithm are discussed and implemented to finalize the structure with higher accuracy and less error.

In this section, three other types of classical algorithms are used to evaluate the performance of the new SDO-ANFIS hybrid model. These algorithms, which include GA, PSO, and ICA, are examined under different conditions to provide the best assessment to solve the iron price-prediction problem. The two key parameters for the SDO algorithm are the number of iterations and the market size. Due to the fact that each algorithm has different functions in different conditions, the best mode is provided by trial and error method and design of different models. In Table 4, the results of the models in the optimal state of their coefficients are obtained. In all models, the number of iteration was considered to be 400.

Table 4. Prediction values of $K_s$ using various hybrid-ANFIS Models.

<table>
<thead>
<tr>
<th>Hybrid Models</th>
<th>Train</th>
<th>Test</th>
<th>Key Parameters</th>
<th>Coefficient Values</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$R^2$</td>
<td>RMSE</td>
<td>$R^2$</td>
<td>RMSE</td>
</tr>
<tr>
<td>GA-ANFIS</td>
<td>0.9341</td>
<td>0.129</td>
<td>0.9183</td>
<td>0.172</td>
</tr>
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<td></td>
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<tr>
<td>PSO-ANFIS</td>
<td>0.9229</td>
<td>0.144</td>
<td>0.9019</td>
<td>0.206</td>
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<tr>
<td>ICA-ANFIS</td>
<td>0.9302</td>
<td>0.132</td>
<td>0.9217</td>
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<tr>
<td>SDO-ANFIS</td>
<td>0.9501</td>
<td>0.126</td>
<td>0.9449</td>
<td>0.134</td>
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The results of Table 4 indicate that the performance of hybrid models is acceptable, and they can make a good assessment of the $K_s$. The new SDO-ANFIS model offers better results than other hybrid models. This high capability represents a successful new model for problem solving. Given this, it can be noted that the SDO-ANFIS model for training and testing data shows high flexibility. The results of all hybrid models are given in Figures 9–16.

Figure 9. The result of GA-ANFIS model for training data.
Given this, it can be noted that the SDO-ANFIS model for training and testing data shows high flexibility. The results of all hybrid models are given in Figures 9–16.

Figure 9. The result of GA-ANFIS model for training data.

Figure 10. The result of GA-ANFIS model for testing data.

Figure 11. The result of PSO-ANFIS model for training data.

Figure 12. The result of PSO-ANFIS model for testing data.
Figure 12. The result of PSO-ANFIS model for testing data.

Figure 13. The result of ICA-ANFIS model for training data.
5. Results and Discussion

The effect of the parameters in determining the $K_s$ is one of the most important parts of this area. In order to investigate the effect of each of the input parameters on the network output, the sensitivity analysis was used. The sensitivity analysis allows for making the network smaller by removing the less effective and unimportant inputs. Given that interactions are seen in the data, it is impossible to determine each effect in the ordinary way. Therefore, in this section, using the superior model of the previous step (SDO-ANFIS), the effect of these parameters on and their uncertainty that have a final result are discussed. Figure 17 shows the effect of 6 parameters on the $K_s$. As can be seen, these

**Figure 14.** The result of ICA-ANFIS model for testing data.

**Figure 15.** The result of SDO-ANFIS model for training data.
5. Results and Discussion

The effect of the parameters in determining the $K_s$ is one of the most important parts of this area. In order to investigate the effect of each of the input parameters on the network output, the sensitivity analysis was used. The sensitivity analysis allows for making the network smaller by removing the less effective and unimportant inputs. Given that interactions are seen in the data, it is impossible to determine each effect in the ordinary way. Therefore, in this section, using the superior model of the previous step (SDO-ANFIS), the effect of these parameters on and their uncertainty that have a final result are discussed. Figure 17 shows the effect of 6 parameters on the $K_s$. As can be seen, these parameters are one of the most important indicators affecting the $K_s$, and different effects cause uncertainty in them. The best parameter that has the most impact on the $K_s$ is the X2 ($\varphi_h$) parameter while X1 (m) was the least effective parameter (0.2). In real conditions, the $f_yh$ (X5) parameter strongly affects $K_s$. However, as in this research only four different values of $f_yh$, i.e., 500 MPa, 550 MPa, 900 MPa, and 1300 MPa, are considered to construct SDO-ANFIS, $f_yh$ showed a small effect. These parameters, because there are interdependencies between them, make it impossible to provide an accurate percentage. Therefore, the developed SDO-ANFIS model is used to check the uncertainty of the parameters. These results also show that due to the different uncertainties between the parameters, the best case should be determined based on important indicators.

Finally, a comparison between the results of the testing data using the four hybrid models is presented in Figure 18. In this figure, the difference between actual and predicted data is given. According to this figure, in four of the models, the least error belonged to the SDO-ANFIS model. In addition, as can be seen, the difference between the actual and predictive data in the SDO-ANFIS model is a definite range, while in other models, the results are seen with more discrepancies. This confirms that the model developed in this research has a lower error rate and can predict the $K_s$ parameter more reliably than other models.
ANFIS model was performed using the new supply–demand-based optimization (SDO) algorithm. New optimization algorithms, new machine learning models, can be used for other engineering problems to identify influential parameters, find significant parameters.

**Figure 18.** The difference between actual and predicted data.

### 6. Conclusions

In this study, using artificial intelligence models, the $K_s$ was estimated. Due to the importance of this issue, the main and influential factors for the design of intelligent systems were collected. After implementing the basic models, the development of the ANFIS model was performed using the new supply–demand-based optimization (SDO) algorithm. This new model performed well compared to the base model. The SDO-ANFIS was also investigated against metaheuristic algorithms, PSO, ICA, and GA. In order to train the hybrid model, 48 pieces of data were considered. A total of 11 pieces of data were also used to test the model. According to the conducted analyses, the following items can be concluded:

- Among the 14 different combinations, the data that included six inputs had less errors;
- Using the model developed in this research and according to the six input parameters, an exact estimation of $K_s$ can be obtained. The experimental data are the main source for the hybrid model training. The quality and quantity of these data thus directly affect the hybrid model performance. In fact, the hybrid model error reduces as the volume of data increases;
- The results of the ANFIS base model for the training and testing sections were $R^2 = 0.8961$ and 0.8821, respectively, and with the development of the model with the SDO algorithm, their accuracy increased to 0.9501 and 0.9449, respectively;
- The results show that the RMSE of hybrid models provide more appropriate values in predicting the $K_s$ in comparison with the basic ANFIS. For the test results, the new SDO-ANFIS model obtained values of RMSE = 0.134, which performed better than other models. Therefore, the SDO-ANFIS model has higher accuracy and less error than other hybrid models for $K_s$ prediction.

The best parameter that has the most impact on the $K_s$ is the $x_2 (\phi_h)$ parameter while $x_1 (m)$ was the least effective parameter. The methodology implemented in this research can be used for other engineering problems to identify influential parameters, find significant combinations of input data, and increase the performance of predictive models using optimization algorithms. New optimization algorithms, new machine learning models, and new datasets can be used for future research.


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**Conflicts of Interest:** The authors declare no conflict of interest.

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